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April 16<sup>th</sup> 2019

NTS Map 32/D/05

# Report of 2019 Total Field Magnetics Survey

## JONATHAN CAMILLERI

### Clifford Township

Report Prepared by

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## Introduction

Dan Patrie Exploration Ltd was contracted by Jonathan Camilleri to perform a Total Field Magnetics GPS Survey of the claim group held by Jonathan in the township of Clifford. Dan Patrie Exploration commenced the survey with a crew of 4 workers on March 1<sup>st</sup> 2019 and concluded the field work by March 4<sup>th</sup> 2019.

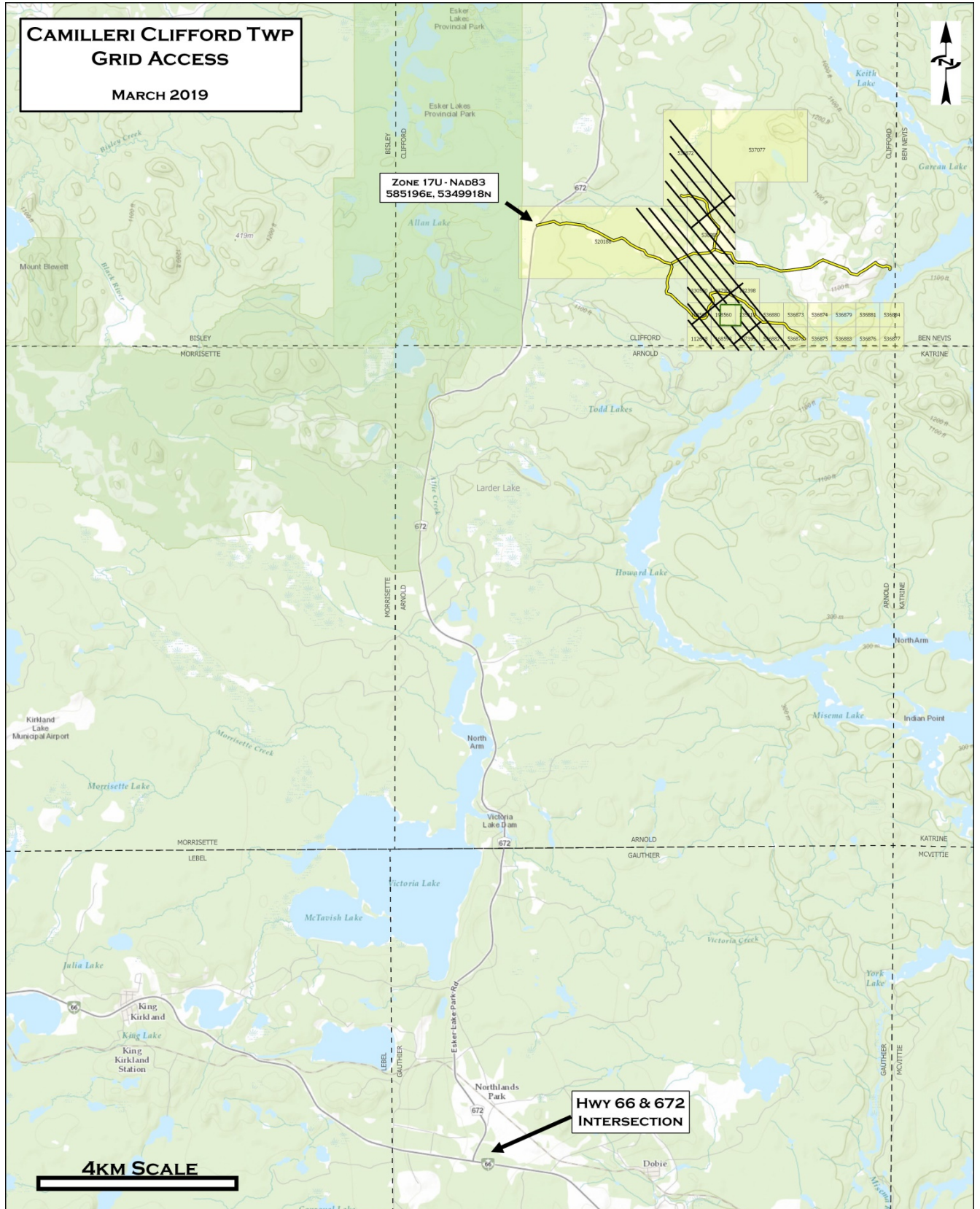
The contiguous claim group consists of 12 unpatented mining claims. The center of the claim group is located at UTM 17 U 588725mE, 5348450mN (Nad 83) approximately 22.5km south/west of the town of Kirkland Lake, Ontario. (Refer to **Map A** - Access Map/**Map B** - Claim Group Map)

## Property Access

The town of Kirkland Lake was used for accommodations and supplies during the work period. Direct access to the property was obtained by pickup trucks via Hwy 66 and Hwy 672. From Hwy 672 an old bush access road is currently still accessible by pickup truck. A detailed access map is provided (**Map A** – Clifford Access Map).



**Map A – Clifford Access Map**



# Claim Group

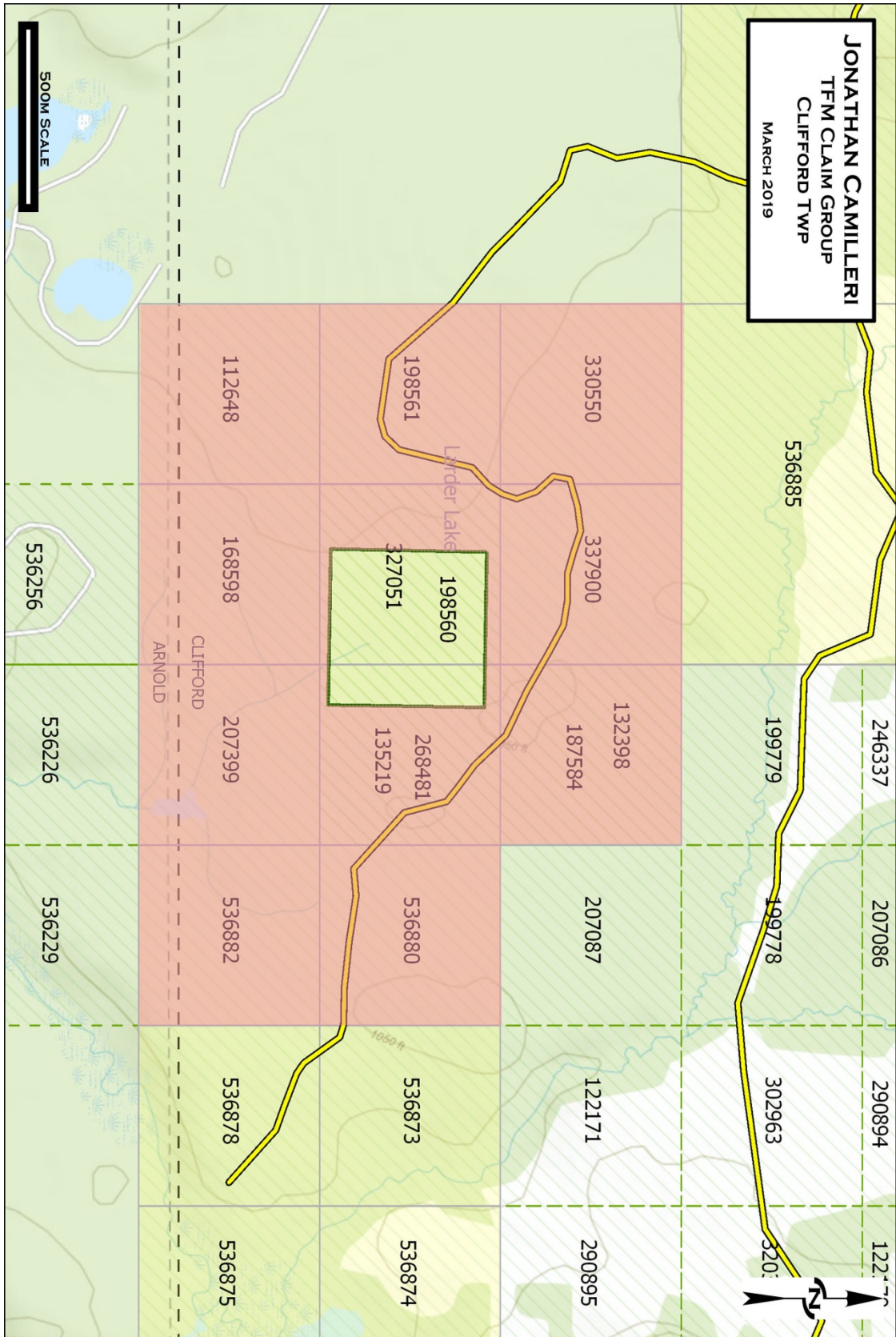
The Following Map and table lists the 12 unpatented mining claims in Clifford Township within the Camilleri claim group where the GPS MAG ground survey was conducted (**Figure 1 & Map B**)

**Figure 1 - Clifford Camilleri Claim Group**

Township / Area	Tenure ID	Anniversary Date	Tenure Status	Tenure Percentage	Work Required	Work Applied
CLIFFORD	132398	2019-05-05	Active	100	200	0
CLIFFORD	135219	2019-05-05	Active	100	200	0
CLIFFORD	198560	2019-05-05	Active	100	200	0
ARNOLD,CLIFFORD	112648	2019-05-05	Active	100	400	0
ARNOLD,CLIFFORD	168598	2019-05-05	Active	100	400	0
CLIFFORD	198561	2019-05-05	Active	100	400	0
ARNOLD,CLIFFORD	207399	2019-05-05	Active	100	400	0
CLIFFORD	330550	2019-05-05	Active	100	400	0
CLIFFORD	337900	2019-05-05	Active	100	400	0
ARNOLD,CLIFFORD	536878	2020-12-17	Active	100	400	0
CLIFFORD	536880	2020-12-17	Active	100	400	0
ARNOLD,CLIFFORD	536882	2020-12-17	Active	100	400	0



Map B – Camilleri TFM Claim Group



## Work Performed

A 9.4km 320° azimuth GPS grid was established covering the Camilleri Clifford claims consisting of 7 lines at 200m intervals. Using Garmin GPSMap 64 GPS units the DPE team walked the grid in pairs with one worker navigating to each station at 25m intervals, while the second worker of each team followed behind recording readings with the Scintrex ENVIMAG magnetometer. **Figure 2** (Line Totals) and **Map C** (Grid Map) represent the grid lines used to conduct the survey. **Map D** displays the survey result in the form of a detailed contoured map.

**Figure 2 – Camilleri Clifford Grid Line Totals**

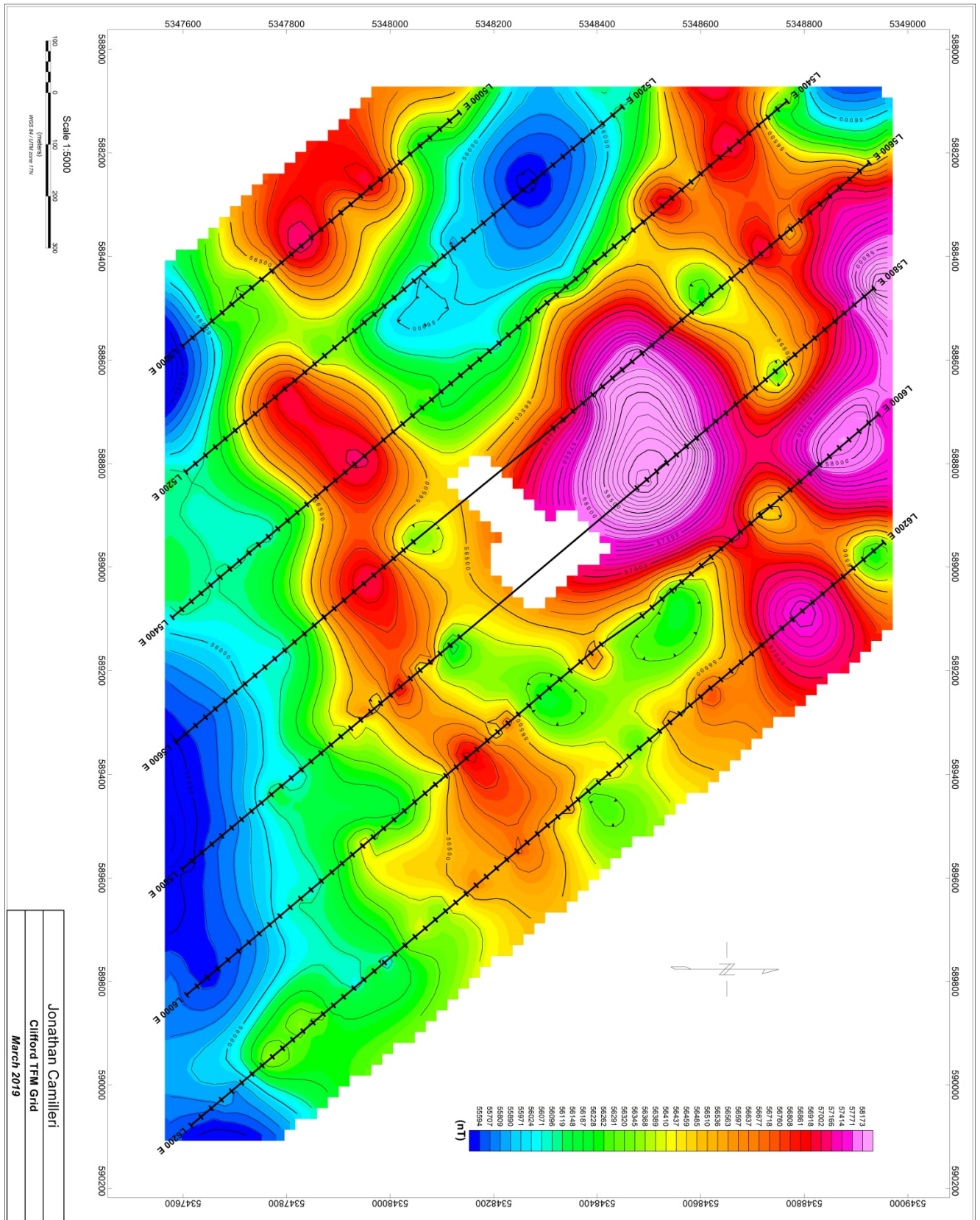
Line		Start	End	Total(m)
L5000E		1400N	2100N	700
L5200E		1250N	2350N	1100
L5400E		1000N	2600N	1600
L5600E		900N	1500N	600
L5600E		1850N	2650N	800
L5800E		750N	1450N	700
L5800E		1900N	2500N	600
L6000E		650N	1650N	1000
L6000E		1750N	2350N	600
L6200E		500N	2200N	1700

**GRID TOTAL 9.4KM**





**Map D – Clifford TFM Contour Map**



# Equipment Specifications

Scintrex ENVIMAG magnetometers (**Figure 3**) were used to conduct the survey. All data was base corrected using a third ENVIMAG at a fixed location for the entirety of the survey. The base station was located approximately 3.5km north/west of the survey grid at UTM 17 U 585820mE, 5349960mN(NAD83). All ENVIMAG's were synchronized and calibrated to the base field of 55550nT.

**Figure 3 – ENVIMAG Specifications**



## EQUIPMENT

REFERENCE: SCINTREX ENVI MAG BROCHURE

### Total Field Operating Range

20,000 to 100,000 nT (gammas)

### Total Field Absolute Accuracy:

± 1 nT

### Sensitivity:

0.1 nT at 2 second sampling rate

### Tuning

Fully solid state. Manual or automatic, keyboard selectable

### Cycling (Reading) Rates

0.5, 1 or 2 seconds

### Gradiometer Option

Includes a second sensor, 1/2m (20 inch) staff extender and processor module.

### VLF Option

Includes a VLF sensor and harness assembly

### 'WALKMAG' Mode

continuous reading, cycling as fast as 0.5 seconds

### Digital Display

LCD "Super Twist", 240 x 64 dots graphics, 8 line x 40 characters alphanumeric

### Display Heater

Thermostatically controlled, for cold weather operations

### Keyboard Input

17 keys, dual function, membrane type

### Notebook Function

32 characters, 5 user-defined MACRO's for quick entry

### Standard Memory

Total Field Measurements: 28,000 readings  
Gradiometer Measurements: 21,000 readings  
Base Station Measurements: 151,000 readings  
VLF Measurements: 4,500 readings for 3 frequencies

### Expanded Memory

Total Field Measurements: 140,000 readings  
Gradiometer Measurements: 109,000 readings  
Base Station Measurements: 750,000 readings  
VLF Measurements: 24,000 readings for 3 frequencies

### Real-Time Clock

Records full date, hours, minutes and seconds with 1 second resolution, ± 1 second stability over 24 hours

### Digital Data Output

RS-232C interface, 600 to 57,600 Baud, 7 or 8 data bits, 1 start, 1 stop bit, no parity format. Selectable carriage return delay (0-999 ms) to accommodate slow peripherals. Handshaking is done by X-on/X-off. High speed Binary Dump. Selectable formats for easy interfacing to commercial software packages.

### Analog Output

0-999 mV full scale output voltage with keyboard selectable range of 1, 10, 100, 1000 or 10,000 full scale

### Power Supply

Rechargeable 'Camcorder' type, 2.3 Ah, Lead-acid battery  
12 Volts at 0.65 Amp for magnetometer, 1.2 Amp for gradiometer  
External 12 Volt input for base station operations  
Optional external battery pouch for cold weather operations

### Battery Charger

110 Volt-230 Volt, 50/60 Hz

### Operating Temperature Range

Standard: -40° to 60°C

### Dimensions & Weight

Console: 250mm x 152mm x 55mm (10" x 6" x 2.25")  
2.45 kg (5.4 lbs) with rechargeable battery

Magnetic Sensor: 70mm x 175mm (2.75" d x 7")  
1 kg (2.2 lbs)

Gradiometer Sensor: 70mm x 675mm (2.75" d x 26.5")  
(with staff extender) 1.15 kg (2.5 lbs)

Sensor Staff: 25mm x 2m (1" d x 76")  
.8 kg (1.75 lbs)

VLF Sensor Head: 140mm x 130mm (5.5" d x 5.1")  
.9 kg (2 lbs)

VLF Sensor: 280mm x 190mm x 75mm (11" x 7.5" x 3")  
1.7 kg (3.7 lbs)

### Options

Base Station Accessories Kit  
GPS  
Software Packages  
Training Programs

## SCINTREX

### SCINTREX

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Website: [www.auslog.com.au](http://www.auslog.com.au)



## **Recomendations**

Dan Patrie Exploration Ltd. recommends establishing a line cutting grid on this property and the surrounding contiguous Camilleri claims followed by an induced polarization survey covering at minimum the anomalous areas indicated by the TFM survey . Proposed would be a 20 to 30km grid of line cutting and IP.

## **Personnel**

Gabriel Roy - Smooth Rock Falls, Ontario

Ronald Bilton – Massey, Ontario

Hunter Busch – Val Caron, Ontario

Justin Abramson – Sudbury, Ontario



# CAMILLERI CLIFFORD TWP GRID ACCESS

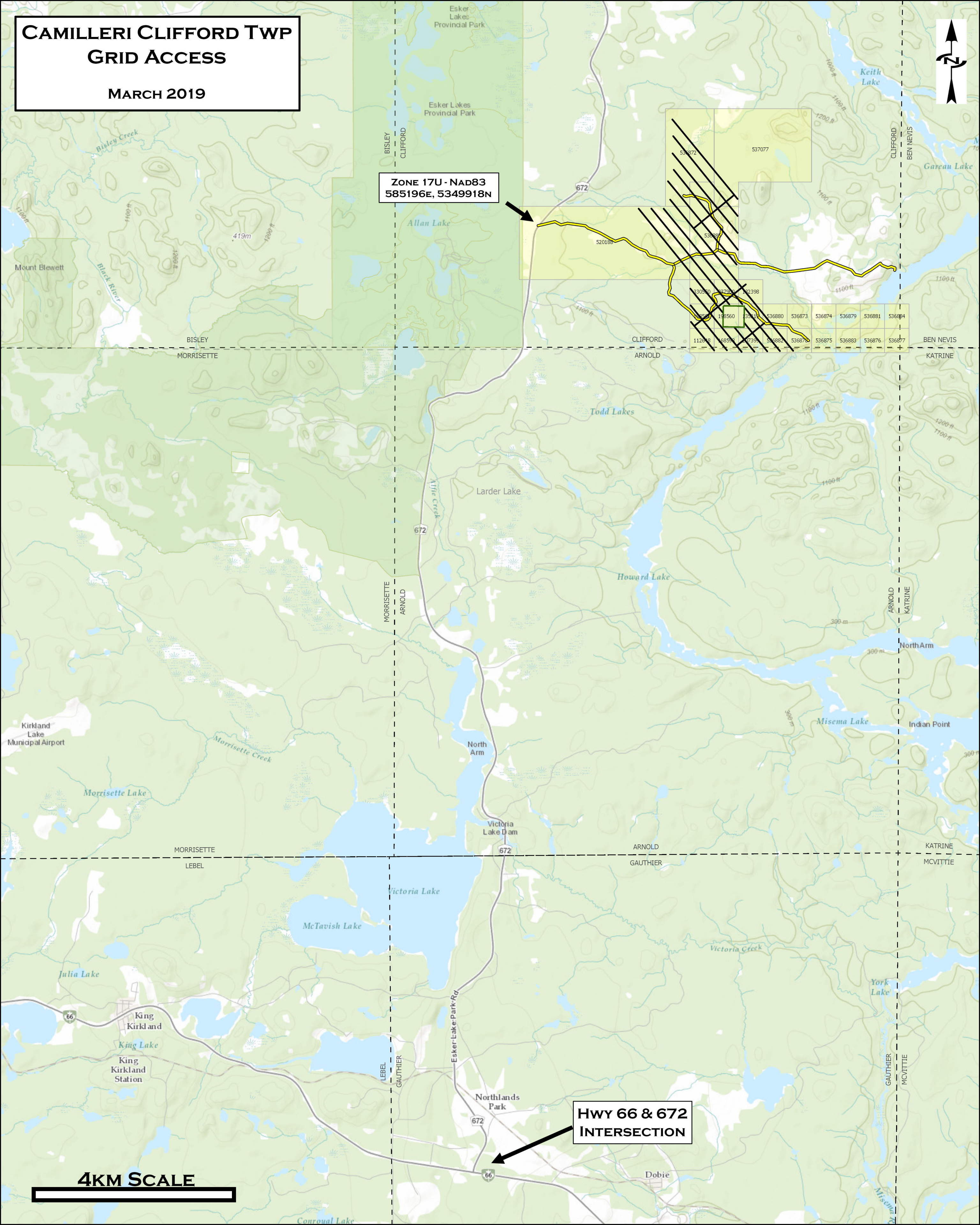
MARCH 2019



**ZONE 17U - NAD83  
585196E, 5349918N**

**HWY 66 & 672  
INTERSECTION**

**4KM SCALE**



Mount Blewett

Kirkland Lake Municipal Airport

Bisley Creek

Black River

Esker Lakes Provincial Park

Esker Lakes Provincial Park

BISLEY CLIFFORD

BISLEY MORRISETTE

MORRISETTE ARNOLD

MORRISETTE LABEL

LEBEL GAUTHIER

Central Lake

Allan Lake

Larder Lake

North Arm

Victoria Lake Dam

Northlands Park

66

672

672

672

672

520188

536872

536877

536880

536883

536886

536889

536892

536895

536898

536899

536902

536905

536908

536911

536914

536917

536920

536923

536926

536929

536932

CLIFFORD

ARNOLD

ARNOLD

GAUTHIER

Dobie

Keith Lake

Gareau Lake

Todd Lakes

Howard Lake

North Arm

Misema Lake

Indian Point

York Lake

Misema Cr.

BEN NEVIS

BEN NEVIS

ARNOLD

KATRINE

ARNOLD

KATRINE

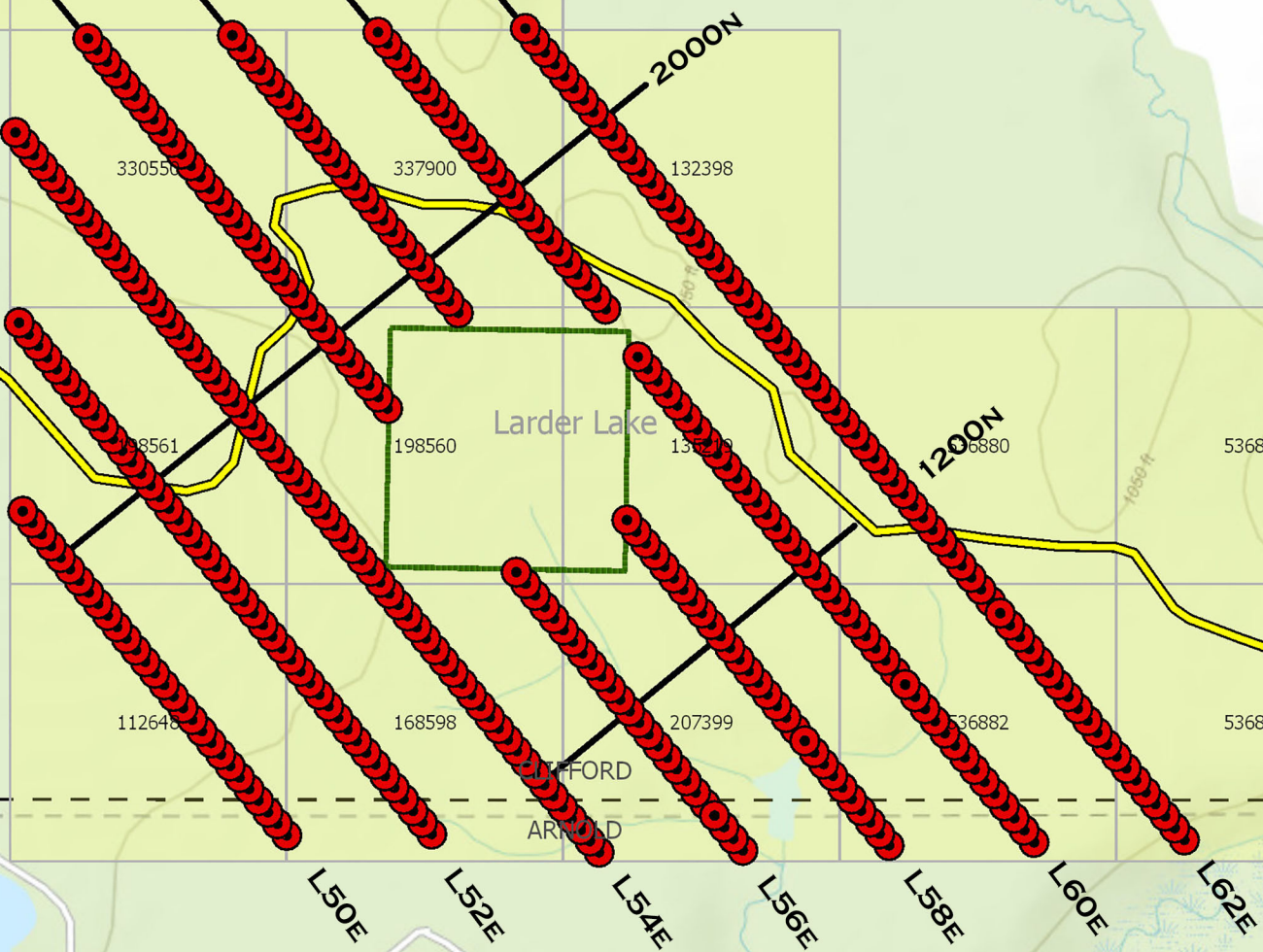
GAUTHIER

MCVITTIE

McVittie

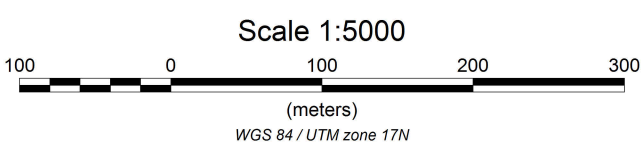
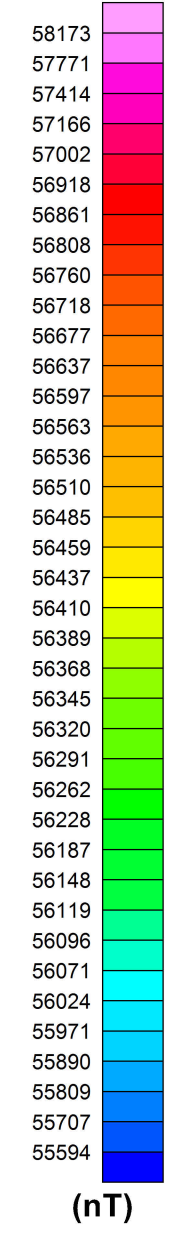
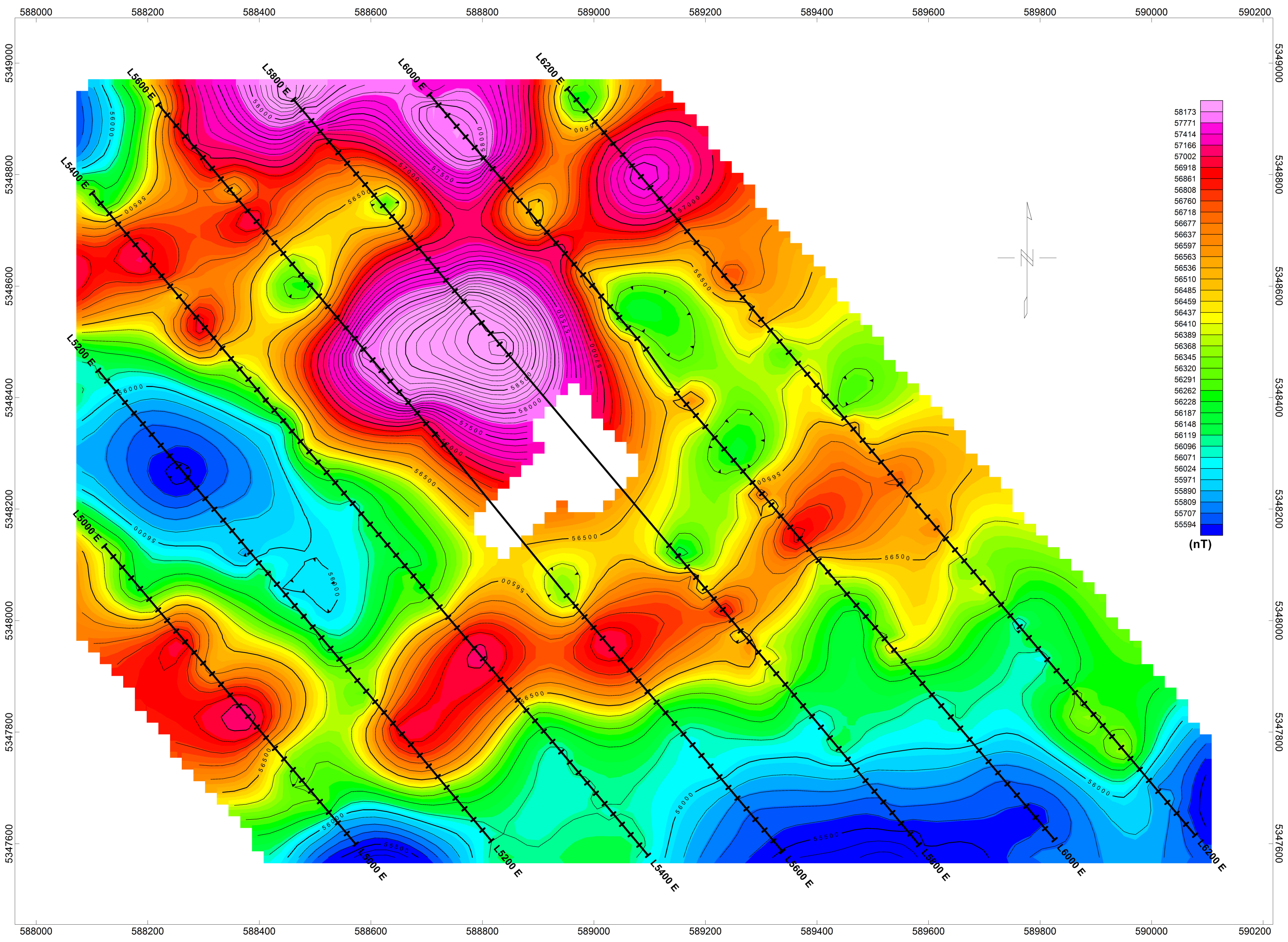


**JONATHAN CAMILLERI**  
CLIFFORD TWP.  
TFM GPS GRID  
MARCH 2019



**600M SCALE**





Jonathan Camilleri  
Clifford TFM Grid  
March 2019