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Report of the
Drone Magnetometer Survey

For
Gowest Gold Ltd.
And
Transition Metals Corp.

on the Claims
114788, 159374, 193978, 193979, 278032 and 307860

Gowan Township
Porcupine Mining Division



October 16, 2019

Prepared by: Rochelle Collins, P. Geo.

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Summary

Gowan Claim 4253015, held by Gowest Gold Ltd. and Transition Metals Corp., is situated 32 km northeast of Timmins, Ontario. Post conversion to the online Mine Lands Administration System (MLAS, April 10, 2018) Gowan Claim 4253015 is comprised of 6 cell units (i.e., unpatented mining claims) 114788, 159374, 193978, 193979, 278032 and 307860 in Gowan Township, Porcupine Mining Division. It is accessible from Highway 655, 11.5 km north of the Kidd Creek Mine access Road.

A survey using a Geometrics MFAM magnetometer mounted on a DJI M600 drone was conducted by Zen Geomap of Timmins over the six claims in Gowan township on August 8, 2019. The survey was performed to evaluate the potential for gold bearing structures on the property.

The flight grid on the property totaled 40.4line km. The flight grid (center of grid UTM Zone 17, 486,870E, 5,394,123N) consisted of 27 north-south grid lines totaling 33.1 km and four tie-lines totaling 7.3 km.

Introduction

Mining claims 114788, 159374, 193978, 193979, 278032 and 307860 are located in Gowan township, Porcupine Mining Division.

A general location and access map are presented as *Figure 1*.

A detailed claim location map is presented as *Figure 2*.

On August 8, 2019 above claims were surveyed using a Geometrics MFAM magnetometer mounted on a DJI M600 drone. Zen Geomap of Timmins, Ontario, carried out the magnetic survey on a contract basis for the client. The survey was performed in order to evaluate the potential for gold bearing structures within the property.

Data processing and maps were completed between August 8-10, 2019. Assessment report was prepared September 16, 2019.

Location and Access

The mining claims are located approximately 32 km north-northeast of the City of Timmins, Ontario (Figure 1). Surface access to the property is easily gained via Highway 655 on an all-weather gravel road that turns east off Highway 655, 11.5 km north of the Kidd Creek Mine access road. This 14 km long all-weather road ends at the Gowest Gold Ltd. Bradshaw Gold Project.

The Gowan Property 114788, 159374, 193978, 193979, 278032 and 307860 claims are accessed by driving approximately 10.5 km down the all-weather access road (Sheridan Road) from Highway 655 via truck and trailer. An Argo is then off loaded on the side of the access road (NAD 83,17U, 482669E, 5399994N). The Argo is then driven approximately 7.5 km in a south easterly direction following an old logging road with extremely heavy alder overgrowth until reaching the lower south west boundary in claim 307860 at (NAD 83, 17U, 486588E 5393942N).

Figure 1 – Location and Access

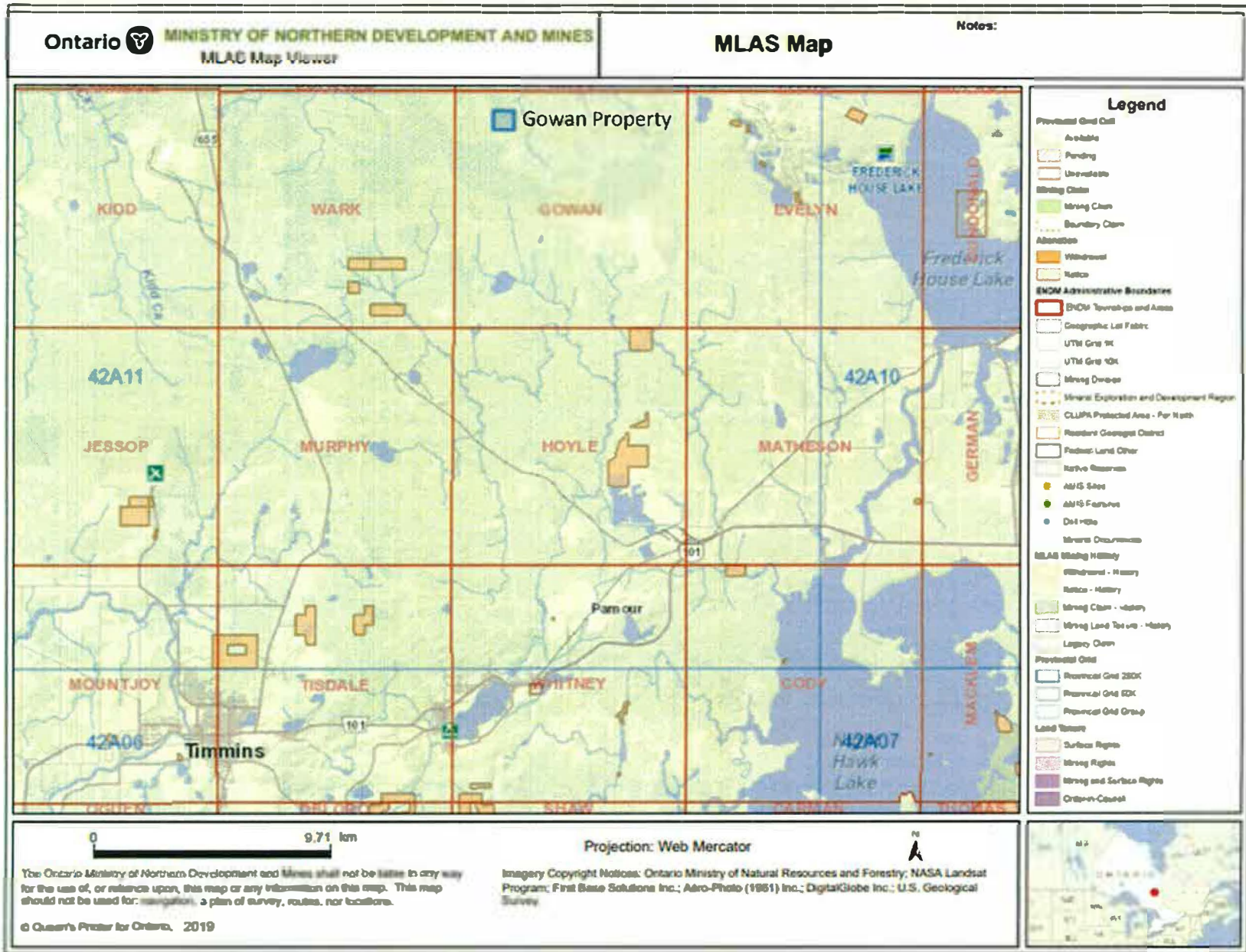
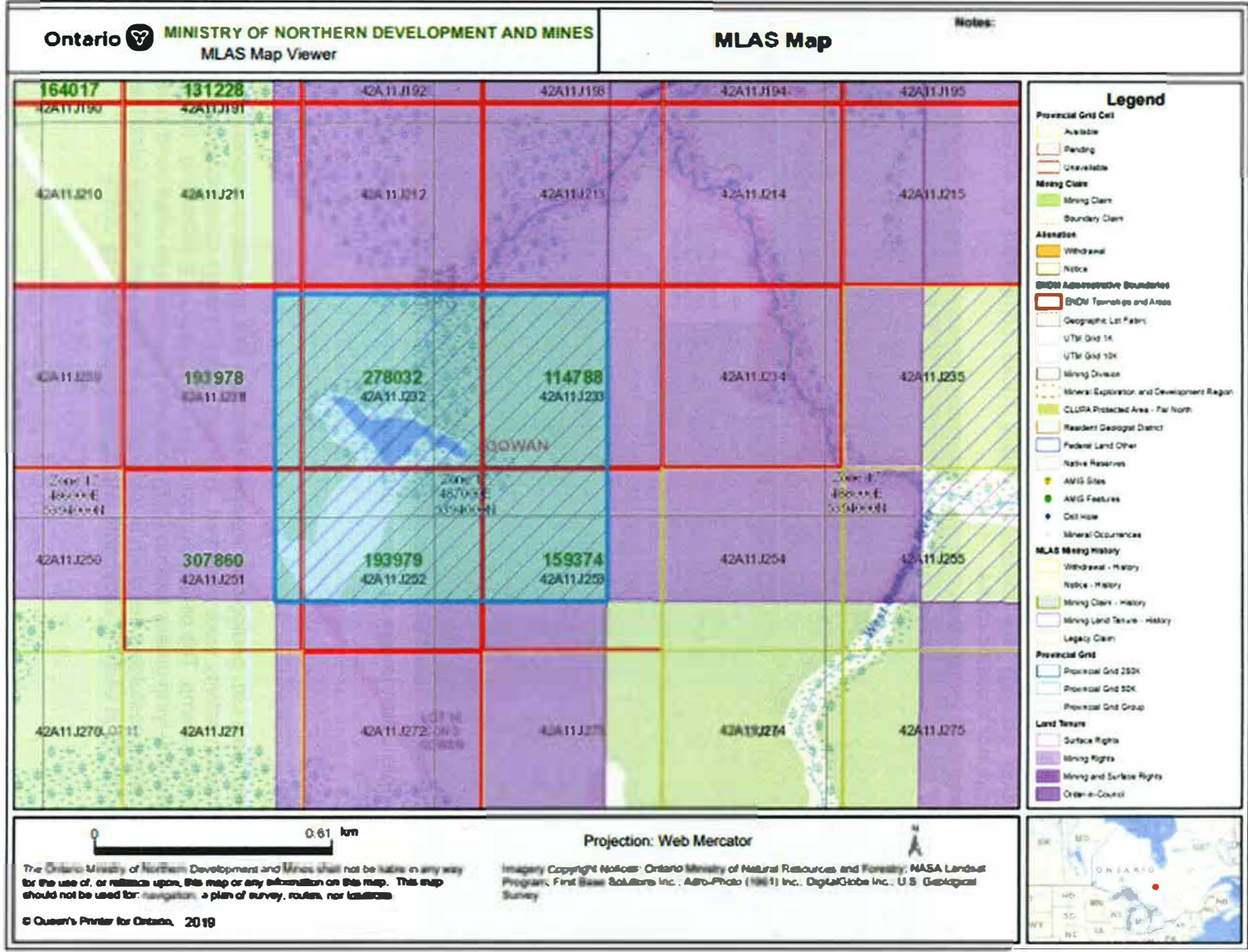


Figure 2 – Claim Location Map



3.0 Regional and Local Geology

Regional Geology

Sourced from the Ontario Geological Survey bedrock data a portion of the Gowan project area is underlain by felsic to intermediate metavolcanic rocks, rhyolitic, rhyodacitic flows, tuffs and breccias.

The surrounding geology are metasedimentary rocks composed of siltstone, argillite, mudstone and minor volcanic rocks.

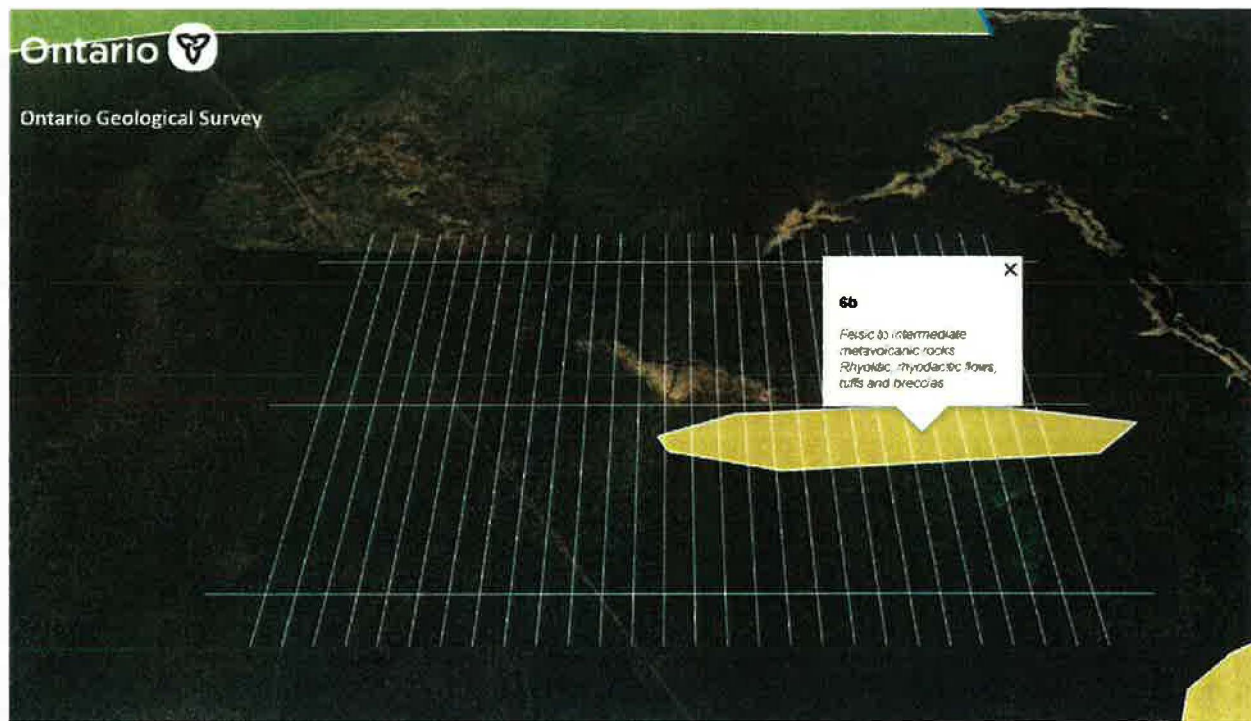


Figure 3: Google Earth Image of survey grid and bedrock overlain in the higher magnetic portion of survey.

Local Geology

In 2011, Gowest Gold Ltd. geologically mapped the claim and no bedrock exposure or signs of previous exploration activity were observed. The claim is dominantly covered by poorly drained spruce forests and swamp. The central portion of the claim is cut by a 400m long, 100-200m wide east-west barren low-lying grassy swamp / bog area with a beaver type small pond in center. The Ontario government postulates the claim is underlain by an east-west striking felsic-intermediate volcanic sliver (50-75 m wide) in sediments (Montgomery and Sparling, 2011).

Type of Mineral Deposit

The client is exploring for gold bearing structures along the Pipestone Trend. Magnetometer is an effective tool for gold exploration.

Property History

The Gowan Property consists of six unpatented mining claims in Gowan Township totalling 64.8 hectares. Gowest Gold Ltd has an option to acquire 100% of the mining rights from Transition Metals.

Previous mineral exploration work conducted on the Gowan Property is summarized in the Table below.

YEAR	AFRI FILE #	COMPANY	WORK TYPE	RESULTS
1965	42A11NE0531	NEW CALUMET MINES LTD.	EM, MAG	Ground Mag & VLEM.
1982	42A11NE0508	COMINCO	RC	2 RC drill holes, GO-124 & 125. hit bedrock at 14 m & 29 m depths. No assay data. No bedrock descriptions.
1983	42A11NE0509	COMINCO	RC	6 RC drill holes, GO-133 to 139. all hit bedrock at 16 to 23.5 m depths. No assay data. Bedrock descriptions too vague to determine rock type.
2011		GOWEST GOLD	AMAG, AEM, GEOL	Helitem EM and Mag conducted by Fugro Airborne Surveys over the Timmins North Project Geological mapping confirmed the 2001 mapping.
2012		GOWEST GOLD	SGH Soil Sampling	Soil samples collected from 50 sites on the property. The interpretation of the SGH survey results has outlined a strong 250m long oval redox cell in the south-central portion of the survey area. This redox cell has a strong potential for gold mineralization

Summary of 2019 Drone Magnetic Survey

The program consisted of a drone magnetic survey carried out on 27 north-south grid lines totaling 33.1 km and four tie-lines totaling 7.3 km. Total line kilometers: 40.4 (see Figure 3 – Grid Map)

Altitude: 50m AGL

A Geometrics MFAM magnetometer mounted on a DJI M600 Pro hexacopter drone was used to survey all grid lines. A Geometrics G856AX proton procession magnetometer was operated as a base station throughout the survey to provide diurnal correction. Equipment specifications are provided in *Appendix I, II and III*.



Figure 4 – Grid Map

Processing

Magnetometer data was collected on 2 Geometrics MFAM sensors operating at 1000hz. The data was processed through a custom program operating in Python. This converts raw data from Geometrics MFAM into a format compatible with Geosoft Oasis Montaj.

Customized import templates were used within Geosoft, to identify and separate magnetic readings into organized grid and tie lines. This step eliminates extraneous magnetic data collected as the drone travels to and from the grid. Grid and tie line data were corrected to remove heading error and lag. Corrected grid data was then leveled based on tie lines.

Discussion of Results

The magnetic survey indicates a very quiet magnetic background with magnetic values ranging between -41nT and -95nT.

Higher magnetic values are present near the middle of the claim group on the eastern half of survey, on claim 159374 south east of a small body of water. The higher magnetic values roughly align with the Ontario Geological Survey bedrock data mapped as felsic to intermediate metavolcanic rocks, rhyolitic, rhyodacitic flows, tuffs and breccias, reflecting a more magnetic lithology (See M1 on Map 3).

The background lithology of the remaining two-thirds of the survey has predominantly low magnetic values. The lower magnetic values align with the Ontario Geological Survey bedrock data mapped as metasedimentary rocks composed of siltstone, argillite, mudstone and minor volcanic rocks.

The 2012, soil and gas hydrocarbon interpreted a north trending shear zone between 487,075E to 487,175E. The magnetic survey is interpreted as indicating a similar trend near 487,100E. Another north trending feature is interpreted along 486,600E.

Several lineaments and faults are also interpreted and shown on Map 4

The overall strike of the underlying geology is also generally in an east-west to southwest-northeast direction. A possible contact with a different lithology at southwest portion of grid area (magnetic low) – sediments.

Conclusions and Recommendations

The magnetic survey completed over the claims has identified a closed magnetic high anomaly i.e. M1 on the south eastern portion of the survey. It is possible that 3D inversion modeling would provide further insight. The current magnetic data was collected at 1000hz with sensitivity of 0.00003nT.

Follow up with an IP survey is recommended with north-south directions lines.

Certificate of Qualifications

I, Rochelle Collins, of the City of Timmins, Province of Ontario, do hereby certify that:

- (1) I am a professional Geologist, residing at 287 Lois Crescent, Timmins Ontario, P4P 1G6.
- (2) I hold a B.Sc. Honours degree in Geology and Geography (1997) from McMaster University of Hamilton, Ontario and an EMBA candidate of Queen's University of Kingston, Ontario (2020).
- (3) I am a registered professional geoscientist with the Professional Geoscientists of Ontario (#1412)
- (4) This report is based on my observations and interpretation of the geophysical data on the Gowan property, maps and figures, surveyed in 2019 and historical assessment data.
- (5) I have no personal interest in the property covered by this report.
- (6) Permission is granted for the use of this report, in whole or in part, for assessment and qualification requirements but not for advertising purposes.

Rochelle Collins

Rochelle Collins, P. Geo., B.Sc.

Dated at Timmins, Ontario

This 16th day of October, 2019.



References

1. Montgomery K. and Sparling G. 2011 Report of geological mapping on claims 4240049, 4254623, 4253014 and 4253015 for Gowest Gold Ltd. Frankfield Project, Porcupine Mining Division, Northeastern Ontario.
2. Email communication with Matthew Johnston, Geophysicist, with comments and interpretation of the magnetic survey data, October 10, 2019.

Appendices

Appendix I

Geometrics MFAM Magnetometer Specifications

System Basics

- System utilizes 2 MFAM sensors
- Sensors are controlled by 1 sensor module
- Sensor module communicates with a Texas Instruments main board
- Sensitivity: 0.00003nT
- Sensors operate at 1000Hz (collect 1000 readings per second on both sensors)

Technical Specifications

SPECIFICATIONS:

Mechanical:

Enclosure Dimensions: 9" x 6 5/8" x 1 3/16"

Sensor Cable length (Development box to Sensor): 20.5 inches

Power:

AC adapter: 13.5 to 16 Volts DC at 1.0A

Battery Pack: 12 volt 1800 mA-Hour Lithium Polymer

FEATURES:

- 1) **TIVA TM4C1294NCPDT Micro controller:** This is a 32 bit ARM Cortex-MF4 based microcontroller running at up to 120 MHz. It has 1024K of flash, with 256K bytes of RAM, and 6 KBytes of EEPROM.
- 2) **USB 2.0 Micro Connector:** USB functionality is provided by the TIVA microcontroller and TIVAWare support libraries.
- 3) **Four User LEDs:** Four user controlled LEDs are wired to TIVA microcontroller GPIO pins PK0, PK1, PN0, and PN1.
- 4) **Two User Switches:** Two user read switches are wired to the microcontroller pins PK6 and PJ1.
- 5) **One Microcontroller Reset Switch:** This switch is used to reset the microcontroller.
- 6) **Wi-Fi port for TI CC3100 Wi-Fi Booster Pack:** The Development board layout allows a TI CC3100 Wi-Fi Booster pack to be directly plugged in. Using TIVAWare libraries, software can be developed to allow Wi-Fi communication between the Development board and a computer.
- 7) **USB XDS110 Port for Firmware Downloading and Debugging:** This second USB port is used as a debug/firmware download interface between the TI Code Composer Studio development suite and the Development Kit.

- 8) **Two RS-232 Serial Ports with RJ-45 Connectors:** Two general purpose serial ports are available to the user. The first serial port is wired to TIVA microcontroller UART4, and supports RTS and CTS handshaking. The second serial port is wired to TIVA microcontroller UART5. This port supports only Tx/D and Rx/D. Both of these ports use +/- 8 volt voltage swings, and support baud rates up to 920 KBaud. Note that these two ports are wired as Data Terminal Equipment (DTE) Thus to connect either of these two ports to a computer it would need to connect through a null modem.

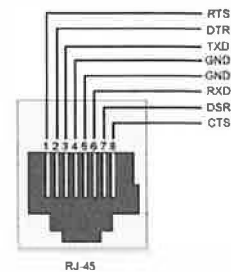


Figure 3: Serial Port Pinout

- 9) **On Board GPS Module:** An Adafruit GPS module is included with the Development Kit. It features 66 channels, -165 dBm sensitivity, and 3 Meter accuracy. An external GPS antenna is included so that signals can be received inside the box even with the cover in place. By default the GPS powers up to 9600 baud with several GPS sentences being output. The firmware that comes with the Development kit reconfigures the GPS to output only an RMC sentence at 115200 baud. This RMC string is sent with the output TCP data packet as described in the "Ethernet Data Format" section. The GPS is wired to UART7 on the TIVA microcontroller using 0-3.3 volt logic swings.

The 1PPS pulse from this GPS goes to the MFAM development module and disciplines the cycle rate to exactly 1 kiloSamples per second.

- 10) **Micro SD Card Slot for Storing Data Locally:** A micro SD card slot is available for the user to read and write data using a SPI interface. It is connected to SPI port 1 of the TIVA microcontroller.
- 11) **10 MHz Timing Reference Input Port:** This input port takes a 10 MHz reference signal from a GPS disciplined reference oscillator, buffers and squares it up, and sends it to the MFAM module. The purpose of this signal is to lock the MFAM clocking system to this reference signal so that the Larmor frequency can be measured to an absolute standard. At this time, the MFAM does not support this feature. This function will be implemented in the future.
- 12) **Ethernet port with Power over Ethernet Compatibility:** The Tiva microcontroller contains a fully integrated Ethernet MAC and PHY. In addition, the Ethernet port can power the Development Kit via Power over Ethernet (PoE) using an Ethernet power injector.
- 13) **1.8 Amp-Hour Battery pack:** Three on board lithium/polymer batteries can power the system for 2 hours. A switch on the Development board allows the battery to be turned on/off. In addition, if the battery voltage falls below 8 volts the MFAM module will automatically shut down while keeping the microcontroller alive.
- 14) **Integrated Battery Charging system:** A lithium/polymer battery charging system is on board. If the battery switch is turned on, and the AC power adapter is plugged in, the batteries will be charged.
- 15) **Four Differential Analog Input Channels:** There are four differential analog inputs available for use. Channels 0 and 1 are +/- 2.5 volts full scale, while channels 2 and 3 are 0 to +5 volts full scale. In the firmware supplied with the Development kit (which sends MFAM/GPS data to the MFAMConsole program on the computer), all four channels are sampled synchronously with the MFAM data input to the Tiva are included in the data stream.
- 16) **On board Power/Status LEDs:** Several Status and Power LEDs are arranged along the front edge of the board. They include the four user LEDs, Power status LEDs (which power source is powering the board, and whether the battery is charging or the voltage low). They are listed in the Front and Back Panel Connection and Indicator section below.

Appendix II

Geometrics G856AX
Proton procession magnetometer specifications

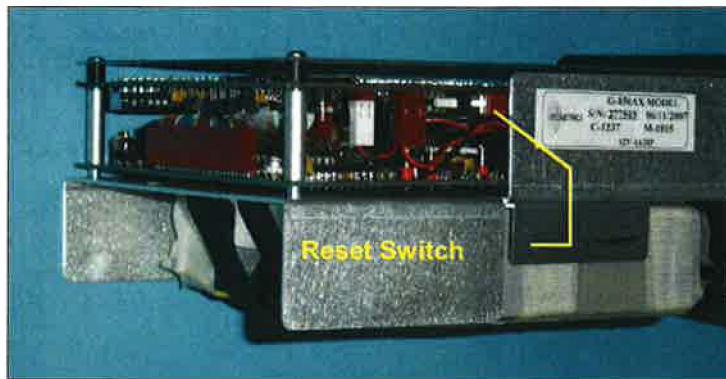


Figure 23. Internal reset switch.

Specifications

- Displays - Six digit display of magnetic field to resolution of 0.1 gamma or time to nearest second. Additional three-digit display of station, day of year, and line number.
- Resolution - Typically 0.1 gamma in average conditions. May degrade to lower resolution in weak fields, noisy conditions or high gradients.
- Absolute accuracy - One gamma, limited by remnant magnetism in sensor and crystal oscillator accuracy.
- Clock - Julian clock with stability of 5 seconds per month at room temperature and 5 seconds per day over the temperature range of -20 to +50 degrees Celsius.
- Tuning - Push button tuning from keyboard with current value displayed on request. Tuning range 20 to 90 μ T.
- Gradient - Tolerates gradients to 1800 gammas/meter. When high Tolerance gradients truncate count interval, maintains partial reading to an accuracy consistent with data.
- Cycle Time - Complete field measurement in three seconds in normal operation. Internal switch selection for faster cycle (1.5 seconds) at reduced resolution or longer cycles for increased resolution.
- Manual Read - Takes reading on command. Will store data in memory on command.
- Memory - Stores more than 5700 readings in survey mode, keeping track of

time, station number, line number day and magnetic field reading. In base station operation, computes for retrieval but does not store time of recording designated by sample interval, allowing storage of up to 12,000 readings.

- Output - Plays data out in standard RS-232 format at selectable baud rates. Also outputs data in real time byte parallel, character serial BCD for use with digital recorders.
- Inputs - Will accept an external sample command.
- Special - An internal switch allows:
 - adjustment of Functions polarization time and count time to improve performance in marginal areas or to improve resolution or speed operation
 - three count averaging
 - choice of lighted displays in auto mode.
- Physical -
 - Instrument console: 7 x 10 ½ x 3 ½ inches (18 x 27 x 9 cm), 6 LB (2.7 kg)
 - Sensor: 3 1/2 x 5 inches (9 x 13 cm), 4 LB (1.8 kg)
 - Staff: 1 inch x 8 feet (3cm x 2.5m), 2 LB (1kg)
- Environmental: Meets specifications from 1 to 40°C. Operates satisfactorily from -20 to 50°C.
- Power - Depending on version, operates from internal rechargeable Gel-cells or 9 D-cell flashlight batteries . May be operated from external power ranging from 12 to 18 volts external power. Power failure or replacement of batteries will not cause loss of data stored in memory.
- Standard system (P/N 16600-02) components:
 - Sensor (P/N 16076-01) and sensor cable (P/N 16134-01)
 - Console (P/N 16601-01)
 - Staff, one top section (P/N 16535-01), two middle sections (P/N 16536-01) and 1 bottom section (P/N 16537-01)
 - Carry harness (P/N 16002-02)
 - Two sets of rechargeable batteries (P/N 16697-01) and battery charger (P/N 16699-01)
 - Carrying case (P/N 16003-01)
 - Download cable (P/N 16492-01)
 - Hardcopy operation manual (P/N 18101-02)
 - Magnetometer CD (P/N 26648-01)
- Optional accessories:
 - Tripod kit for base-station operation (P/N 16708-02)
 - Gradiometer kit (P/N 166651-01)
 - Gradiometer carry/storage case (16003-01)

Appendix III - DJI Matrice 600 Pro Specifications

Specifications

• Aircraft

Diagonal Wheelbase	1133 mm
Dimensions	1668 mm x 1518 mm x 727 mm with propellers, frame arms and GPS mount unfolded (including landing gear) 437 mm x 402 mm x 553 mm with propellers, frame arms and GPS mount folded (excluding landing gear)
Weight (with six TB47S batteries)	9.5 kg
Weight (with six TB48S batteries)	10 kg
Max Takeoff Weight Recommended	15.5 kg
Hovering Accuracy (P-GPS)	Vertical: ± 0.5 m Horizontal: ± 1.5 m
Max Angular Velocity	Pitch: 300°/s, Yaw: 150°/s
Max Pitch Angle	25°
Max Wind Resistance	8 m/s
Max Ascent Speed	5 m/s
Max Descent Speed	3 m/s
Max Speed	40 mph / 65 kph (no wind)
Max Service Ceiling Above Sea Level	2170 propellers: 2500 m, 2195 propellers: 3500 m
Hovering Time* (with six TB47S batteries)	No payload: 32 min, 6 kg payload: 16 min
Hovering Time* (with six TB48S batteries)	No payload: 38 min, 5.5 kg payload: 18 min
Flight Control System	A3 Pro
Supported DJI Gimbals	Ronin-MX; ZENMUSE™ Z30, Zenmuse X5/X5R, Zenmuse X3, Zenmuse X1, Zenmuse Z15 Series HD Gimbal: Z15-A7, Z15-BMPCC, Z15-5D III, Z15-GH4
Retractable Landing Gear	Standard
Operating Temperature	14° to 104° F (-10° to 40° C)

• Remote Controller

Operating Frequency	920.8 MHz to 928 MHz (Japan); 5.725 GHz to 5.825 GHz, 2.400 GHz to 2.483 GHz
Max Transmission Distance	FCC Compliant: 3.1 mi (5 km), CE Compliant: 2.2 mi (3.5 km) (Unobstructed, free of interference)
Transmitter Power (EIRP)	10 dBm @ 900M, 13 dBm @ 5.8G, 20 dBm @ 2.4G
Video Output Port	HDMI, SDI, USB
Operating Temperature	14° to 104° F (-10° to 40° C)
Battery	6000 mAh LiPo 2S

• Charger (Model: MC6S600)

Voltage Output	26.1 V
Rated Power	600 W
Single Battery Port Output Power	100 W




• Standard Battery (Model: TB47S)

Capacity	4500 mAh
Voltage	22.2 V
Battery Type	LiPo 6S
Energy	99.9 Wh
Net Weight	595 g
Operating Temperature	14° to 104° F (-10° to 40° C)
Max Charging Power	180 W

• Optional Battery (Model: TB48S)

Capacity	5700 mAh
Voltage	22.8 V
Battery Type	LiPo 6S
Energy	129.96 Wh
Net Weight	680 g
Operating Temperature	14° to 104° F (-10° to 40° C)
Max Charging Power	180 W

* Hovering time is based on flying at 10 meters above sea level, in a no-wind environment and landing with a 10% battery level

CE1313   **RoHS** 

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:
 (1) This device may not cause harmful interference, and
 (2) this device must accept any interference received, including interference that may cause undesired operation.

HDMI
REGISTERED TRADEMARK

DJI incorporates HDMI™ technology. The terms HDMI and HDMI High Definition Multimedia Interface, and the HDMI Logo are trademarks or registered trademarks of HDMI Licensing LLC in the United States and other countries.

Download the detailed user manual at:
www.dji.com/matrice600-pro

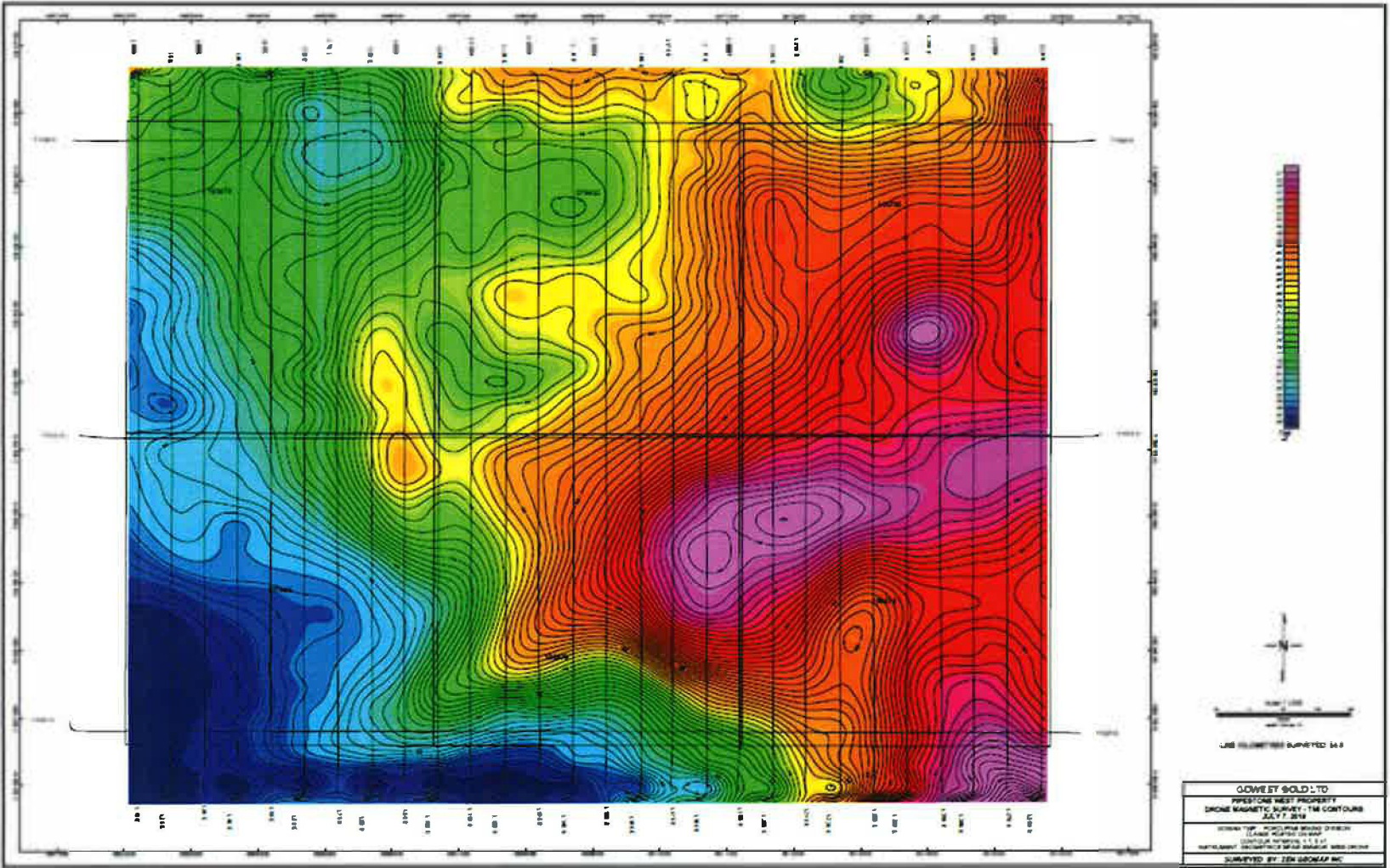
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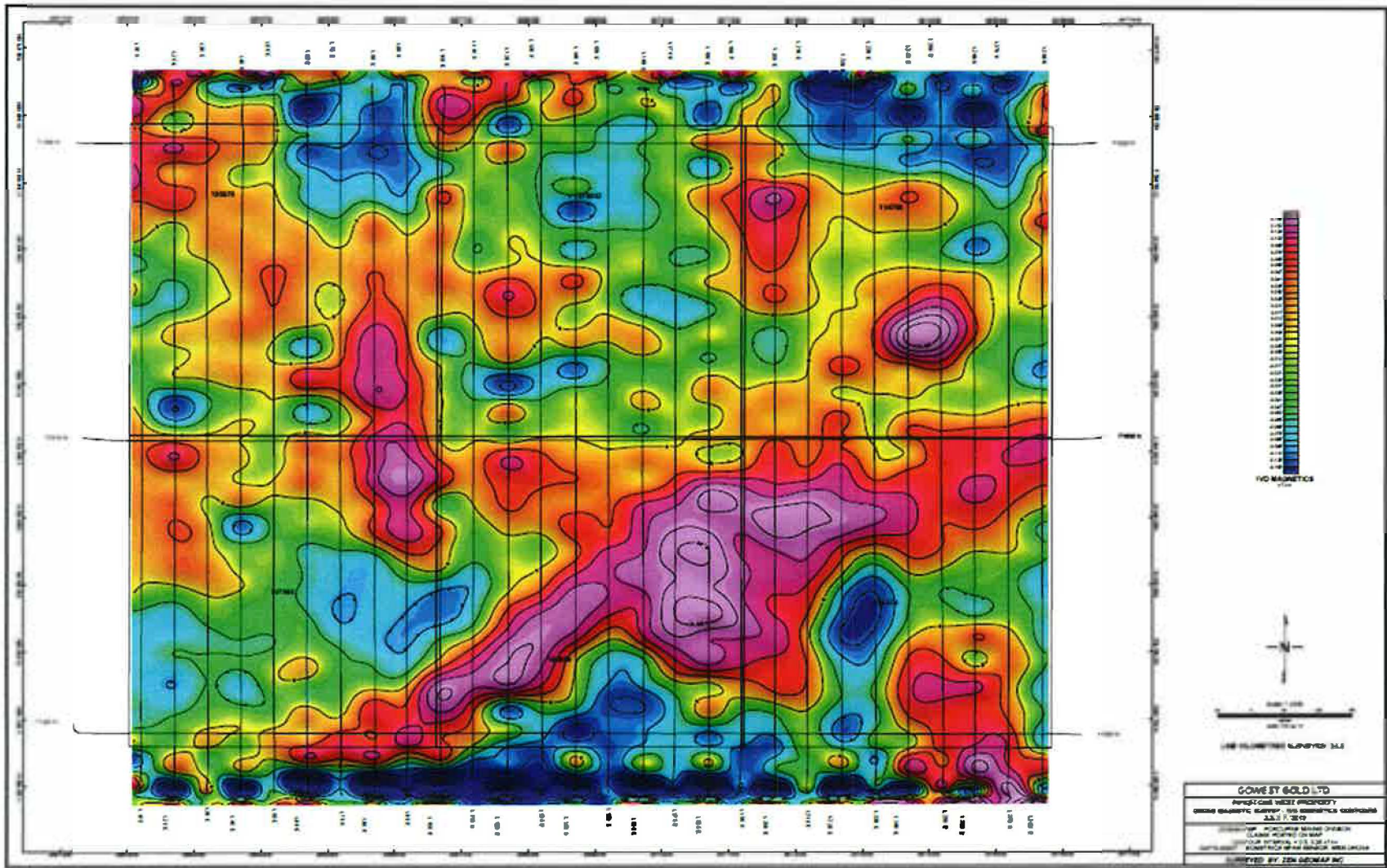
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Appendix V - MLAS Conversion of Legacy Claim to Mining Cells

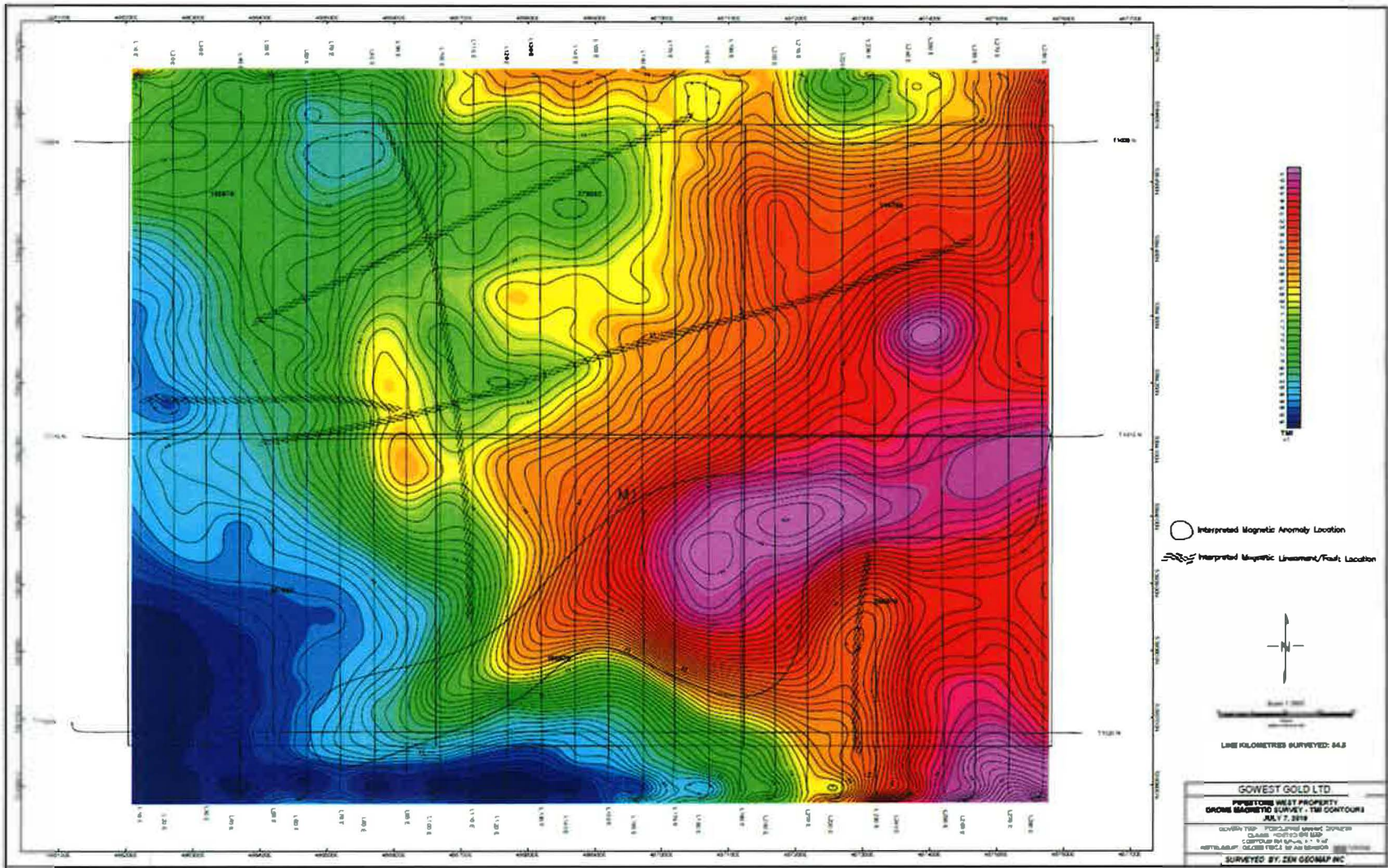
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4253015	GOWAN	159374	Mining Claim Single Cell	2020-02-02	Active	60	200
4253015	GOWAN	193978	Mining Claim Single Cell	2020-02-02	Active	60	200
4253015	GOWAN	193979	Mining Claim Single Cell	2020-02-02	Active	60	200
4253015	GOWAN	278032	Mining Claim Single Cell	2020-02-02	Active	60	200
4253015	GOWAN	307860	Mining Claim	2020-02-02	Active	60	200



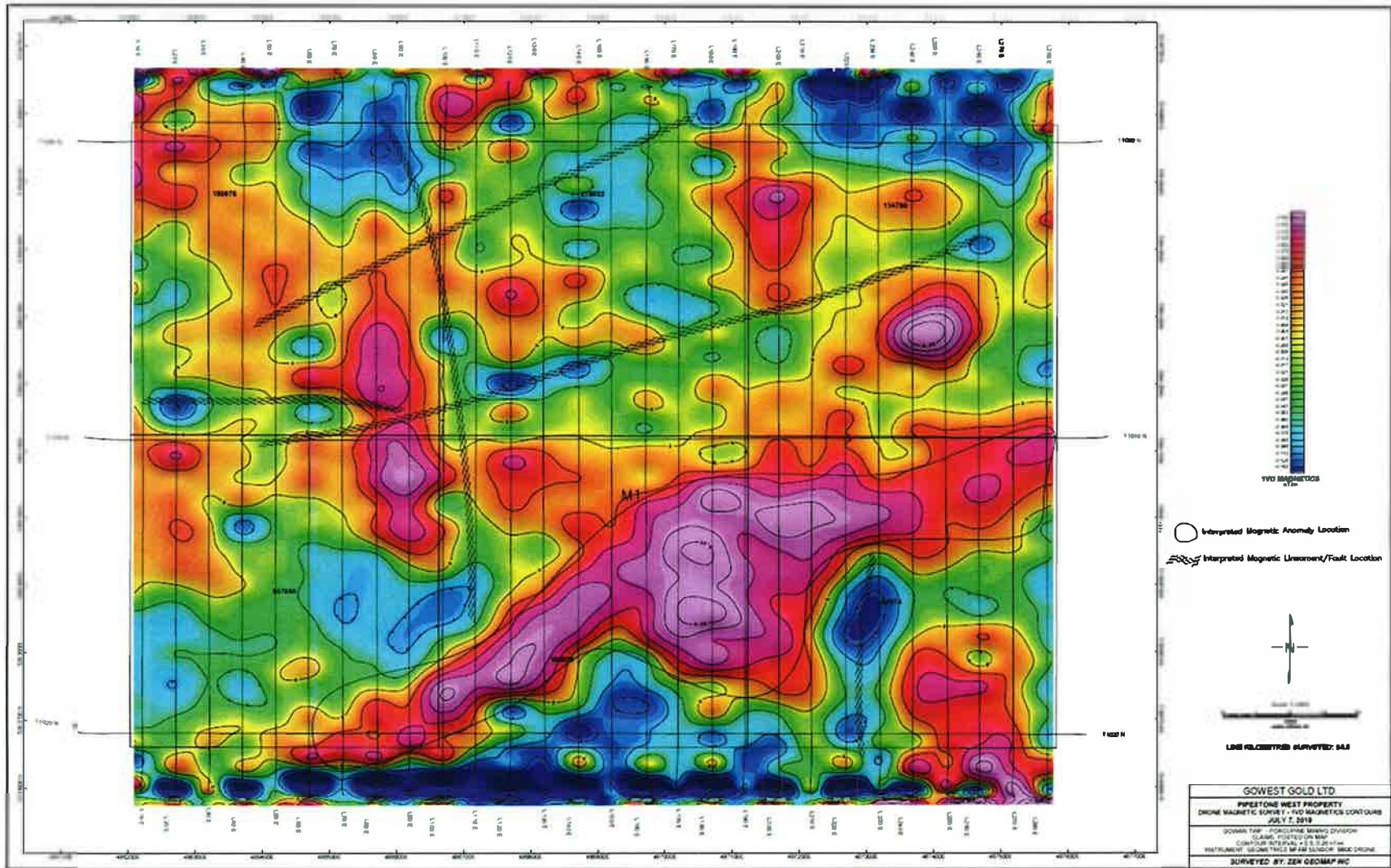
Map 1: Total Field Magnetic Survey - Contours



Map 2: 1st Vertical Derivative - Contours




Map 3: Total Field Magnetic Survey - with Interpretation Lines



Map 4: 1st Vertical Derivative - with Interpretation Lines



Ontario 

Ontario Geological Survey

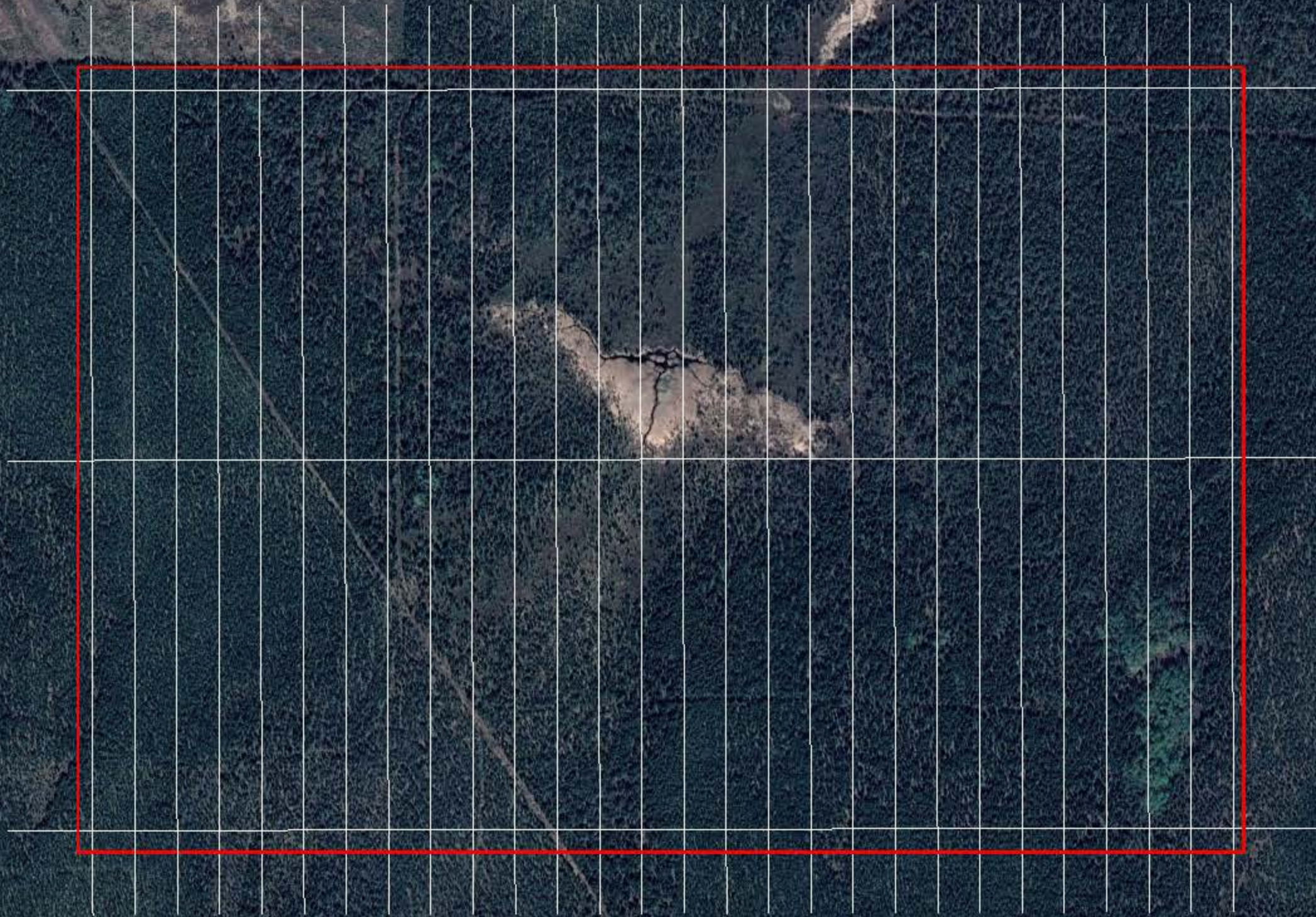


Image © 2019 Maxar Technologies
Image © 2019 CNES / Airbus

Google Earth

Ontario 

Ontario Geological Survey



Gowest Claims 50m

Gridlines 33.1 Km
Tielines 7.3 Km

Total flight km 40.4 Km

5 flights

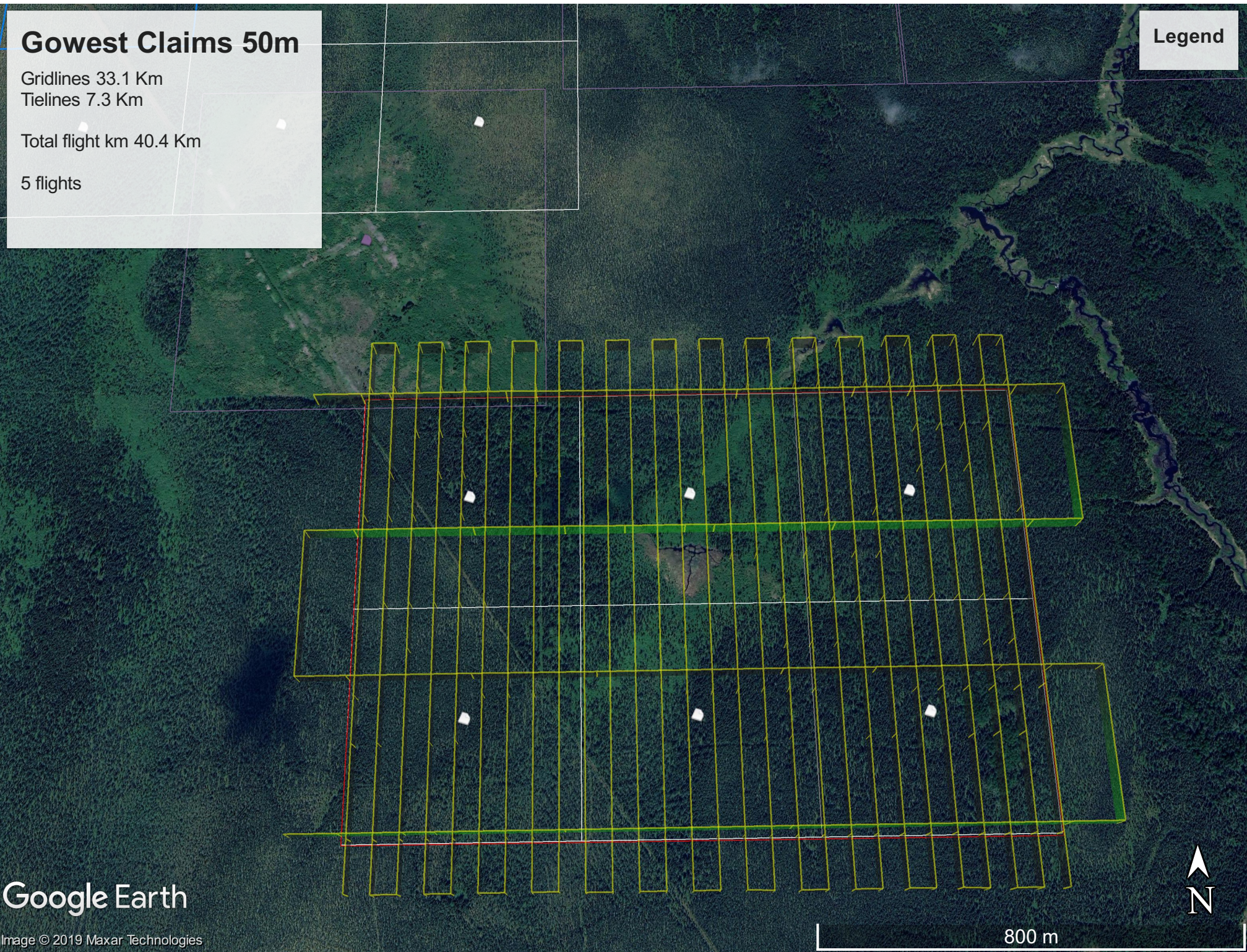
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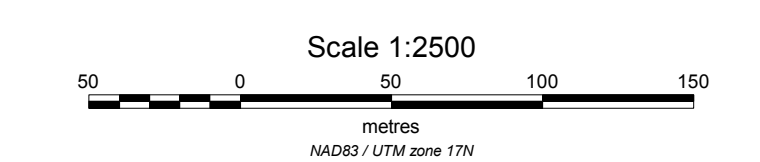
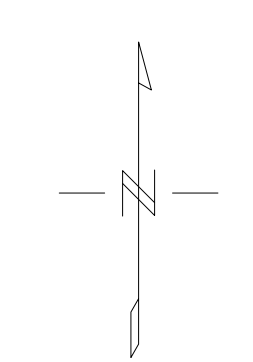
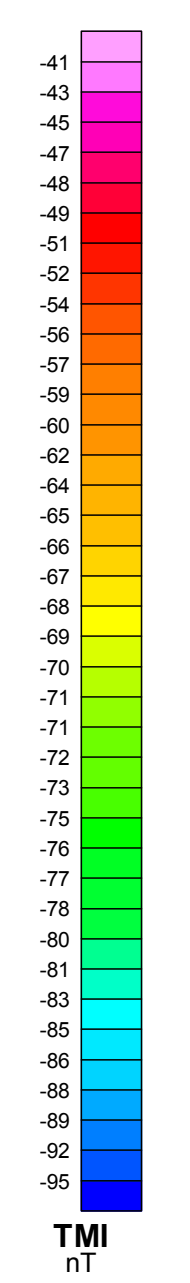
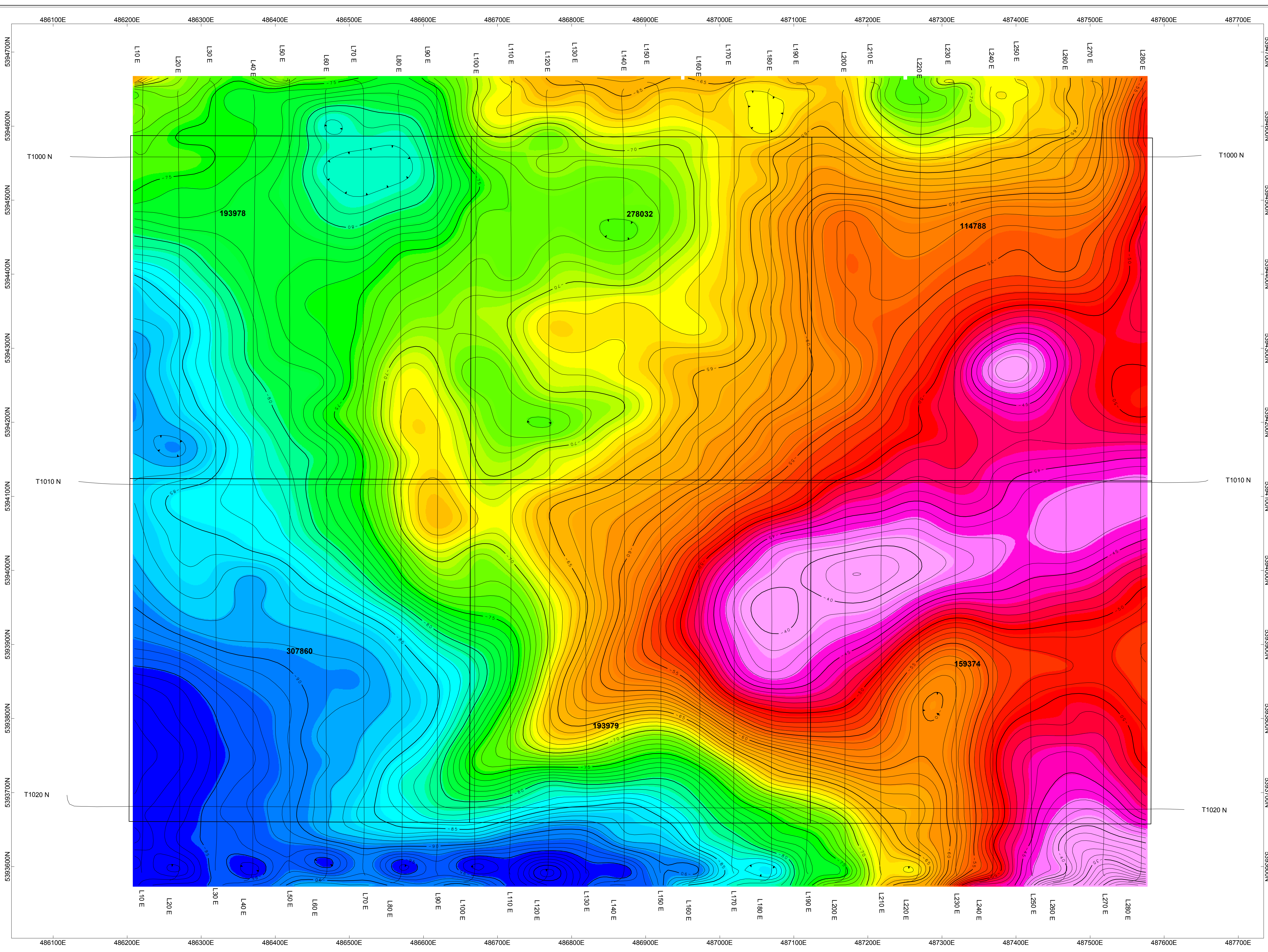
Google Earth

Image © 2019 Maxar Technologies



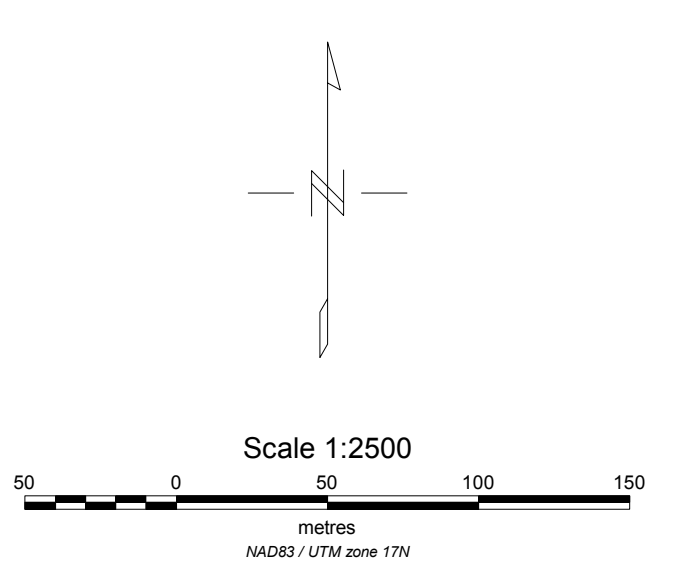
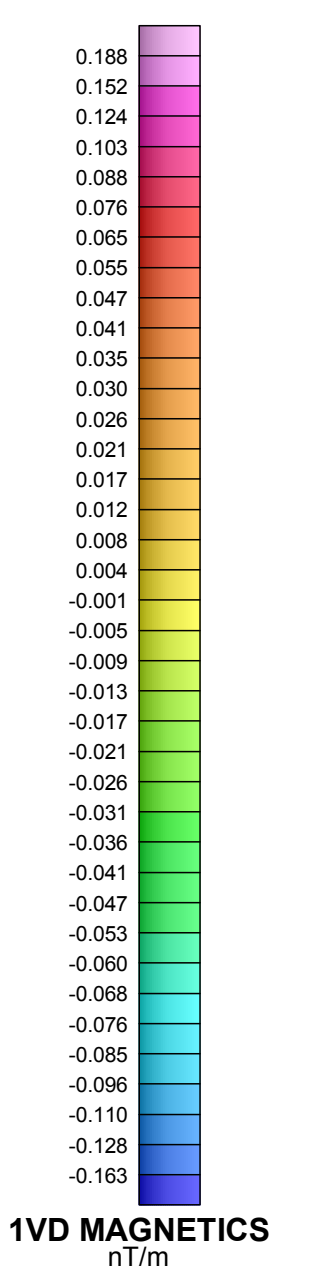
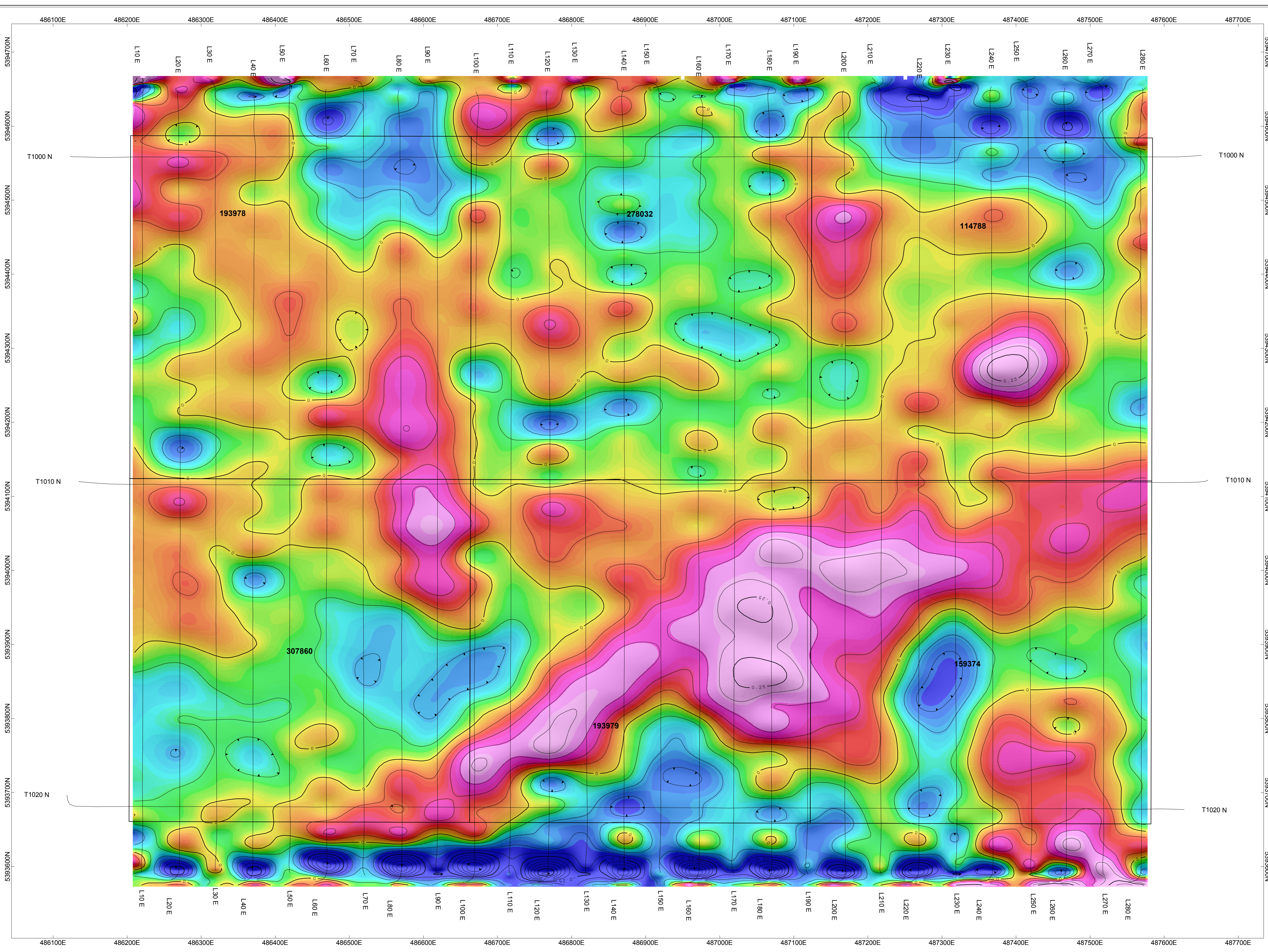
800 m





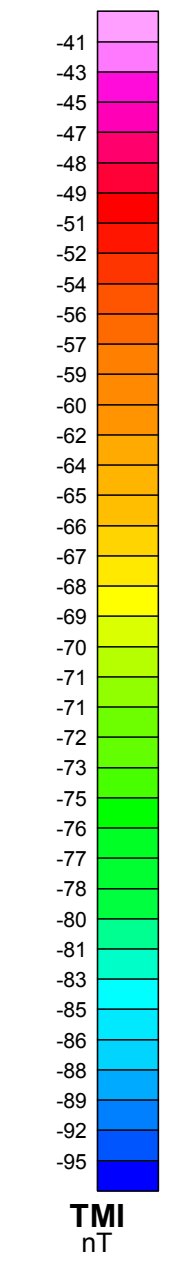
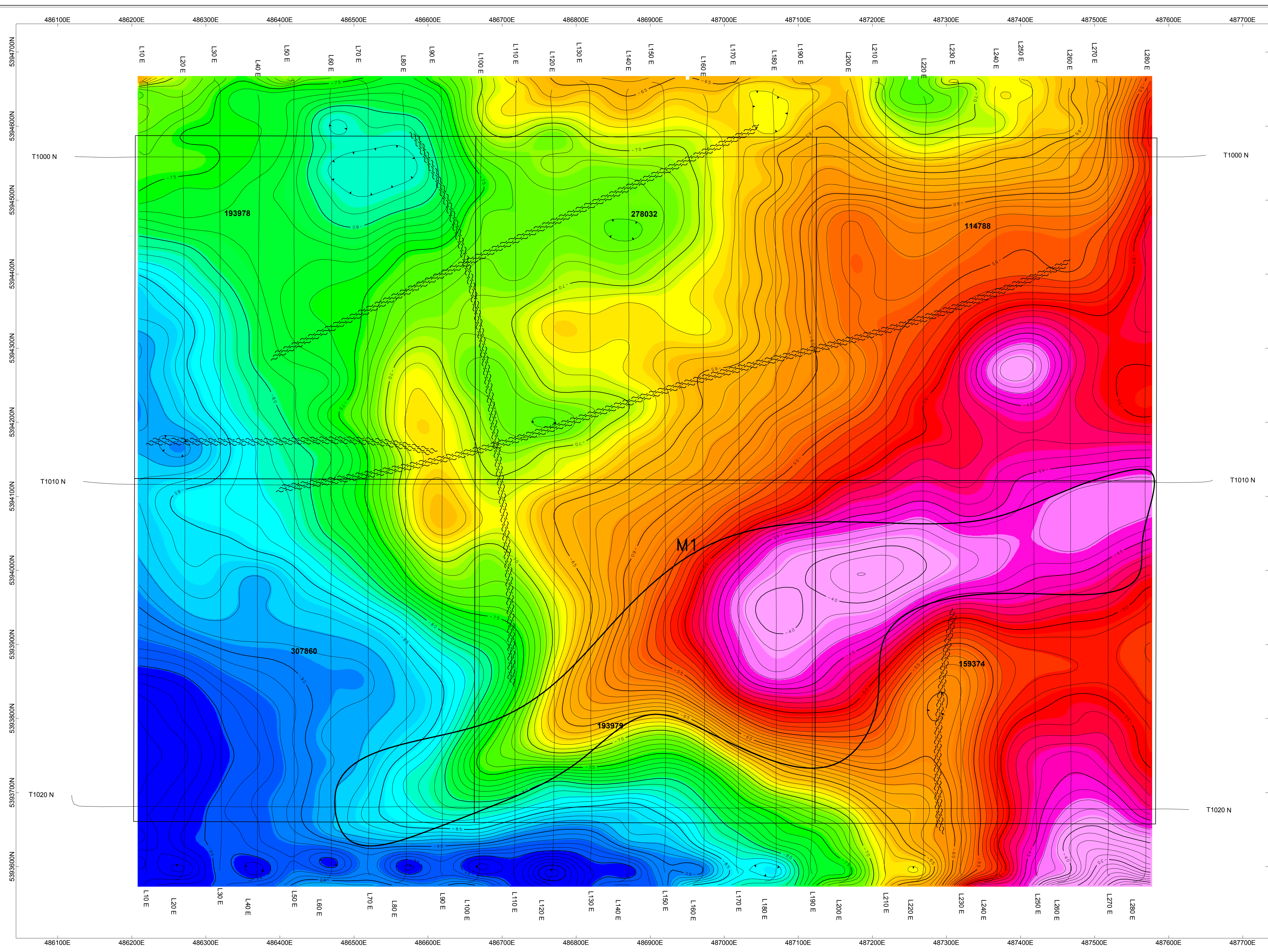
LINE KILOMETRES SURVEYED: 34.8



GOWEST GOLD LTD.	
PIPESTONE WEST PROPERTY	
DRONE MAGNETIC SURVEY - TMI CONTOURS	
JULY 7, 2019	
GOWAN TWP. - PORCUPINE MINING DIVISION	
CLAIMS: POSTED ON MAP	
CONTOUR INTERVAL = 1.5 nT	
INSTRUMENT: GEOMETRICS MFAM SENSOR M600 DRONE	
SURVEYED BY: ZEN GEOMAP INC	

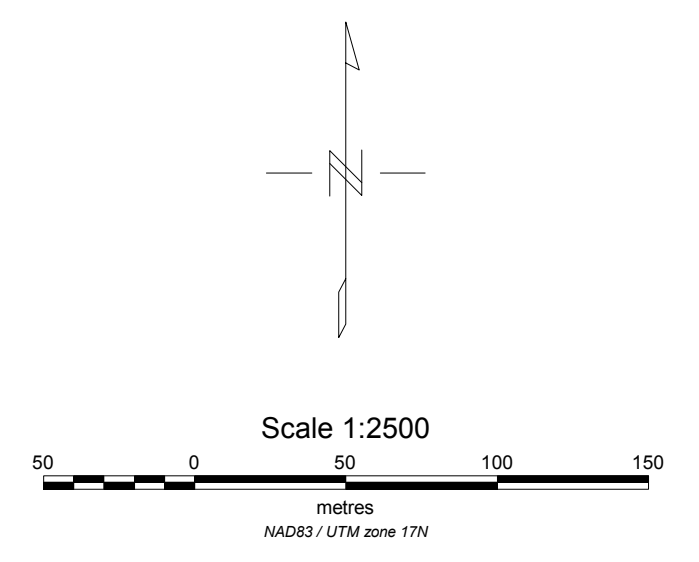


LINE KILOMETRES SURVEYED: 34.8

<p>GOWEST GOLD LTD. PIPESTONE WEST PROPERTY DRONE MAGNETIC SURVEY - 1VD MAGNETICS CONTOURS JULY 7, 2019</p> <p>GOWAN TWP. - PORCUPINE MINING DIVISION CLAIMS: POSTED ON MAP CONTOUR INTERVAL = 0.5, 0.25 nT/m INSTRUMENT: GEOMETRICS MFAM SENSOR M600 DRONE</p> <p>SURVEYED BY: ZEN GEOMAP INC</p>

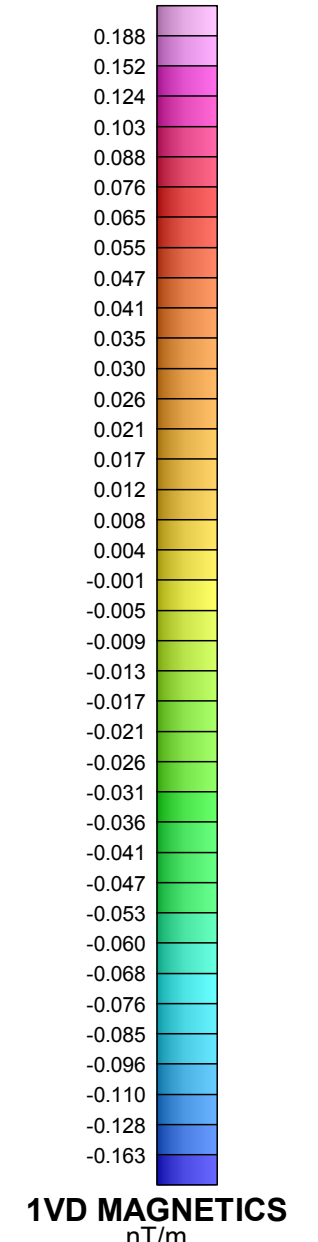
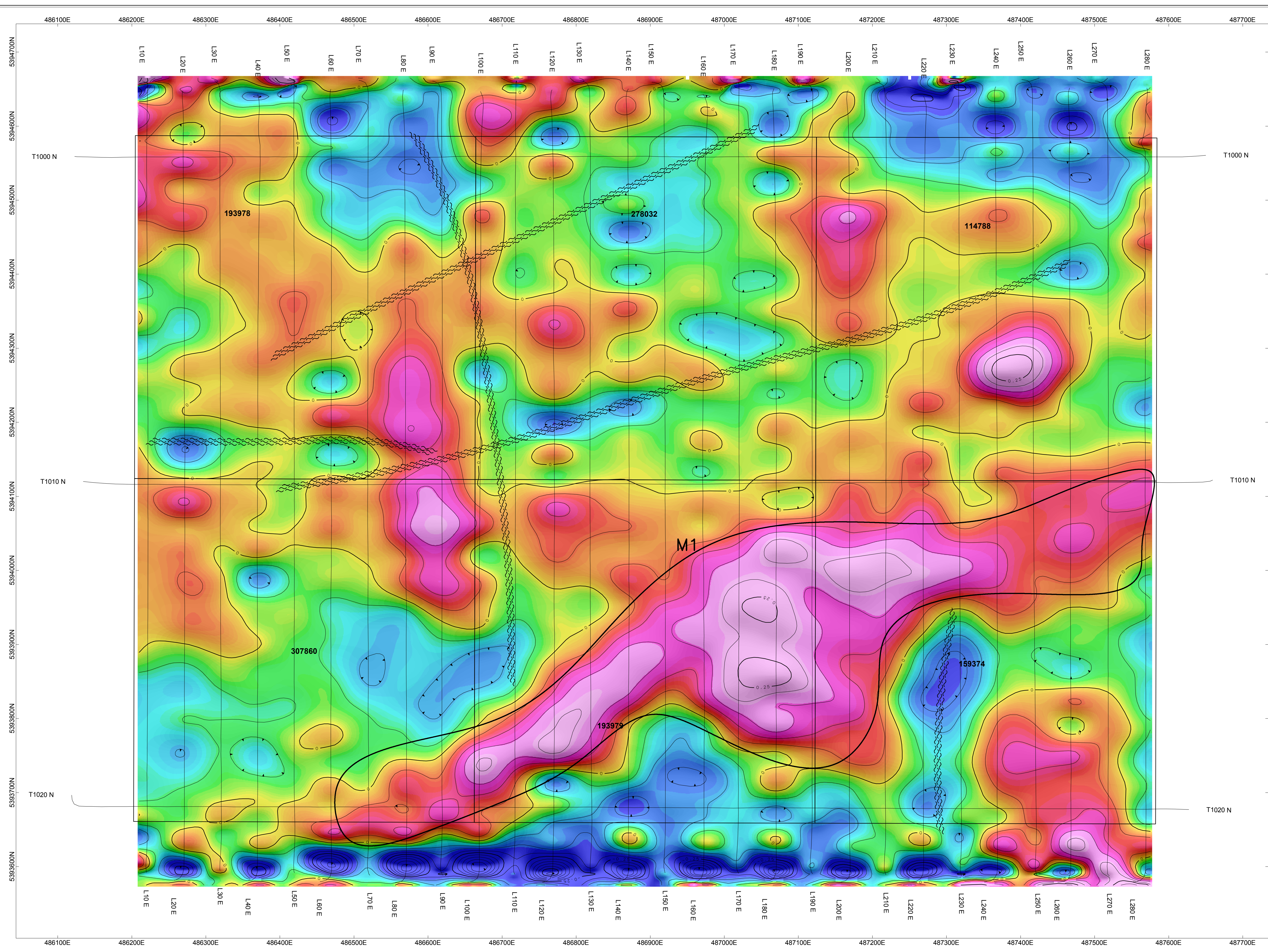


-  Interpreted Magnetic Anomaly Location
-  Interpreted Magnetic Lineament/Fault Location

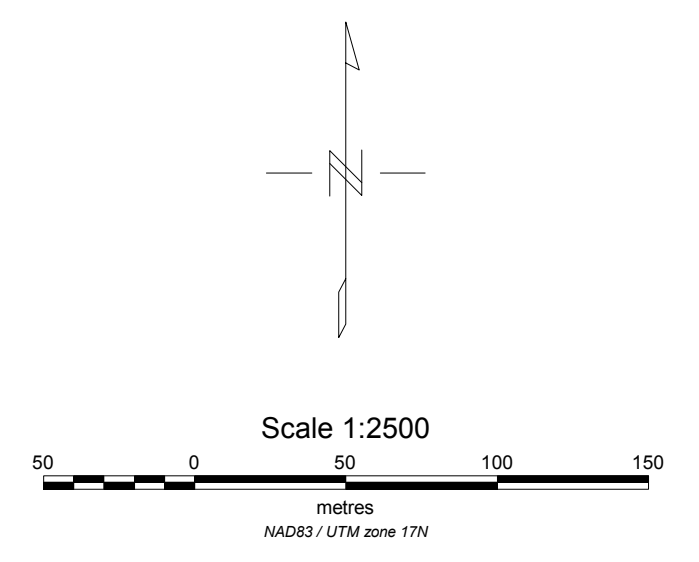


LINE KILOMETRES SURVEYED: 34.8

<p>GOWEST GOLD LTD.</p> <p>PIPESTONE WEST PROPERTY</p> <p>DRONE MAGNETIC SURVEY - TMI CONTOURS</p> <p>JULY 7, 2019</p>
<p>GOWAN TWP. - PORCUPINE MINING DIVISION</p> <p>CLAIMS: POSTED ON MAP</p> <p>CONTOUR INTERVAL = 1, 5 nT</p> <p>INSTRUMENT: GEOMETRICS MFAM SENSOR M600 DRONE</p>
<p>SURVEYED BY: ZEN GEOMAP INC</p>



- Interpreted Magnetic Anomaly Location
- Interpreted Magnetic Lineament/Fault Location



LINE KILOMETRES SURVEYED: 34.8

<p>GOWEST GOLD LTD.</p> <p>PIPESTONE WEST PROPERTY</p> <p>DRONE MAGNETIC SURVEY - 1VD MAGNETICS CONTOURS</p> <p>JULY 7, 2019</p> <p>GOWAN TWP. - PORCUPINE MINING DIVISION</p> <p>CLAIMS: POSTED ON MAP</p> <p>CONTOUR INTERVAL = 0.5, 0.25 nT/m</p> <p>INSTRUMENT: GEOMETRICS MFAM SENSOR M600 DRONE</p> <p>SURVEYED BY: ZEN GEOMAP INC</p>
