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# Magnetometer Survey Over the

# AULD PROPERTY Auld Township, Ontario





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#### **1. SURVEY DETAILS**

#### 1.1 PROJECT NAME

This project is known as the **Auld Property**.

1.2 CLIENT

AURORA SILVER MINES LIMITED

14579 Government Rd. Larder Lake, Ontario P0K1L0

## 1.3 LOCATION

The Auld Property is located approximately 28km southeast of Elk Lake, Ontario. The survey area is located in Auld Township and covers mining claim 4217442, within the Larder Lake Mining Division.



Figure 1: Location of the Auld Property





# 1.4 ACCESS

Access to the property was attained with a 4x4 truck via Indian Bay Road. Henwood Road 3 heads south from highway 65 approximately 25km east of Elk Lake. The Indian Bay Road is travelled by truck for an additional 10.3km to where a unnamed forestry road extends east. This forestry road is travelled for an additional 5 km to the Auld Property.

# 1.5 SURVEY GRID

The traversed lines were established using a GPS in conjunction with the execution of the survey. The GPS operator would establish sample locations while remaining approximately 12.5m in front of the magnetometer operator. GPS waypoints and magnetic samples were taken every 12.5m along these controlled traverses. The GPS used was a Garmin GPSMAP 62s with an external antenna for added accuracy.



Figure 2: Claim Map with Auld Property Traverses





## 2. SURVEY WORK UNDERTAKEN

### 2.1 SURVEY LOG

| _               | _                              |       | Min    | Max    | Total<br>Survey |
|-----------------|--------------------------------|-------|--------|--------|-----------------|
| Date            | Description                    | Line  | Extent | Extent | (m)             |
| October 9, 2014 | Locate survey area and perform |       |        |        |                 |
|                 | survey.                        | 0     | 0      | 1600N  | 1600            |
|                 |                                | 100E  | 0      | 1600N  | 1600            |
|                 |                                | 200E  | 0      | 1600N  | 1600            |
|                 |                                | 0     | 0      | 300E   | 300             |
|                 |                                | 1300N | 0      | 300E   | 300             |
|                 |                                | 1600N | 0      | 300E   | 300             |

#### Table 1: Survey Log

#### 2.2 PERSONNEL

Bruce Lavalley of Britt, Ontario, conducted all magnetic data collection with Claudia Moraga also of Britt, Ontario being responsible for GPS control and waypoint collection.

#### 2.3 SURVEY SPECIFICATIONS

The survey was conducted with a GSM-19 v7 Overhauser magnetometer with a second GSM-19 magnetometer for a base station mode for diurnal correction.

A total of 5.7 line kilometers of magnetometer was read over the Auld Property on October 9, 2014. This consisted of 456 magnetometer samples taken at a 12.5m sample interval.





# 3. OVERVIEW OF SURVEY RESULTS

#### **3.1 SUMMARY INTERPRETATION**



Figure 3: Google Image with Magnetic Overlay





The magnetic survey indicates the presence of a possible circular magnetically depressed feature. This feature appears to have a magnetically elevated east rim. The wavelength of the magnetic signature appears smoothed which indicates the probable presence of a sedimentary cap. Looking at this as a whole it is probable that there exists a Nipissing Diabase sill under a sedimentary cap.

I would recommend compiling this data with that of the magnetic surveys previously acquired. This would form a more complete picture of the model.





#### **APPENDIX A**

#### STATEMENT OF QUALIFICATIONS

I, C. Jason Ploeger, hereby declare that:

- 1. I am a professional geophysicist with residence in Larder Lake, Ontario and am presently employed as a Geophysicist and Geophysical Manager of Canadian Exploration Services Ltd. of Larder Lake, Ontario.
- 2. I am a Practicing Member of the Association of Professional Geoscientists, with membership number 2172.
- 3. I graduated with a Bachelor of Science degree in geophysics from the University of Western Ontario, in London Ontario, in 1999.
- 4. I have practiced my profession continuously since graduation in Africa, Bulgaria, Canada, Mexico and Mongolia.
- 5. I am a member of the Ontario Prospectors Association, a Director of the Northern Prospectors Association and a member of the Society of Exploration Geophysicists.
- 6. I do not have nor expect an interest in the properties and securities of **Aurora Silver Mines Limited.**
- 7. I am responsible for the final processing and validation of the survey results and the compilation of the presentation of this report. The statements made in this report represent my professional opinion based on my consideration of the information available to me at the time of writing this report.



C. Jason Ploeger, P.Geo., B.Sc. Geophysical Manager Canadian Exploration Services Ltd.

Larder Lake, ON February 11, 2015





#### **APPENDIX B**

#### THEORETICAL BASIS AND SURVEY PROCEDURES

#### TOTAL FIELD MAGNETIC SURVEY

Base station corrected Total Field Magnetic surveying is conducted using at least two synchronized magnetometers of identical type. One magnetometer unit is set in a fixed position in a region of stable geomagnetic gradient, and away from possible cultural effects (i.e. moving vehicles) to monitor and correct for daily diurnal drift. This magnetometer, given the term 'base station', stores the time, date and total field measurement at fixed time intervals over the survey day. The second, remote mobile unit stores the coordinates, time, date, and the total field measurements simultaneously. The procedure consists of taking total magnetic measurements of the Earth's field at stations, along individual profiles, including Tie and Base lines. A 2 meter staff is used to mount the sensor, in order to optimally minimize localized near-surface geologic noise. At the end of a survey day, the mobile and base-station units are linked, via RS-232 ports, for diurnal drift and other magnetic activity (ionospheric and sferic) corrections using internal software.

For the gradiometer application, two identical sensors are mounted vertically at the ends of a rigid fiberglass tube. The centers of the coils are spaced a fixed distance apart (0.5 to 1.0m). The two coils are then read simultaneously, which alleviates the need to correct the gradient readings for diurnal variations, to measure the gradient of the total magnetic field.





#### **APPENDIX C**

#### **GSM** 19



### Specifications

Overhauser Performance

Resolution: 0.01 nT Relative Sensitivity: 0.02 nT Absolute Accuracy: 0.2nT Range: 20,000 to 120,000 nT Gradient Tolerance: Over 10,000nT/m Operating Temperature: -40°C to +60°C

**Operation Modes** 

Manual: Coordinates, time, date and reading stored automatically at min. 3 second interval.

Base Station: Time, date and reading stored at 3 to 60 second intervals. Walking Mag: Time, date and reading stored at coordinates of fiducial. Remote Control: Optional remote control using RS-232 interface. Input/Output: RS-232 or analog (optional) output using 6-pin weatherproof connector.

#### **Operating Parameters**

Power Consumption: Only 2Ws per reading. Operates continuously for 45 hours on standby.

Power Source: 12V 2.6Ah sealed lead acid battery standard, other batteries available

Operating Temperature: -50°C to +60°C

Storage Capacity

Manual Operation: 29,000 readings standard, with up to 116,000 optional. With 3 VLF stations: 12,000 standard and up to 48,000 optional.

Base Station: 105,000 readings standard, with up to 419,000 optional (88 hours or 14 days uninterrupted operation with 3 sec. intervals)

Gradiometer: 25,000 readings standard, with up to 100,000 optional. With 3 VLF stations: 12,000, with up to 45,000 optional.





**Omnidirectional VLF** 

Performance Parameters: Resolution 0.5% and range to  $\pm 200\%$  of total field. Frequency 15 to 30 kHz.

Measured Parameters: Vertical in-phase & out-of-phase, 2 horizontal components, total field coordinates, date, and time.

Features: Up to 3 stations measured automatically, in-field data review, displays station field strength continuously, and tilt correction for up to  $\pm 10^{\circ}$  tilts.

Dimensions and Weights: 93 x 143 x 150mm and weighs only 1.0kg.

Dimensions and Weights

Dimensions: Console: 223 x 69 x 240mm Sensor: 170 x 71mm diameter cylinder Weight: Console: 2.1kg Sensor and Staff Assembly: 2.0kg

Standard Components

GSM-19 magnetometer console, harness, battery charger, shipping case, sensor with cable, staff, instruction manual, data transfer cable and software.

### Taking Advantage of a "Quirk" of Physics

Overhauser effect magnetometers are essentially proton precession devices except that they produce an order-of magnitude greater sensitivity. These "supercharged" quantum magnetometers also deliver high absolute accuracy, rapid cycling (up to 5 readings / second), and exceptionally low power consumption.

The Overhauser effect occurs when a special liquid (with unpaired electrons) is combined with hydrogen atoms and then exposed to secondary polarization from a radio frequency (RF) magnetic field. The unpaired electrons transfer their stronger polarization to hydrogen atoms, thereby generating a strong precession signal-- that is ideal for very high-sensitivity total field measurement. In comparison with proton precession methods, RF signal generation also keeps power consumption to an absolute minimum and reduces noise (i.e. generating RF frequencies are well out of the bandwidth of the precession signal).

In addition, polarization and signal measurement can occur simultaneously - which enables faster, sequential measurements. This, in turn, facilitates advanced statistical averaging over the sampling period and/or increased cycling rates (i.e. sampling speeds).

• The unique Overhauser unit blends physics, data quality, operational efficiency, system design and options into an instrumentation package that ... exceeds proton precession and matches costlier optically pumped cesium capabilities



Magnetometer Survey Auld Property Auld Township, Ontario



# APPENDIX C

#### **GARMIN GPS MAP 62S**



Physical & Performance:

| Unit dimensions,<br>WxHxD:      | 2.4" x 6.3" x 1.4" (6.1 x 16.0 x 3.6 cm)                        |
|---------------------------------|---|
| Display size, WxH:              | 1.43" x 2.15" (3.6 x 5.5 cm); 2.6" diag (6.6 cm)                |
| Display resolution,<br>WxH:     | 160 x 240 pixels  |
| Display type:                   | transflective, 65-K color TFT                                   |
| Weight:                         | 9.2 oz (260.1 g) with batteries                                 |
| Battery:                        | 2 AA batteries (not included); NiMH or Lithium recom-<br>mended |
| Battery life:                   | 20 hours  |
| Waterproof:                     | yes (IPX7)  |
| Floats:                         | no  |
| High-sensitivity re-<br>ceiver: | yes   |
| Interface:                      | high-speed USB and NMEA 0183 compatible                         |





| Maps & Memory:                 |  |  |  |
|--------------------------------|--|--|--|
| Basemap:                       | yes                                      |  |  |
| Preloaded maps:                | no                                       |  |  |
| Ability to add maps:           | yes                                      |  |  |
| Built-in memory:               | 1.7 GB                                   |  |  |
| Accepts data cards:            | microSD <sup>™</sup> card (not included) |  |  |
| Waypoints/favorites/locations: | 2000                                     |  |  |
| Routes:                        | 200                                      |  |  |
| Track log:                     | 10,000 points, 200 saved tracks          |  |  |

| Features & Benefits:                             |   |  |  |
|--|---|--|--|
| Automatic routing (turn by turn routing on       | yes (with optional mapping for detailed |  |  |
| roads):  | roads)                                  |  |  |
| Electronic compass:                              | yes (tilt-compensated, 3-axis)          |  |  |
| Touchscreen:                                     | no                                      |  |  |
| Barometric altimeter:                            | yes                                     |  |  |
| Camera:  | no                                      |  |  |
| Geocaching-friendly:                             | yes (paperless)                         |  |  |
| Custom maps compatible:                          | yes                                     |  |  |
| Photo navigation (navigate to geotagged photos): | yes                                     |  |  |
| Outdoor GPS games:                               | no                                      |  |  |
| Hunt/fish calendar:                              | yes                                     |  |  |
| Sun and moon information:                        | yes                                     |  |  |
| Tide tables:                                     | yes                                     |  |  |
| Area calculation:                                | yes                                     |  |  |





| Custom POIs (ability to add additional points of interest):   | yes |
|---|-----|
| Unit-to-unit transfer (shares data wire-<br>lessly with similar units):   | yes |
| Picture viewer:   | yes |
| Garmin Connect <sup>™</sup> compatible (online<br>community where you analyze, catego-<br>rize and share data): | yes |

• Specifications obtained from www.garmin.com





**APPENDIX D** 

LIST OF MAPS (IN MAP POCKET)

Posted contoured TFM plan map (1:2500)

1) AURORA-AULD-MAG-CONT

Claim Map with Magnetic Traverses (1:20000)

2) AURORA-AULD-GRID

TOTAL MAPS=2



| 55648   |           |     |
|---------|-----------|-----|
| 55589   |           |     |
| 55560   |           |     |
| 55550   |           |     |
| 55542   |           |     |
| 55535   |           |     |
| 55533   |           |     |
| 55529   |           |     |
| 55527   |           |     |
| 55525   |           |     |
| 55521   |           |     |
| 55519   |           |     |
| 55516   |           |     |
| 55514   |           |     |
| 55512   |           |     |
| 55508   |           |     |
| 55505   |           |     |
| 55502   |           |     |
| 55499   |           |     |
| 55497   |           |     |
| 55495   |           |     |
| 55492   |           |     |
| 55490   |           |     |
| 55486   |           |     |
| 55484   |           |     |
| 55482   |           |     |
| 55481   |           |     |
| 55477   |           |     |
| 55473   |           |     |
| 55470   |           |     |
| 55466   |           |     |
| 55461   |           |     |
| 55455   |           |     |
| 55448   |           |     |
| 55439   |           |     |
| 55433   |           |     |
| 55428   |           |     |
| 55420   |           |     |
| Magnet  | omo       | tor |
| nanoTes | sla (n    |     |
|         | · · · · · | ,   |





# **AULD PROPERTY** Auld Township, Ontario

TOTAL FIELD MAGNETIC CONTOURED PLAN MAP **Base Station Corrected** 

Posting Level: 0nT Field Inclination/Declination: 74degN/12degW Station Seperation: 12.5 meters Total Field Magnetic Contours: 50nT

#### GSM-19 OVERHAUSER MAGNETOMETER/VLF v7

Receiver Operated By: Bruce Lavalley GPS Operated By: Claudia Moraga Processed by: Jason Ploeger Map Drawn By: C Jason Ploeger, B.Sc. February 2015



Drawing :AURORA-AULD-MAG-CONT

