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LOGISTICS REPORT ON COMBINED HELICOPTER-BORNE MAGNETIC AND VLF-EM SURVEY KUKAGAMI PROPERTY, ONTARIO

for DERRY, MICHENER, BOOTH, & WAHL by AERODAT LIMITED June, 1987

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# LIST OF MAPS

(Scale 1:10,000)

<u>Maps</u>

0. Photomosaic base.

1. Total Field Magnetic Contours

2. VLF-EM Total Field Contours.

#### 1. INTRODUCTION

This report describes an airborne geophysical survey carried out on behalf of Derry, Michener, Booth, & Wahl by Aerodat Limited. Equipment operated included a high-sense Cesium magnetometer, a VLF-EM system, a tracking camera, and a radar altimeter.

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The survey area, identified as the Kukagami Property, was located about 40 kilometres northeast of Sudbury, in Kelly Township, Ontario. The survey was flown in three flights on May 7, 1987. At a nominal line spacing of 100 metres, 66 transverse lines of 2.4 to 3.0 kilometres length totalling 178 line kilometres were flown to provide thorough coverage of survey block. The quality of the recorded geophysical data was considered to be well within the specifications described in the contract.

# 2. SURVEY AREA LOCATION

2 - 1

The survey area is depicted on the index map shown below. The flight line direction was 25 degrees west of north. The area is accessible by float plane to Kukagami Lake on the west or Maskinonge on the east; and by dirt road to within 6 kilometres south of the area.



### 3. AIRCRAFT AND EQUIPMENT

### 3.1 Aircraft

The helicopter used for the survey was an Aerospatiale A-Star 350B operated by Questral Helicopters Limited, with registration JIX. Installation of the geophysical and ancillary equipment was carried out by Aerodat. The survey aircraft was flown at a mean terrain clearance of 75 metres.

### 3.2 Equipment

## 3.2.1 VLF-EM System

The VLF-EM system was a Herz Totem 2A. This instrument measured the total field and quadrature components from two transmitting stations, providing two channels of both line and orthogonal information.

The sensor was towed in a bird 10 metres below the helicopter, 65 metres above the terrain. The transmitting station used for the line channels was NAA (Cutler, Maine, 24.0 kHz). For the orthogonal direction, station NSS (Annapolis, Maryland, 21.4 kHz) was received.

### 3.2.2 Magnetometer

The magnetometer was a Scintrex Cesium optically



pumped high sensitivity type. The sensitivity of the instrument was 0.2 gammas at a 0.2 second sampling rate. The sensor was towed in a bird 12 metres below the helicopter.

### 3.2.3 Magnetic Base Station

A Geometrics 803 proton precession magnetometer was operated at the base of operations to record diurnal variations of the earth's magnetic field. The clock of the base station was synchronized with that of the airborne system to facilitate later correlation.

### 3.2.4 Radar Altimeter

A King Air radar altimeter was used to record terrain clearance. The output from the instrument is a linear function of altitude for maximum accuracy.

### 3.2.5 Tracking Camera

A Geocam tracking camera was used to record flight path on 35mm film. The camera was operated in strip mode and the fiducial numbers for cross-reference to the analog and digital data were imprinted on the margin of the film.

# 3.2.6 Analog Recorder

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An RMS dot-matrix recorder was used to display the data during the survey. In addition to manual and time fiducials, the following data was recorded:

Channel	Input	Scale
MAGF	Magnetometer Sensor-Fine	2.5 nT/mm
ALT	Radar Altimeter	10 ft./mm
MAGN	Magnetometer Sensor-Noise	.025 nT/mm
VOQ	VLF-EM Quadrature - Ortho	2.5%/mm
VOT	VLF-EM Total Field - Ortho	2.5%/mm
VLQ	VLF-EM Quadrature - Line	2.5%/mm
VLT	VLF-EM Total Field - Line	2.5%/mm
MAGC	Magnetometer Sensor-Coarse	25.0 nT/mm

# 3.2.7 Digital Recorder

An RMS DGR 33 digital acquisition system recorded the survey on magnetic tape. Information recorded was as follows:

Equipment	Interval		
VLF-EM	0.2 seconds		
Magnetometer	0.2 seconds		
Altimeter	0.2 seconds		



Positional information was also recorded at 0.2 second

3 - 4

### 3.2.8 Radar Positioning System

intervals on a DAC/NAV I.

A Motorola Mini-Ranger (MRS III) radar navigation system was used for both navigation and flight path recovery. Transponders sited at fixed locations were interrogated several times per second and the ranges from these points to the helicopter measured to a high degree of accuracy. A navigational computer triangulates the position of the helicopter and provides the pilot with navigation information. The range/range data was recorded on magnetic tape for subsequent flight path determination.

#### 4. DATA PRESENTATION

4 - 1

### 4.1 Base Map and Flight Path

A photomosaic base at a scale of 1:10,000 was prepared by enlargement of aerial photographs of the survey area. This base was used for both the navigation and flight path recovery in conjunction with the 35 mm tracking film.

### 4.2 Total Field Magnetic Contours

The aeromagnetic data was corrected for diurnal variations by subtraction of the digitally recorded base station magnetic profile. No correction for regional variation was applied.

The corrected profile data were interpolated onto a regular grid at a 20m true scale interval using a cubic spline technique. The grid provided the basis for threading the presented contours at a 2 gamma interval.

The aeromagnetic data have been presented with flight path on a greyflex copy of the photo base map.

### 4.3 VLF-EM Total Field Contours

The line VLF-EM total field signals from Naa (Cutler,



Maine) were also gridded at a 20 metre interval and and presented on a greyflex copy of the photo base map along with the flight lines.

## 5. GENERAL INTERPRETIVE CONSIDERATIONS

#### Total Field Magnetics

The total field magnetic map shows contours of the total field using a high sensitivity magnetometer, at a fine contour interval of five gammas.

The magnetic map is characterized by numerous magnetic features and should be carefully correlated with existing geologic maps of the area. Such correlations should prove extremely useful for updating the known geology of the area.

#### VLF Electromagnetics

The VLF-EM method employs the radiation from powerful military radio transmitters as the primary signals. The magnetic field associated with the primary field is elliptically polarized in the vicinity of electrical conductors. The Herz Totem uses three coils in the X, Y, Z configuration to measure the total field and vertical quadrature component of the polarization ellipse.

The relatively high frequency of VLF (15-25 kHz) provides high response factors for bodies of low conductance. Relatively "disconnected" sulphide ores have been found to produce measureable VLF signals. For the same reason, poor conductors such as sheared contacts, breccia zones, narrow faults, alteration zones and porous

flow tops normally produce VLF anomalies. The method can therefore be used effectively for geological mapping. The only relative disadvantage of the method lies in its sensitivity to conductive overburden. In conductive ground the depth of exploration is severely limited.

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The effect of strike direction is important in the sense of the relation of the conductor axis relative to the energizing electromagnetic field. A conductor aligned along a radius drawn from a transmitting station will be in a maximum coupled orientation and thereby produce a stronger response than a similar conductor at a different strike angle. Theoretically, it would be possible for a conductor, oriented tangentially to the transmitter to produce no signal. The most obvious effect of the strike angle consideration is that conductors favourably oriented with respect to the transmitter location and also near perpendicular to the flight direction are most clearly rendered and usually dominate the map presentation.

The total field response is an indicator of the existence and position of a conductivity anomaly. The response will be a maximum over the conductor, without any special filtering, and strongly favour the upper edge of the conductor even in the case of a relatively shallow dip.

The vertical quadrature component over steeply dipping sheet-like conductors will be a cross-over type response with the cross-over closely associated with the upper edge of the conductor.

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The response is a cross-over type due to the fact that it is the vertical rather than total field quadrature component that is measured. The response shape is due largely to geometrical rather than conductivity considerations and the distance between the maximum and minimum on either side of the cross-over is related to target depth. For a given target geometry, the larger this distance the greater the depth.

The amplitude of the quadrature response, as opposed to shape is function of target conductance and depth as well as the conductivity of the overburden and host rock. As the primary field travels down to the conductor through conductive material it is both attenuated and phase shifted in a negative sense. The secondary field produced by this altered field at the target also has an associated phase shift. This phase shift is positive and is larger for relatively poor conductors. This secondary field is attenuated and phase shifted in a negative sense during return travel to the surface. The net effect of these 3 phase shifts determine the phase of the secondary field sensed at the receiver.

A relatively poor conductor in resistive ground will yield a net positive phase shift. A relatively good conductor in more conductive ground will yield a net negative phase shift. A combination is possible whereby the net phase shift is zero and the response is purely in-phase with no quadrature component.

A net positive phase shift combined with the geometrical cross-over shape will lead to a positive quadrature response on the side of approach and a negative on the side of departure. A net negative phase shift would produce the reverse. A further sign reversal occurs with a 180 degree change in instrument orientation as occurs on reciprocal line headings. During digital processing of the quadrature data for map presentation this is corrected for by normalizing the sign to one of the flight line headings.

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Respectfully submitted, AERODAT LIMITED

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Richard D.C. Yee P.Eng., Geophysicis

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June, 1987

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KELLY TOWNSHIP CLAIMS

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# **Ministry of Natural Resources**

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GEOPHYSICAL – GEOLOGICAL – GEOCHEMICAL TECHNICAL DATA STATEMENT

TO BE ATTACHED AS AN APPENDIX TO TECHNICAL REPORT FACTS SHOWN HERE NEED NOT BE REPEATED IN REPORT TECHNICAL REPORT MUST CONTAIN INTERPRETATION, CONCLUSIONS ETC.

Type of Survey(s) <u>Ai</u> Township or Area <u>V</u> Claim Holder(s) <u>N;</u> Survey Company <u>Ae</u> Author of Report	rborne H Kelly Ckeldale rodat L R.D.C. Y TORANT	elicoptor El Resources Hd./Derry M e.e. P.Ehy	cctromagnet Inc. ichenn Borth	ue and Magnetic MINING CLAIMS TRAVERSED List numerically vol Scre attached lisT (prefix) (number)
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# GEOPHYSICAL TECHNICAL DATA

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P	rofile scale		-	
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Z	Diurnal correction method			
MA	Base Station check-in interval (hours)			
<b>_</b>	Base Station location and value			
Ŋ	Instrument			
EL	Coil configuration		· · · · · · · · · · · · · · · · · · ·	
UN	Coil separation			
M	Accuracy			
IR	Method:	Shoot back	In line	Parallel line
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G	Parameters measured	(specify V.L.F. station)		
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Instrument	Range
Survey Method	
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Corrections made	
RADIOMETRIC	
Instrument	
Values measured	
Energy windows (levels)	
Height of instrument	Background Count
Size of detector	5
Overburden	
	(type, depth — include outcrop map)
OTHERS (SEISMIC, DRILL WEI	LL LOGGING ETC.)
Type of survey	
Instrument	
Accuracy	
Parameters measured	
Additional information (for under	standing results)
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Type of survey(s)	
Instrument(s)	(specify for each type of survey)
Accuracy	(specify for each type of survey)
Aircraft used	
Sensor altitude	
Navigation and flight path recovery	y method
Aircraft altitude	Line Spacing
Miles flown over total area	Over claims only

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Terrain	Analytical Method					
	Reagents Used					
Drainage Development	Field Laboratory Analysis					
Estimated Range of Overburden Thickness	No. (tests)					
	Extraction Method					
	Analytical Method					
	Reagents Used					
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(Includes drying, screening, crushing, ashing)	Name of Laboratory		<b>,</b>			
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KELLY TOWNSHIP CLAIMS

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