

# REPORT ON A HELICOPTER-BORNE MAGNETIC AND ELECTROMAGNETIC SURVEY

"featuring the AeroQuest AeroTEM® System"



2.29089

McArthur Property  
McArthur Township, Timmins Area, Ontario

for

## MUSTANG MINERALS CORP.

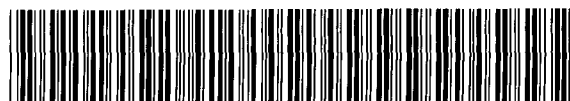
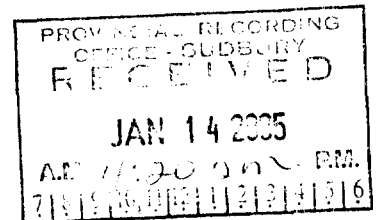
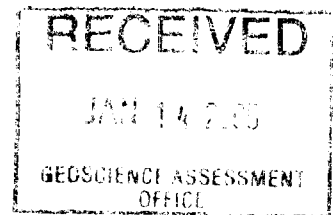
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by

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April, 2004



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## MAPS

The results of the survey are presented in a series of black line and colour maps at a scale of 1:10,000. Map products are as follows:

- Plate 1. Flight path with EM anomaly centres.
- Plate 2. Total Magnetic Intensity (TMI) colour grid w/line contours and anomaly centres.
- Plate 3. Z1 On-time, Z5 On-time,, and Z0 Off-time EM profiles and anomaly centres.
- Plate 4. Z0 Off-time EM colour grid w/line contours and anomaly centres.

All the maps show the flight path, claims fabric, and skeletal topography, and EM anomalies represented by conductance classified symbols. An anomaly identifier label, the estimated conductance in siemens, and the number of off-time channels of response are posted alongside the anomaly symbol. Colour contour maps show colour fill plus superimposed line contours.

## DIGITAL DATA on CD-ROM

The results of the survey are archived on a single CD-ROM as Geosoft GDB (binary) database(s) as well as Geosoft maps and magnetic grids. A *readme.txt* file may be found on the CD which describes the contents in more detail.

For the reader's convenience, a copy of Geosoft's Oasis Montaj Ver 6.0 Free Interface is included on the CD. To install the interface, unzip the two files and follow the instructions in the PDF format (Adobe Reader) guide.

The CD also contains a digital version of this report in PDF (Adobe Acrobat) format including the technical paper by Balch, et al, which is re-printed in the appendix of this report. Adobe Acrobat Reader Ver 5.0 has been included on the CD.

# **REPORT ON A HELICOPTER-BORNE MAGNETIC AND ELECTROMAGNETIC SURVEY**

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## **1. INTRODUCTION**

This report describes a helicopter-borne geophysical survey carried out on behalf of Mustang Minerals Corp. on the McArthur Property, in McArthur Township, in the Timmins Area of Ontario.

Principal geophysical sensors included AeroQuest's exclusive AeroTEM<sup>®</sup> time domain helicopter electromagnetic system and a high sensitivity cesium vapour magnetometer. Ancillary equipment included a GPS navigation system with GPS base station, radar altimeter, video recorder, and a base station magnetometer. Raw streaming EM data, consisting of 126 channels of Z and X component sampled at 300 times per second during both on-current and off-current times, was recorded. A second RMS "analogue" acquisition system recorded 6 Z-component and one X-component channels of semi-processed EM data at 7.5 times per second, in addition to recording GPS position, magnetic field, and terrain clearance.

Appendix 1 lists the UTM corner co-ordinates for the survey area as well as for the claim block outline. The total line kilometres (unwindowed) flown was 338.3 km. The survey flying described in this report took place on April 14 and 15, 2004.

Bedrock EM anomalies were interpreted and graded according to the estimated conductance. This report describes the survey, the data processing and presentation and includes an interpretation report, prepared separately by Mr. J. Rudd, in the appendix.

## **2. SURVEY AREA**

The McArthur survey block lies primarily in McArthur Township but a part spills over into Douglas Township to the east. The block lies approximately 31 km south-southeast of the city of Timmins and 53 km northwest of the village of Matachewan (Figure 1). Access to the area is by numerous logging roads and trails connecting to highway 101 and Timmins. The property is centred at 48°13'N latitude, 81°14'W longitude.

The McArthur Property consists of 14 unpatented mining claims covering 2357.3 hectares lying primarily in McArthur Township, but two claims lie east of the township line in Douglas Township. All the claims are within the Porcupine Mining Division. The claim block may be located on NTS 1:50,000 map sheets 42A/3 as well as Ontario claim Map G-3227.



Figure 1 Regional Setting in Ontario

McArthur Property Claims

Claim #	Township	Due Dates
P 3013869	DOUGLAS	2006-MAR-16
P 3013870	DOUGLAS	2006-MAR-16
P 3012766	MCARTHUR	2005-NOV-27
P 3012767	MCARTHUR	2005-NOV-27
P 3012778	MCARTHUR	2006-JAN-28
P 3012779	MCARTHUR	2006-JAN-28
P 3013865	MCARTHUR	2006-MAR-16
P 3013866	MCARTHUR	2006-MAR-16
P 3013867	MCARTHUR	2006-MAR-16
P 3013868	MCARTHUR	2006-MAR-16
P 3013871	MCARTHUR	2006-MAR-16
P 3013872	MCARTHUR	2006-MAR-16
P 3013873	MCARTHUR	2006-MAR-16
P 3013874	MCARTHUR	2006-MAR-16

The survey crew was accommodated at the Ramada Inn on Highway 101 west of Timmins, Ontario. Survey specification details may be found in the next section of the report.

### 3. SURVEY SPECIFICATIONS AND PROCEDURES

The survey specifications are summarised in the following table:

Area Name	Line Spacing (m)	Line Direction	Unwindowed Total Survey (km)	Windowed Total Survey (km)	Dates Flown (2004)
McArthur Survey	100	N-S	338.3	253.1	Apr 14 & 15

The unwindowed kilometres flown is calculated by adding up the survey and control (tie) line lengths as presented in the database. The windowed kilometres is determined in the same manner but after masking the database with an outline of the claims boundary. All the survey lines were flown in the UTM grid North/South direction. The control (tie) lines were flown perpendicular to the survey lines.

Nominal EM bird terrain clearance was ~30m (100 ft). The magnetometer sensor was mounted in a smaller bird connected to the tow rope 21 metres above the EM bird and 17 metres below the helicopter. Nominal survey speed was 75 km/hr. Scan rates for data acquisition was 0.1 second for the magnetometer, electromagnetics and altimeter and 0.2 second for the GPS determined position. This translates to a geophysical reading about every 2-3 metres along flight track.

Navigation was assisted by a GPS receiver and the RMS data acquisition system which reports GPS co-ordinates as NAD83 latitude/longitude and directs the pilot over a pre-programmed survey grid. The x-y-z position of the aircraft, as reported by the GPS, is recorded at 0.2 second intervals.

Unlike frequency domain electromagnetic systems, the AeroTEM<sup>®</sup> system has negligible drift due to thermal expansion. The system static offset is removed by high altitude zero calibration lines and employing local levelling lines.

The operator was responsible for ensuring the instrument was properly warmed up prior to departure and that the instruments operated properly throughout the flight. He also maintained a detailed flight log during the survey noting the times of the flight as well as any unusual geophysical or topographic features.

On return of the aircrew to the base camp, the RMS acquisition system survey data on FlashCard was downloaded to the data processing work station. The MDAS recorded data, on removable hard-drive, was also downloaded to the processing station and archived onto DVD. In-field processing included flight preparation, transfer of the RMS acquired data to Geosoft GDB database format and production of preliminary EM, magnetic contour, and flight path maps. Survey lines which showed excessive deviation from the intended flight path were re-flown.

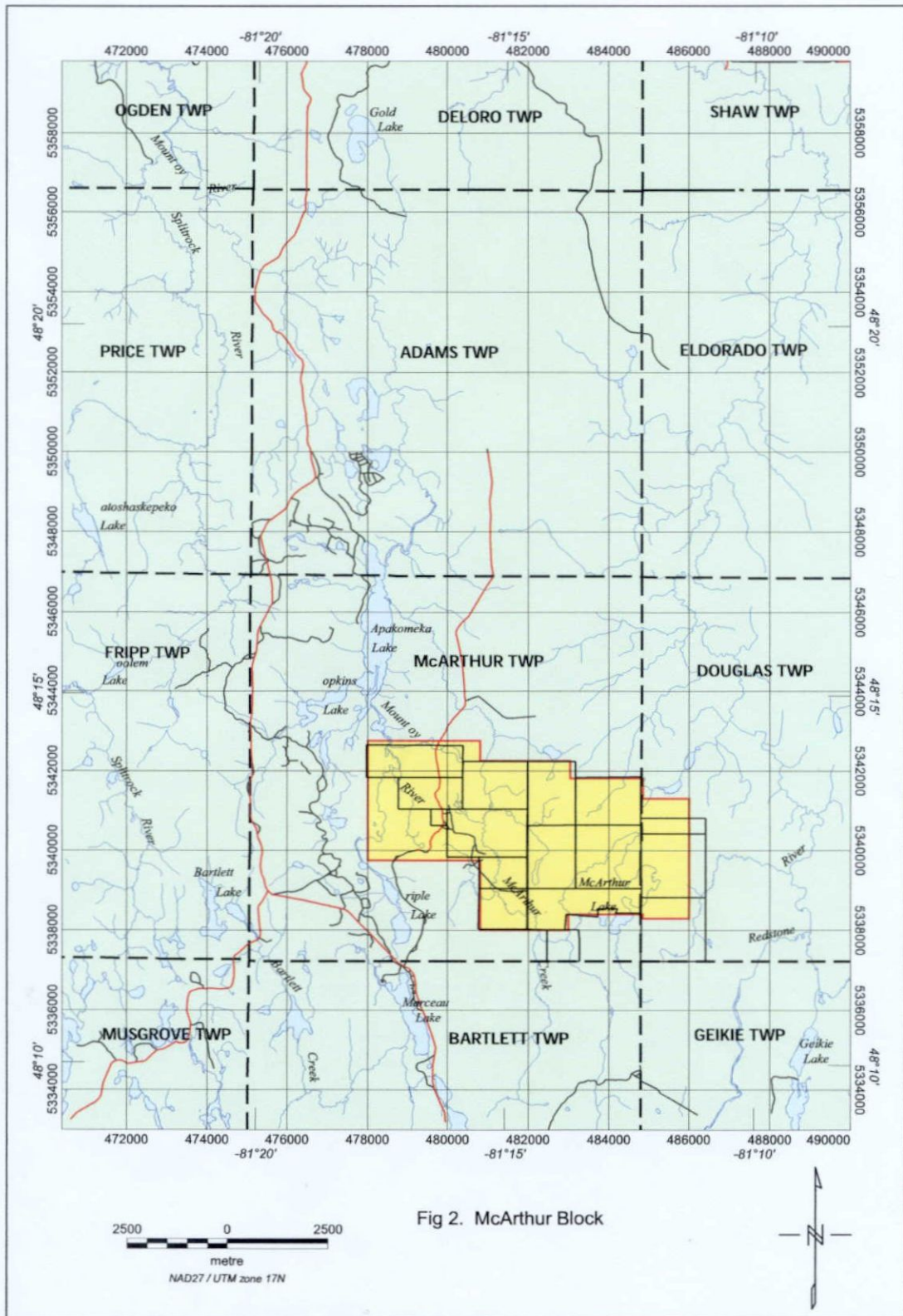


Fig 2. McArthur Block



## 4. AIRCRAFT AND EQUIPMENT

### 4.1 Aircraft

A Eurocopter (Aerospatiale) AS350B2 "A-Star" helicopter - registration C-FAVI was used as survey platform. The helicopters was owned and operated by Abitibi Helicopters Ltd., LaSarre, P.Q. Installation of the geophysical and ancillary equipment was carried out by AeroQuest Limited at the Gateway Helicopters Base in North Bay, Ont. then ferried to the survey area. The survey aircraft was flown at a nominal terrain clearance of 220 ft (70 m).

### 4.2 Magnetometer

The AeroQuest airborne survey system employed the Geometrics G-823A cesium vapour magnetometer sensor installed in a two metre towed bird airfoil attached to the main tow line, 17 metres below the helicopter. The sensitivity of the magnetometer is 0.001 nanoTesla at a 0.1 second sampling rate. The nominal ground clearance of the magnetometer bird was 51 metres (170 ft.). The magnetics data is recorded at 10Hz by the RMS DGR-33.



Fig.3 The mag bird (foreground) and EM bird

### 4.3 Electromagnetic System

The electromagnetic system employed was an AeroQuest AeroTEM<sup>®</sup> Time Domain towed bird system. A triangular transmitter on-time pulse of 1.150 millisecond is employed, at a base frequency of 150 Hz. During every tx on-off cycle (300 per second), 126 contiguous channels of raw x and z component (as well as a transmitter current monitor, itx) of the received waveform are measured. Each channel width is 26.455 microsec starting at the beginning of the Tx pulse on. This 126 channel data is referred to as the raw streaming data.



Fig.4 Instrument Rack

The AeroTEM system has two separate EM data recording streams, the conventional RMS DGR-33 and the MDAS system.

#### RMS DGR-33 Acquisition System

In addition to the magnetics, altimeter and position data, six time channels of on-board real time processed off-time EM decay in the Z direction and one in the X direction are recorded by the RMS DGR-33 acquisition system at 7.5 samples per second. These channels are derived by a real-time binning, stacking and filtering procedure on the raw streaming data. The RMS data (Z1 to Z6, X1) is also sent to the analogue chart recorder and is often referred to as the analogue data.

The channel window timing of the RMS DGR-33 6 channel system is described in the table below.

RMS Channel	Start time (microsec)	End time (microsec)	Width (microsec)	Streaming Channels	Noise tolerance
Z1, X1	1269.8	1322.8	52.9	48-50	20 ppb
Z2	1322.8	1455.0	132.2	50-54	20 ppb
Z3	1428.6	1587.3	158.7	54-59	15 ppb
Z4	1587.3	1746.0	158.7	60-65	15 ppb
Z5	1746.0	2063.5	317.5	66-77	10 ppb
Z6	2063.5	2698.4	634.9	78-101	10 ppb

### MDAS Acquisition System

The 126 channels of raw streaming are recorded by the MDAS acquisition system onto a removable hard drive. The streaming data may undergo post-survey processing to yield 33 stacked and binned on-time and off-time channels at a 10 Hz sample rate. The timing of those reduced streaming channels is described in the following table.

Processed Channel	Measured Channels	Start (microsec)	Stop (microsec)	Mid (microsec)	Width (microsec)
1 ON	24	634.9	661.4	648.1	26.5
2 ON	25	661.4	687.8	674.6	26.5
3 ON	26	687.8	714.3	701.1	26.5
4 ON	27	714.3	740.7	727.5	26.5
5 ON	28	740.7	767.2	754.0	26.5
6 ON	29	767.2	793.7	780.4	26.5
7 ON	30	793.7	820.1	806.9	26.5
8 ON	31	820.1	846.6	833.3	26.5
9 ON	32	846.6	873.0	859.8	26.5
10 ON	33	873.0	899.5	886.2	26.5
11 ON	34	899.5	925.9	912.7	26.5
12 ON	35	925.9	952.4	939.2	26.5
13 ON	36	952.4	978.8	965.6	26.5
14 ON	37	978.8	1005.3	992.1	26.5
15 ON	38	1005.3	1031.7	1018.5	26.5
16 ON	39	1031.7	1058.2	1045.0	26.5
0 OFF	44	1164.0	1190.5	1177.2	26.5
1 OFF	45	1190.5	1216.9	1203.7	26.5
2 OFF	46	1216.9	1243.4	1230.2	26.5
3 OFF	47	1243.4	1269.8	1256.6	26.5
4 OFF	48	1269.8	1296.3	1283.1	26.5
5 OFF	49	1296.3	1322.8	1309.5	26.5
6 OFF	50	1322.8	1349.2	1336.0	26.5
7 OFF	51	1349.2	1375.7	1362.4	26.5
8 OFF	52	1375.7	1402.1	1388.9	26.5
9 OFF	53	1402.1	1428.6	1415.3	26.5
10 OFF	54	1428.6	1455.0	1441.8	26.5
11 OFF	55	1455.0	1481.5	1468.3	26.5
12 OFF	56	1481.5	1507.9	1494.7	26.5
13 OFF	57-60	1507.9	1640.2	1574.1	132.3
14 OFF	61-68	1613.8	1825.4	1719.6	211.6
15 OFF	69-84	1825.4	2248.7	2037.0	423.3
16 OFF	85-116	2248.7	3095.2	2672.0	846.6

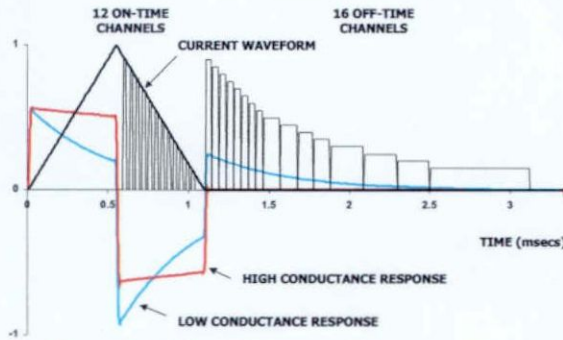


Fig. 5 Schematic of Tx and Rx waveforms

The current AeroTEM<sup>®</sup> Transmitter Dipole moment is 38.8 kNIA. The AeroTEM<sup>®</sup> bird was towed 38 metres (125 ft) below the helicopter. More technical details of the system may be found in the technical paper in the Appendix.

#### 4.4 Ancillary Systems

##### Magnetometer and GPS Base Station

An integrated GPS and magnetometer base station was set up to monitor the static position GPS errors to permit differential post-processing and to record the diurnal variations of the earth's magnetic field. Each sensor, GPS and magnetic, receiver/signal processor was attached to a dedicated laptop computer for purposes of instrument control and/or data display and recording. The laptops were, in turn, linked together to provide a common recording time reference using the GPS clock.

The base magnetometer was a Scintrex CS-2 cesium precession magnetometer coupled with a Picodas MEP-710 frequency counter/decoupler. Data logging and magnetometer control was provided by the Picodas *basemag.exe* software. The logging was configured to measure at 1.0 second intervals. Digital recording resolution was 0.1 nT. The sensor was placed on a tripod away from potential noise sources in the parking lot of the Ramada Hotel. A continuously updated profile plot of the base station values was available for viewing on the base station display.

The GPS base station employed a Leica Mx9212 12 channel GPS receiver with external antenna mounted near the magnetometer sensor. Although the GPS receiver was controlled by the Picodas *cdu510.exe* software, logging was not engaged as the aircraft employed a real-time differential GPS receiver. The base GPS was used only for the GPS clock for synchronisation purposes.

##### Radar Altimeter

A Terra TRA 3500/TRI-30 radar altimeter was used to record terrain clearance. The antenna was mounted on the outside of the helicopter beneath the cockpit. The recorded data represented the height of the antenna, i.e. helicopter, above the ground. The Terra altimeter has an altitude accuracy of +/- 1.5 metres.

### **Video Tracking and Recording System**

A high resolution colour VHS/8mm video camera was used to record the helicopter ground flight path along the survey lines. The video is digitally annotated with GPS position and time and can be used to verify ground positioning information and cultural causes of anomalous geophysical data.

### **GPS Navigation System**

The navigation system consisted of an Ag-Nav Inc. AG-NAV2 GPS navigation system comprising a PC based acquisition system, navigation software, a deviation indicator in front of the aircraft pilot to direct the flight, a full screen display with controls in front of the operator, a Trimble AgGPS132 WAAS enabled GPS receiver mounted on the instrument rack and a Trimble antenna mounted on the magnetometer bird.

WAAS (Wide Area Augmentation System) consists of approximately 25 ground reference stations positioned across the United States that monitor GPS satellite data. Two master stations, located on either coast, collect data from the reference stations and create a GPS correction message. This correction accounts for GPS satellite orbit and clock drift plus signal delays caused by the atmosphere and ionosphere. The corrected differential message is then broadcast through one of two geostationary satellites, or satellites with a fixed position over the equator. The corrected position has a published accuracy of under 3 metres. A recent static ground test of the Trimble WAAS GPS yielded a standard deviation in x and y of under 0.6 metres and for z under 1.5 metres over a two hour period.

Survey co-ordinates are set-up prior to survey and the information is fed into the airborne navigation system. The co-ordinate system employed in the survey design was NAD27 Canada Mean UTM. The real-time differentially corrected GPS positional data was recorded by the RMS DGR-33 in NAD27 latitude and longitude at 0.2 second intervals directly in the analogue geophysical data file. The datum of the recorded latitude/longitude depended on the datum defined in the navigation file used to guide the survey aircraft.

### **Digital Acquisition System**

The RMS Instruments DGR33A data acquisition system was used to collect and record the analogue data stream, i.e. the geophysical and positional data, including processed 6 channel EM, magnetic, radar altimeter, GPS position, and time. The data was recorded on 128Mb capacity FlashCard. The RMS output was also directed to a thermal chart recorder.

The AeroTEM received waveform sampled during on and off-time at 126 channels per decay, 300 times per second, was logged in parallel by the proprietary MDAS data acquisition system. The channel sampling commences at start of the Tx cycle and the width of each channel is 26.445 microseconds. The streaming data was recorded on a removable hard-drive and was later backed-up onto DVD-ROM on the field-processing computer.

## **5. PERSONNEL**

The following AeroQuest personnel were involved in the project

Field -

Party Chief: Bert Simon

Data Processor: Neil Fiset

Operator: Chris Kozak

Office-

Data Processing and Report: Neil Fiset/Chris Balch/Steve Balch

Interpretation: Jonathan Rudd

The survey pilot, Joel Breton, was employed directly by the helicopter operator - Abitibi Helicopters Ltd.

## **6. DELIVERABLES**

The report includes a set of four geophysical maps plotted at 1:10,000 scale. The map types are as follows:

- Plate 1. Flight path with EM anomaly centres.
- Plate 2. Total Magnetic Intensity (TMI) colour grid w/line contours and anomaly centres.
- Plate 3. Z1 On-time, Z5 On-time, and Z0 Off-time EM profiles and anomaly centres.
- Plate 4. Z0 Off-time EM colour grid w/line contours and anomaly centres.

The basic map coordinate/projection system used to create the maps was NAD27 Canada Mean Universal Transverse Mercator Zone 17. For reference, the latitude and longitude are also noted on the maps.

All the maps show flight path trace with time reference fiducials marked at a 10 second interval, skeletal topography, claims fabric, and conductor picks represented by an anomaly symbol classified according to estimated conductance. The anomaly symbol is accompanied by postings denoting the conductance, an anomaly identifier label and the number of off-time channels of response. The anomaly symbol legend may be found in the margin of the maps. Colour contour maps show colour fill plus superimposed line contours.

The geophysical profile data is archived digitally in a Geosoft GDB binary format database. The binary database contains both the processed streaming data and the RMS data.

The Geosoft database included is as follows (filename extension is ".gdb"):

<u>Area</u>	<u>RMS &amp; Streaming Data</u>
McArthur	McArthur.gdb

A description of the various channels found in this database may be found in the appendices of this report.

An archive CD complements the hard copy report and maps. It contains the digital database as well as the geophysical maps and grids in Geosoft format.

## **7. DATA PROCESSING AND PRESENTATION**

All in-field and post-field data processing was carried out using Geosoft Montaj as well as AeroQuest proprietary data processing software. Plotting was on a 36 inch wide HP650C ink-jet plotter.

### **7.1 Base Map**

The geophysical maps accompanying this report are based on positioning in the datum of NAD27 Canada Mean. The survey geodetic GPS positions have been map projected using the Universal Transverse Mercator projection in Zone 17.

A summary of the map datum and projection specifications are as follows:

Ellipse: Clark 1866

Ellipse major axis: 6378206.4m eccentricity: 0.082271854

Datum: North American 1927 - Canada Mean

Datum Shifts (x,y,z) : 10, -158, -187 metres

Map Projection: Universal Transverse Mercator Zone 17 (Central Meridian 81°W)

Central Scale Factor: 0.9996

False Easting, Northing: 500,000m, 0m

The skeletal topography, provided by Mustang Minerals Corp., was derived from the digital Ontario Base Map (OBM) 1:20,000 map series. The claims fabric was downloaded from the MNDM website in NAD83 then reprojected to NAD27 Canada Mean before merging with the topographic data.

## **7.2 Flight Path & Terrain Clearance**

The position of the survey helicopter was directed by use of the Global Positioning System (GPS). Positions were updated five times per second (5Hz) and expressed as NAD27 latitude and longitude calculated from the raw pseudorange derived from the C/A code signal.

The instantaneous GPS flight path, after conversion to UTM co-ordinates, is drawn using linear interpolation between the x/y positions. The time reference fiducials are drawn on the map at appropriate intervals and are used to reference the digital data files to the plan map.

The raw Digital Terrain Model (DTM) was derived by simply taking the satellite position altitude and subtracting the radar altimeter. The calculated values are relative and are not tied into to surveyed geodetic heights.

## **7.3 Electromagnetic Data**

The raw streaming data, sampled at a rate of 38,400 Hz (126 channels, 300 times per second) was reprocessed using a proprietary software algorithm developed by Mr. Steve Balch. Processing began with a segmenting and synchronisation procedure that isolates the relevant portion of the flight and pre-processes the time series to ensure data synchronisation is maintained. The pre-processed segment was then partially stacked and tested for high noise events, including sferics, which are skipped during the main stacking procedure. The coefficients for the waveform deconvolution process were also determined.

During the main processing algorithm, data were stacked for 40 full-cycles or 0.2 seconds. Deconvolution of the system waveform, primary field removal during the on-time, and system transient removal during the off-time were performed ahead of the stacking. The data were then binned into the 16 On-time and 17 Off-time channels and their base levels corrected. The resulting profiles were then filtered using a filter with 11 coefficients. An overburden stripped response was generated by subtracting the off-time response from the on-time response for the X1 to X16 and Z1 to Z16 channels.

The final processing step was to merge the processed EM data back into a Geosoft GDB file with the GPS position, altimeter, levelled magnetics, etc. data. The EM fiducial is used to synchronise the two datasets. The processed channels are labelled in the database as ZOn1 to ZOn16, ZOff0 to ZOff16, XOn1 to XOn16, and XOff0 to XOff16. The overburden stripped channels are labelled Z1Obr to Z16Obr and X1Obr to X16Obr. In the database, the processed AeroTEM EM channels are expressed as nT/sec. To convert to parts per billion (ppb), multiply by 6.96.



Conductors were interpreted based on a close visual examination of the EM profiles and taking into account the magnetic data along with geological and geochemical data provided by the client. A report of that interpretation may be found in the Appendices.

Conductors were interpreted based on a close visual examination of the EM profiles and taking into account the magnetic data along with geological and geochemical data provided by the client. A report of that interpretation may be found in the Appendices.

At each conductor pick, the on-time and off-time conductance have been calculated based on a conventional vertical thin sheet model and where the channel response satisfies a threshold of 5.0 nT/s on-time and 2.5 nT/s off-time. From these calculated values, an interpreted conductance (COND) value has been assigned to each anomaly. The assigned value is determined from the off-time response, unless there are 16 off-time channels with nT/s >2.0 in the response. In that event the assigned value is taken from the on-time because of the higher conductance. In the case of conductors marked by a double peak type response (thin, shallow sources) where the EM coupling is a minima over or near the conductor axis, the conductance value (COND) is derived from the higher response area adjacent to the axis. For each interpreted conductor, the number of off-time channels of response (from channels ZOff1-ZOff16) above the threshold is also noted.

Each conductor pick has been given an identification letter label and has also been classified according to a set of seven ranges of conductance values. The anomalies were then plotted on the plan maps with one of seven symbols reflecting that classification level. Adjacent to the map symbol is posted the identifier label as well as the interpreted conductance values in siemens, and the number of off-time channels of response above 2.5nT/sec. The maximum possible number of off-time channels is 16 given the first channel of the 17 processed channels is not included.

With regard to the six channel off-time data recorded by the RMS DGR-33, after a lag correction then a two stage digital filtering process was used to remove any residual short wavelength noise. Sharp large amplitude events were removed with a 0.4 sec non-linear filter. The signal to noise ratio was further improved by the application of a low pass linear digital filter. This filter has zero phase shift which prevents any lag or peak displacement from occurring, and it suppresses only variations with a wavelength less than about 1.0 seconds or 30 metres. This filter is referred to as a 1.0 sec linear filter. The raw channels are denoted in the database with the suffix "raw", e.g. z1raw, x1raw, etc. The filtered channels are indicated by the "f" suffix, e.g.. z1f, x1f, etc.

During the high elevation checks, an internal 5 second wide calibration pulse in all EM channels was generated in order to ensure that the gain of the system remained constant and within specifications.

#### **7.4 Magnetic Data**

Prior to any levelling the magnetic data was subjected to a lag correction of -0.1 seconds and a spike removal filter. The filtered aeromagnetic data were then corrected for diurnal variations using the magnetic base station and the intersections of the tie lines. No corrections for the regional reference field (IGRF) were applied. The corrected profile data were interpolated on to a grid using a random grid technique with a grid cell size of 25 metres. The final levelled grid provided the basis for threading the presented contours which have a minimum contour interval of 10 nT.

Respectfully submitted,



Neil Fiset, B.Sc.,  
AeroQuest Limited  
August 18, 2004

**APPENDIX 1**

Interpretation Report by J. Rudd

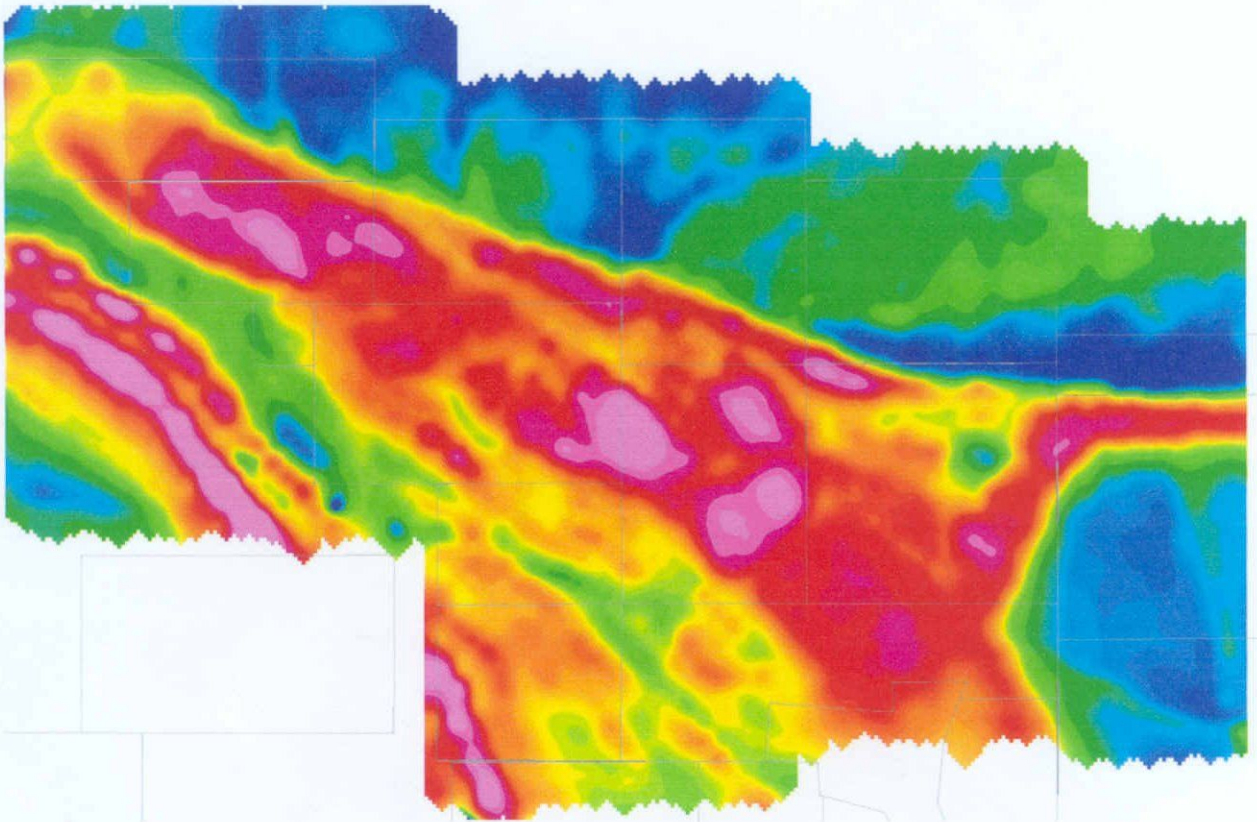
# INTERPRETATION REPORT

Summary of an AeroTEM Airborne Geophysical Survey

on the McArthur Property

for

Mustang Minerals Corp.



by

Jonathan Rudd

August 14, 2004

## **Introduction**

Aeroquest Limited flew an AeroTEM helicopter electromagnetic and magnetometer survey over the McArthur Property owned by Mustang Minerals Corp. on April 14 and 15, 2004. The main purpose of the survey was to detect new Ni-Cu-PGM mineralization associated with possible ultramafic units. The second purpose of the survey was to identify other conductive targets that have the potential to be a mineralizing system and to characterize these targets as well. The AeroTEM survey comprised a total of 338 1-km with a line spacing of 100m. Conductor picks are listed in Appendix A.

## **Results**

The magnetic data set is dominated by two northwest trending dykes and a large broad magnetic high which extends with a general northwest trend through the central portion of the survey area. The two interpreted magnetic dykes have different characteristics. The southwestern one has a stronger magnetic susceptibility and has no associated conductive response whereas the northeastern one has a lower magnetic response and has a conductive response along its entire length. The conductive nature of the northeast dyke is described below. The magnetic high in the central portion of the survey area may be reflecting an ultramafic intrusion, so any conductivity within this feature or at its margins would be prospective for Ni-Cu-PGM mineralization.

There is only one highly conductive source in the survey area (at 'A' on Figure 1). This trend coincides with the northeastern of the two northwest trending magnetic linears. The conductance along the strike of this feature is variable, and appears to be independent of the strength of the magnetic response. As a result, it is likely that the conductance is only associated with the magnetic response and is not the same source. The source of the conductance is likely to be a formational feature. However, the source should be followed up on at least one line to identify the source.

There are no priority follow-up targets for potential Ni-Cu-PGM mineralization. There are several other weak to moderate conductance sources in the survey area. None of these correlate with discrete magnetic features. The stronger features such as anomaly 390A, 440A and 490B (in the vicinity of 'B' on Figure 1) should be followed up for possible VMS sources. The very weak anomalies, 130B, 140B and 150B in the vicinity of 'C' on Figure 1 should be followed up for possible PGM-rich mineralization because of their position at or near the southern margin of the main central magnetic unit.

Respectfully Submitted,

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Jonathan Rudd  
Aeroquest Limited

## Appendix A – EM Anomaly Listing

LINE	Easting	Northing	Num	Cond	# of Chan's	LABEL	DESCRIPTION
10	478002	5341394	1	1.6	9	A	Low conductance, thin source, sub-vertical, north dip, correlating magnetic response
20	478099	5341331	1	2.6	15	A	Low conductance, thin source, sub-vertical, north dip, correlating magnetic response
30	478203	5341323	1	0.8	13	A	Low conductance, thin source, sub-vertical, north dip, correlating magnetic response, response appears deeper on this line
40	478300	5341250	1	3.7	15	A	Low conductance, thin source, sub-vertical, north dip, correlating magnetic response, possibly multiple conductors on this line
50	478402	5341195	1	3.2	16	A	Low to moderate conductance, thin source, sub-vertical, south dip, correlating magnetic response, appears close to surface on this line
60	478500	5341135	1	29.2	16	A	High conductance, thicker source, correlating magnetic response, higher conductance related to thicker source
70	478601	5341075	1	5.5	15	A	Moderate conductance, multiple closely spaced sources, correlating magnetic response
80	478699	5341820	1	0.4	5	B	Very low conductance, higher conductance feature within a broader overburden-style response, correlating weak magnetic high
80	478702	5341014	2	30.2	16	A	High conductance, correlating magnetic response, close to surface
90	478802	5340952	1	39.4	16	A	High conductance, north dipping, close to surface correlating magnetic response
90	478804	5341880	2	0.7	3	B	Very low conductance, higher conductance feature within a broader overburden-style response, no correlating magnetic response
100	478903	5340864	1	5.2	14	A	Moderate conductance, correlating magnetic response, source is probably deeper on this line
110	479004	5340829	1	4.1	13	A	Weak to moderate conductance, probable north dip, correlating magnetic high, source is likely small and slightly buried
120	479097	5340615	1	0.6	9	A	Low indicated conductance, deep source with correlating magnetic high
130	479202	5340643	1	2.4	3	A	Low conductance, probably multiple closely spaced conductors, correlating magnetic high
130	479202	5341419	2	0.1	5	B	Low conductance, thin, south dipping feature flanking the north side of a weak magnetic high
140	479298	5341326	1	0.4	2	B	Low conductance, thin, south dipping feature flanking the north side of a weak magnetic high

140	479296	5340452	2	2.3	15	A	Low conductance, thin, sub-vertical to south-dipping source with correlating magnetic high
150	479404	5340321	1	2.7	4	A	Low conductance, possible multiple closely spaced sources with correlatin magnetic high
150	479402	5341320	2	0.3	5	B	Low conductance, thin, vertical feature at the boundary between low magnetic (south) and higher magnetics (north)
160	479496	5340144	1	19.0	15	A	Moderate to high conductance feature with sub-vertical north dip and a weak correlating magnetic high
170	479602	5340064	1	37.0	16	A	High conductance feature with a north dip and a weak correlating magnetic high
180	479699	5340825	1	3.4	15	B	Low conductance feature with no correlating magnetic response
180	479700	5339960	2	81.1	16	A	High conductance feature with a north dip and a weak correlating magnetic high
190	479806	5339896	1	45.6	16	A	High conductance feature with a sub-vertical north dip and a weak correlating magnetic high
190	479796	5340830	2	0.6	11	B	Low conductance, thin source with no correlating magnetic response
200	479903	5339799	1	7.7	4	A	Moderate to high conductance feature, probable multiple closely spaced sources, correlating magnetic high
210	479995	5339655	1	21.0	16	A	High conductance feature, probable multiple closely spaced sources, correlating magnetic high
210	480004	5342551	2	0.0	3	B	Very weak source with no correlating magnetic response
220	480101	5342545	1	0.0	4	B	Very weak source with no correlating magnetic response
220	480099	5339570	2	6.3	14	A	Moderate conductance feature with correlating magnetic high, source is close to end of line, so response is not fully defined
230	480204	5342503	1	0.0	4	A	Very weak source with no correlating magnetic response
290	480801	5338616	1	15.0	16	A	Moderate to high conductance feature, probable multiple closely spaced sources, correlating magnetic high
290	480799	5340044	2	1.1	14	B	Low conductance feature with no correlating magnetic response, dipping to the north
290	480803	5340349	3	1.2	13	C	Small, low conductance source with possible correlation with weak magnetic high response
300	480900	5338498	1	33.9	16	B	High conductance feature with a correlating magnetic high
300	480902	5338318	2	42.5	16	A	High conductance feature with a correlating magnetic high
310	481000	5338118	1	30.8	16	A	High conductance feature, probable multiple closely spaced sources, correlating magnetic high

320	481104	5337897	1	26.3	16	B	High conductance feature, probable multiple closely spaced sources, correlating magnetic high
320	481103	5337773	2	36.9	16	A	High conductance feature, probable multiple closely spaced sources, correlating magnetic high
390	481800	5339632	1	6.2	14	A	Moderate conductance source, probable end response from adjacent line, no discrete magnetic correlation
400	481900	5339641	1	2.0	14	A	Low conductance source, no magnetic correlation
400	481899	5339540	2	1.4	1	B	Small, low conductance source with no correlating magnetic response
410	481999	5339590	1	2.4	13	A	Small, low conductance source with possible correlation with weak magnetic high response
440	482297	5338932	1	7.3	13	A	Low conductance source, no magnetic correlation
450	482401	5338950	1	1.4	12	A	Low conductance source, no magnetic correlation
490	482798	5339084	1	2.3	14	A	Low conductance source, no magnetic correlation
490	482808	5338829	2	8.7	15	B	Moderate conductance source, no magnetic correlation
510	483001	5339137	1	1.5	6	A	Small (single line) low conductance source, no discrete magnetic correlation
99902	478082	5341400	1	12.4	15	A	Moderate conductance feature with correlating magnetic high
99903	479379	5340401	1	8.9	15	A	Moderate conductance thin feature with correlating magnetic high



**APPENDIX 2**

Block corner co-ordinates (UTM Zone 17 - NAD27 Canada Mean)

McArthur Survey Block Outline			
478000.0mE	5339750.0mN	486000.0mE	5341300.0mN
478000.0mE	5342750.0mN	486000.0mE	5338300.0mN
480400.0mE	5342750.0mN	484850.0mE	5338300.0mN
480800.0mE	5342750.0mN	484850.0mE	5338400.0mN
480800.0mE	5342250.0mN	483000.0mE	5338400.0mN
483050.0mE	5342250.0mN	483000.0mE	5338000.0mN
483050.0mE	5341800.0mN	480800.0mE	5338000.0mN
484850.0mE	5341800.0mN	480800.0mE	5339750.0mN
484850.0mE	5341300.0mN	478000.0mE	5339750.0mN

McArthur Claim Block Outline			
480767.6mE	5338029.0mN	484804.3mE	5341843.0mN
480774.9mE	5339048.4mN	484804.6mE	5340820.0mN
480778.8mE	5339847.2mN	486407.7mE	5340820.0mN
479976.1mE	5339843.3mN	486407.9mE	5338823.5mN
479975.6mE	5340623.6mN	484810.4mE	5338819.0mN
479582.2mE	5340628.5mN	484806.7mE	5338428.9mN
479577.1mE	5341034.8mN	484169.8mE	5338428.9mN
478776.0mE	5341031.6mN	484219.4mE	5338543.5mN
478771.1mE	5341832.9mN	483735.4mE	5338538.5mN
477979.3mE	5341837.6mN	483731.9mE	5338341.0mN
477979.2mE	5342641.2mN	482937.4mE	5338403.5mN
480379.1mE	5342635.8mN	482909.8mE	5338021.0mN
480379.1mE	5342234.0mN	482478.0mE	5338017.7mN
481980.9mE	5342239.4mN	481967.6mE	5338021.7mN
483180.8mE	5342234.0mN	480767.6mE	5338029.0mN
483180.8mE	5341832.2mN		

### APPENDIX 3

#### Description of Database Fields (Geosoft GDB database)

Column	Description
x	Zone 17 UTM Easting in metres (NAD27-Canada Mean)
y	Zone 17 UTM Northing in metres (NAD27-Canada Mean)
x83	Zone 17 UTM Easting in metres (NAD83)
y83	Zone 17 UTM Northing in metres (NAD83)
lat	Latitude in decimal degrees (NAD27-Canada Mean)
long	Longitude in decimal degrees (NAD27-Canada Mean)
lat83	Latitude in decimal degrees (NAD83)
long83	Longitude in decimal degrees (NAD83)
fiducial	Time reference fiducial in seconds
manfid	Manual Fiducial
chartfid	Chart Recorder Fiducial
emfid	Fiducial counter for streaming data synchronisation
utctime	UTC Time in seconds of the day
rtctime	Local (System) time in HH:MM:SS
fitno	Flight number
date	Date in YY/MM/DD format
galtf	GPS Altitude in metres
ralt	Radar Altimeter in metres
bheight	Terrain clearance of EM bird in feet
dtm	Raw Digital Terrain Model in metres
basemag	Base Station magnetic field in nT
rawmag	Raw total magnetic intensity in nT
mag	Diurnally corrected Total Magnetic Intensity in nT
magtie	Final levelled Total Magnetic Intensity in nT
x1	Raw RMS Off-Time EM-X component of channel 1 in ppb
z1raw-z6raw	Raw RMS Off-Time EM-Z component of channels 1 to 6 in ppb
x1f	Smoothed RMS Off-Time EM-X component of channel 1 in ppb
z1f-z6f	Smoothed RMS Off-Time EM-Z component of channels 1 to 6 in ppb
ZOn1-ZOn16	Processed Streaming On-Time Z component Channels 1-16 in nT/sec
ZOff0-ZOff16	Processed Streaming Off-Time Z component Channels 0-16 in nT/sec
XOn1-XOn16	Processed Streaming On-Time X component Channels 1-16 in nT/sec
XOff0-XOff16	Processed Streaming Off-Time X component Channels 0-16 in nT/sec
Z1Obr-ZObr16	Overburden stripped Z component response Channels 1-16 in nT/sec
X1Obr-XObr16	Overburden stripped X component response Channels 1-16 in nT/sec
ZOff17-ZOff22	Special weighted combination channels in nT/sec (see note below)
anum	Index number of conductor pick

anomlabel	Letter label of conductor pick
nchan	No of off-time (or on-time) channels with response over 2.5nT/sec
on_con	On-time conductance in siemens
off_con	Off-time conductance in siemens
Aclass	Classification from 1-7 based on conductance of pick
cond	Interpreted conductance in siemens

Weighted channels:

ZOff17:  $0.25*ch44 + 0.50*ch45 + 0.25*ch46$

ZOff18 :  $(ch46+ch47)/2$

ZOff19 :  $(ch48+ch49+ch50+ch51)/4$

ZOff20 :  $(ch52..ch59)/8$

ZOff21 :  $(ch60..ch75)/16$

ZOff22 :  $(ch76..ch107)/32$

In the databases the Survey lines, Tie Lines, and High Altitude/Internal Q coil lines are prefixed with an "L" or "Line", "T" or "Tie", and "S" or "Test", respectively.

**APPENDIX 4**      Technical Paper

**Mineral Exploration with the AeroTEM System**

*S.J. Balch, W.P. Boyko, G. Black, and R.N. Pedersen, AeroQuest Limited, Presented at the SEG Int'l Exposition and 72nd Annual Meeting, Salt Lake City, Utah, October 6-11, 2002*

## Mineral Exploration with the AeroTEM System

S.J. Balch\*, W.P. Boyko, G. Black, and R.N. Pedersen, AeroQuest Limited.

### Summary

AeroTEM is a concentric-loop time-domain EM system designed for mineral exploration and geologic mapping. The high dipole moment of the transmitter in combination with the unique *superimposed dipole* coil geometry allows the system to achieve a depth of exploration similar to fixed-wing systems, but with the resolution and target response symmetry that is typical of conventional helicopter-towed EM systems. AeroTEM has flown over 20,000 line-km since its introduction in 1999. Ground follow-up geophysical surveys and drilling programs have confirmed the depth of exploration to be in excess of 200 m with high spatial resolution of target conductors confirmed. The compact, rigid system geometry should provide for a true on-time measurement of secondary fields from highly conductive sources often associated with Ni-Cu-PGE mineralization, thereby gaining a considerable advantage over all towed-receiver fixed-wing airborne EM systems, which are known to be blind to such targets (Hanneson, 1998).

### Introduction

Airborne EM systems, as they have evolved since the 1940's generally fall into one of two categories, namely, (1) the loosely coupled towed-bird systems on fixed-wing aircraft, and (2) the rigid transmitter-receiver configuration towed by helicopters (e.g., Fountain, 1998). The fixed-wing systems operate in the time domain and are characterized by a wideband high-moment transmitter to maximize depth penetration, especially in a resistive environment. The rigid helicopter systems operate in the frequency domain and are characterized by multiple narrow-band low-moment transmitters and closely spaced receivers to maximize spatial resolution and provide moderate depth penetration. Thus one system seeks to maximize signal while the other strives to minimize noise, both attempting to increase the signal-to-noise-ratio...this being the *only* determining factor of an EM system's level of performance.

The AeroTEM system is a wide-band time-domain EM design that draws on the rigid design of the frequency-domain systems and the high-moment transmitter design of the fixed-wing platforms. The system attempts to both maximize signal and minimize noise by incorporating the two major advantages of airborne EM systems—transmitter power and rigid coil geometry. As Duckworth (1993) so succinctly states, the optimum coupling to a target by a transmitter-receiver coil pair is achieved by only two possible coil configurations. The first optimum coupling is



Figure 1. The AeroTEM airborne electromagnetic system.

achieved when the coil separation is 0.6 times the distance to the target; the second optimum coupling is achieved when the coils are coincident. Because target depth cannot be known a priori, the coincident coil geometry is obviously preferred.

### Method

The system (Figure 1) consists of a 3-axis receiver coil mounted centrally within a large 5-m diameter transmitter loop. The transmitter waveform is a triangular current pulse of 1.15 ms duration at a base frequency of 150 Hz with a peak current of 260 A for a total transmitter moment of 40,000 Am<sup>2</sup>. The mutually orthogonal receiver coils are mounted with the X-axis along the flight line, Y transverse, and Z vertical. System waveforms and typical conductor responses are shown in Figure 2.

The system is towed 40 m below the helicopter at a nominal terrain clearance of 30 m. The present transmitter produces a peak primary field of 300 nT vertically below the transmitter at ground level. Because *both* the transmitter and receiver are located close to the ground, AeroTEM produces a stronger target response in the upper 50 m of the earth compared to a fixed-wing aircraft with a peak dipole moment of 500,000 Am<sup>2</sup> and a peak primary field of 55 nT at ground surface.

The strength of the primary field from an EM transmitter decreases rapidly with distance from the transmitter location. High moment transmitters on fixed-wing aircraft, such as GEOTEM, tend to have better depth penetration because the strength of the primary field—even at 300 m—

## The AeroTEM System

is sufficiently high to energize a conductor and produce a measurable secondary field. Large loop ground EM systems have even greater depth penetration, owing to the lower rate at which the primary field falls off with distance from the transmitter for distances on the order of the loop dimensions. The strength of the primary field from the AeroTEM transmitter is compared with that of some common systems in Figure 3.

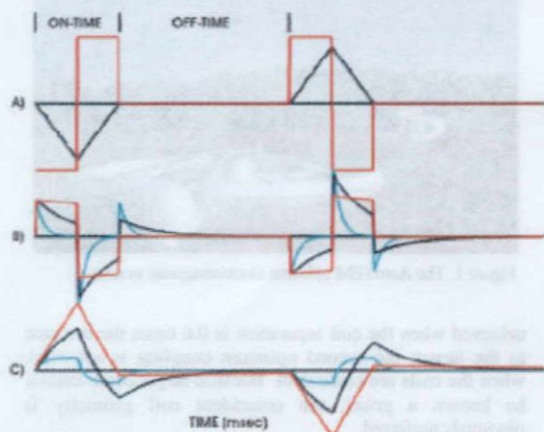


Figure 2. The AeroTEM system is characterized by a) a triangular current pulse at the transmitter and a step response at the receiver. The  $dB/dt$  response in b) and the B-field in c) are shown for conductor time constants of 0.1 ms (blue), 0.5 ms (black) and 5 ms (red).

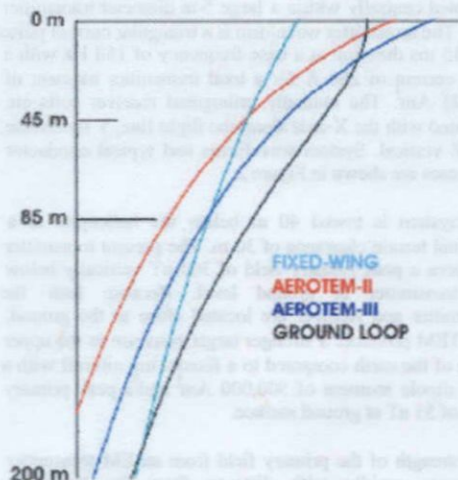


Figure 3: Primary field strength versus depth is compared for fixed-wing ( $500,000 \text{ Am}^2$ ), AeroTEM-II ( $40,000 \text{ Am}^2$ ), AeroTEM-III ( $80,000 \text{ Am}^2$ ) and ground moving-loop (diameter 100 m, 15 A current, single turn) surface to 200 m.

Although the fixed-wing and ground EM systems gain an advantage in primary field at depth, this energy is diffused over a larger volume, thus reducing their effectiveness in energizing smaller conductors. For large loop ground EM systems, this is especially a problem where large regional conductors can mask the more subtle responses of smaller isolated targets.

### Example One: Spatial Resolution

The vertical (Z-axis) component produces responses that are independent of the flight line direction. The close proximity of the transmitter and receiver coils produces very sharp anomaly edges. These two factors combine to produce images of the Z component channels that have high spatial resolution.

In the following example, the amplitude of the earliest off-time channel for the Z component receiver coil is shown in Figure 4. The survey was conducted for Nuinsco Resources in the Lac Rocher area of Quebec during an exploration program for Ni-Cu-PGE deposits.

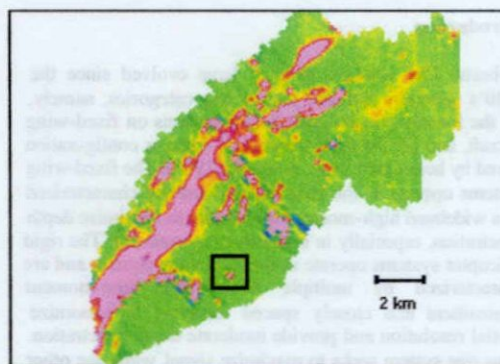


Figure 4. Color image of the earliest time channel, AeroTEM Z component. The black outline represents a conductor response from a near-surface target of limited strike extent.

One discrete anomaly detected from the Lac Rocher survey, and represented by the black outline in Figure 4, is shown in profile format in Figure 5. The approximate lateral extent of the conductor response is 50 m on the earliest time channel (width at half-maximum). The narrow response of this isolated conductor compares favorably with the spatial resolution achieved with conventional HEM systems.

## The AeroTEM System

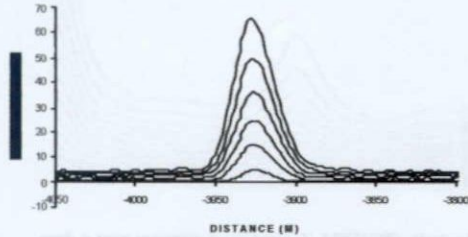


Figure 5: The high spatial resolution of AeroTEM is demonstrated by the EM response of an isolated conductor. The width of the response is less than 50 m on the earliest time channel (peak amplitude at half-maximum).

### Example Two: Airborne - Ground Comparison

Aurogin Resources, in joint venture with Heron Mines, flew an 800 line-km AeroTEM survey over the Belledune Property in New Brunswick in the search for Cu-Zn-Pb deposits. Several AeroTEM airborne EM conductors were identified from that survey over two separate areas.

A ground follow-up program of Crone Pulse EM was conducted over one selected target in Area Two. The AeroTEM early-time Z component response is shown in Figure 6. The anomaly subjected to the ground follow-up program is outlined in black (Figure 6).

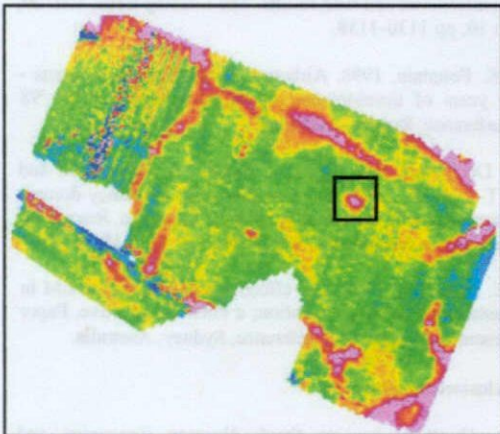


Figure 6: Early-time Z component AeroTEM response over the Belledune Survey Area Two. A detailed ground follow-up survey was centered over the response outlined in black.

An expanded view of the airborne response is shown in Figure 7. The Crone early-time response is shown in Figure 8. The conductor was located within an area of favorable geology. Modeling of the Crone response suggested a sub-horizontal conductor dipping at  $-25^\circ$  below the horizontal and located approximately 100 m below surface. The AeroTEM response also suggested a flat-lying conductor because of the symmetric Z component response.

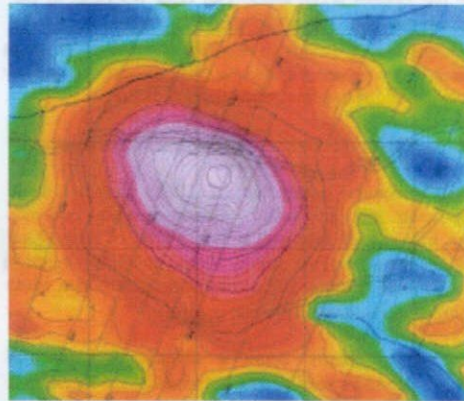


Figure 7: AeroTEM earliest time-channel Z component response, Belledune Property, New Brunswick. The survey was flown with a line spacing of 100 m.

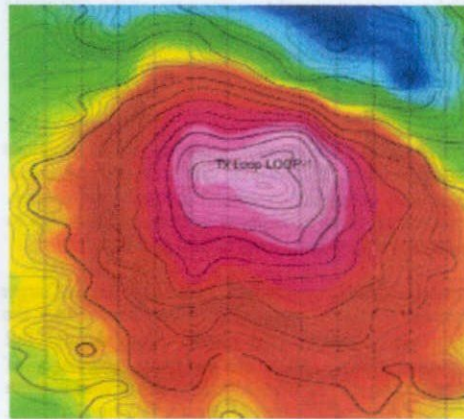


Figure 8: Crone Pulse EM vertical component, amplitude of time channel 10, from the Belledune Property, New Brunswick. The survey was performed in-loop with a 100 m line spacing.

## The AeroTEM System

Two boreholes were drilled to then evaluate the EM responses and both intersected up to 15% sulphide containing significant Au-Ag-Cu within a volcanic rhyolite. Downhole Pulse EM surveys confirmed the intersection of a conductor approximately 170 m downhole, coincident with the intersected mineralization, and corresponding to a vertical depth of 145 m. The peak response in the earliest AeroTEM time channel was 90 ppb, or roughly 200 times above the system noise level. The peak response in the Crone survey was 110 nT/s, about 200 times above the system noise level. This is an example of a drilling program that could have proceeded directly from the airborne survey without the added expense of ground geophysics.

### Example Three: Airborne – Airborne Comparison

Nuinsco Resources conducted GEOTEM and AeroTEM surveys over the Lac Rocher property covering both the known mineralized area and a larger area of unexplored claims. In one area of the survey both GEOTEM (Figure 9) and AeroTEM (Figure 10) recorded responses that were coincident with a large magnetic anomaly.

Both systems clearly show a distinct, multi-channel anomaly. Nuinsco drilled the conductor in 1999 and intersected 2.2 m of massive sulphide at a depth of 200 m below surface. The AeroTEM peak response was 3 ppb or 10 times the system noise level, while the GEOTEM peak response was 400 ppm or 40 times system noise level. While noise levels are dependent upon the level of filtering, the higher apparent signal-to-noise-ratio of the GEOTEM response can be attributed to its higher moment transmitter and the depth of the conductor.

### Conclusions

AeroTEM shows a high spatial resolution, due to its unique coil configuration. The system produces responses that compare well with existing ground and airborne systems. The present depth of exploration is estimated to be up to 250 m with a typical noise level of  $\pm 0.5$  ppb.

Improvements to the system will come in the form of larger transmitter moments, decreased noise levels and the development of true on-time measurements through full waveform recording. There are numerous advantages of using helicopter-towed time-domain systems with a depth penetration approaching that of the fixed-wing platforms. The success of these systems will no doubt be dictated by the perceived needs of the mineral exploration industry for such techniques.

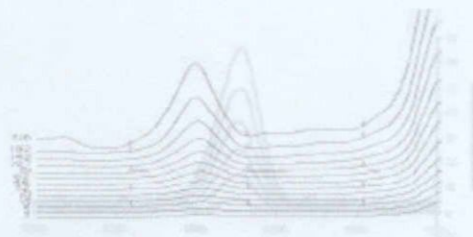


Figure 9: GEOTEM Z component response over a deep conductor at Lac Rocher.

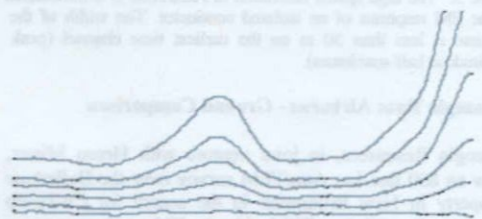


Figure 10: AeroTEM Z component response over a deep conductor at Lac Rocher.

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### Acknowledgments

AeroQuest wishes to thank Nuinsco Resources and Aurogin Resources for permission to publish the survey data from their respective properties.



APPENDIX 4: Instrumentation Specification Sheets

# AEROQUEST LIMITED

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## AEROTEM Helicopter Electromagnetic System

### System Characteristics

Transmitter: Triangular Pulse Shape Base Frequency 30 or 150 Hz.

Tx On Time - 5,750 (30Hz) or 1,150 (150Hz) microsec.

Tx Off Time - 10,915 (30Hz) or 2,183 (150Hz) microsec.

Loop Diameter - 5 m.

Peak Current - 250 A.

Peak Moment - 38,800 NIA.

Typical Z Axis Noise at Survey Speed = 8 ppb peak.

Sling Weight: 270 Kg.

Length of Tow Cable: 40 m.

Bird Survey Height: 30 m or less nominal.

### Receiver

Three Axis Receiver Coils (x, y, z) positioned at centre of transmitter loop.

Selectable Time Delay to start of first channel 21.3 , 42.7, or 64.0 msec.

### Analogue Display & Acquisition

Six Channels per Axis.

Analogue (RMS) Channel Widths: 52.9, 132.3, 158.7, 158.7, 317.5, 634.9 microsec.

Recording & Display Rate = 10 readings per second.

MDAS Digital recording at 126 sample per decay curve at a maximum of 300 curves per second (26.455 microsec channel width).

### System Considerations

Comparing a fixed wing time domain transmitter with a typical moment of 500,000 NIA flying at an altitude of 120 m with a Helicopter TDEM at 30 m, notwithstanding, the substantial moment loss in the airframe of the fixed wing, the same penetration by the lower flying helicopter system would only require a sixty-fourth of the moment. Clearly the AeroTEM system with nearly 40,000 NIA has more than sufficient moment.

The airframe of the fixed wing presents a response to the towed bird, which must be compensated for dynamically. This problem is non-existent for AeroTEM since transmitter and receiver positions are fixed. The AeroTEM system is completely portable, and can be assembled at the survey site within half a day.

# NEIL Fiset

Consulting Geophysicist

---

## Author's Statement of Qualifications

I, Neil Fiset, of 15 Valley Ridge St., Nepean, Ont., do hereby certify that :

1. I hold a Bachelor of Science degree in Geology(1976) from the University of New Brunswick, Fredericton, New Brunswick.
2. I am a member of the Canadian Exploration Geophysicists Society.
3. Since 1976 I have been an employee of Scintrex Limited, Noranda Exploration Co. Ltd., JVX Ltd. and the United Nations.
5. I have been a self-employed consultant since 1996.
4. I am presently a consulting Geophysicist, practising in Canada and overseas.
5. Permission is granted to Mustang Minerals Corp. to use this report in a prospectus or other financial offering.
6. I have not received, directly or indirectly, nor do I expect to receive any interest, direct or indirect, in the properties of Mustang Minerals Corp. or any affiliate thereof, nor do I beneficially own, directly or indirectly, any securities in Mustang Minerals Corp. or any affiliate thereof

Signed on this 18th day of August, 2004 at Nepean, Ont.



Neil Fiset, BSc.  
Consulting Geophysicist

**Work Report Summary**

Transaction No: W0560.00090 Status: APPROVED  
 Recording Date: 2005-JAN-14 Work Done from: 2004-APR-14  
 Approval Date: 2005-FEB-03 to: 2004-APR-15

Client(s):  
 303851 MUSTANG MINERALS CORP.

Survey Type(s):  
 AEM AMAG

**Work Report Details:**

Claim#	Perform	Perform Approve	Applied	Applied Approve	Assign	Assign Approve	Reserve	Reserve Approve	Due Date
P 3012766	\$322	\$322	\$400	\$400	\$0	0	\$0	\$0	2006-NOV-27
P 3012767	\$2,576	\$2,576	\$3,200	\$3,200	\$0	0	\$0	\$0	2006-NOV-27
P 3012778	\$4,830	\$4,830	\$6,000	\$6,000	\$0	0	\$0	\$0	2007-JAN-28
P 3012779	\$1,932	\$1,932	\$2,400	\$2,400	\$0	0	\$0	\$0	2007-JAN-28
P 3013865	\$2,898	\$2,898	\$3,600	\$3,600	\$0	0	\$0	\$0	2007-MAR-16
P 3013866	\$4,186	\$4,186	\$5,200	\$5,200	\$0	0	\$0	\$0	2007-MAR-16
P 3013867	\$3,864	\$3,864	\$4,800	\$4,800	\$0	0	\$0	\$0	2007-MAR-16
P 3013868	\$5,152	\$5,152	\$4,000	\$4,000	\$1,152	1,152	\$0	\$0	2006-MAR-16
P 3013869	\$5,152	\$5,152	\$4,000	\$4,000	\$1,152	1,152	\$0	\$0	2006-MAR-16
P 3013870	\$1,288	\$1,288	\$1,000	\$1,000	\$288	288	\$0	\$0	2006-MAR-16
P 3013871	\$3,864	\$3,864	\$3,000	\$3,000	\$864	864	\$0	\$0	2006-MAR-16
P 3013872	\$3,864	\$3,864	\$3,000	\$3,000	\$864	864	\$0	\$0	2006-MAR-16
P 3013873	\$3,864	\$3,864	\$3,000	\$3,000	\$672	672	\$192	\$192	2006-MAR-16
P 3013874	\$3,925	\$3,925	\$3,000	\$3,000	\$0	0	\$925	\$925	2006-MAR-16
	<b>\$47,717</b>	<b>\$47,717</b>	<b>\$46,600</b>	<b>\$46,600</b>	<b>\$4,992</b>	<b>\$4,992</b>	<b>\$1,117</b>	<b>\$1,117</b>	

External Credits: \$0

Reserve:  
 \$1,117 Reserve of Work Report#: W0560.00090

\$1,117 Total Remaining

Status of claim is based on information currently on record.



42A03NE2010 2.29089 DOUGLAS

Date: 2005-FEB-03

GEOSCIENCE ASSESSMENT OFFICE  
933 RAMSEY LAKE ROAD, 6th FLOOR  
SUDBURY, ONTARIO  
P3E 6B5

MUSTANG MINERALS CORP.  
1351 E. KELLY LAKE RD. UNIT 8  
SUDBURY, ONTARIO  
P3E 5P5 CANADA

Tel: (888) 415-9845  
Fax:(877) 670-1555

**Submission Number:** 2.29089  
**Transaction Number(s):** W0560.00090

Dear Sir or Madam

**Subject: Approval of Assessment Work**

We have approved your Assessment Work Submission with the above noted Transaction Number(s). The attached Work Report Summary indicates the results of the approval.

At the discretion of the Ministry, the assessment work performed on the mining lands noted in this work report may be subject to inspection and/or investigation at any time.

If you have any question regarding this correspondence, please contact STEVEN BENETEAU by email at [steve.beneteau@ndm.gov.on.ca](mailto:steve.beneteau@ndm.gov.on.ca) or by phone at (705) 670-5855.

Yours Sincerely,



Ron C. Gashinski  
Senior Manager, Mining Lands Section

**Cc:** Resident Geologist

Ken J. Lapierre  
(Agent)

Mustang Minerals Corp.  
(Assessment Office)

Assessment File Library

Mustang Minerals Corp.  
(Claim Holder)

Date / Time of Issue: Tue Feb 22 09:34:31 EST 2005

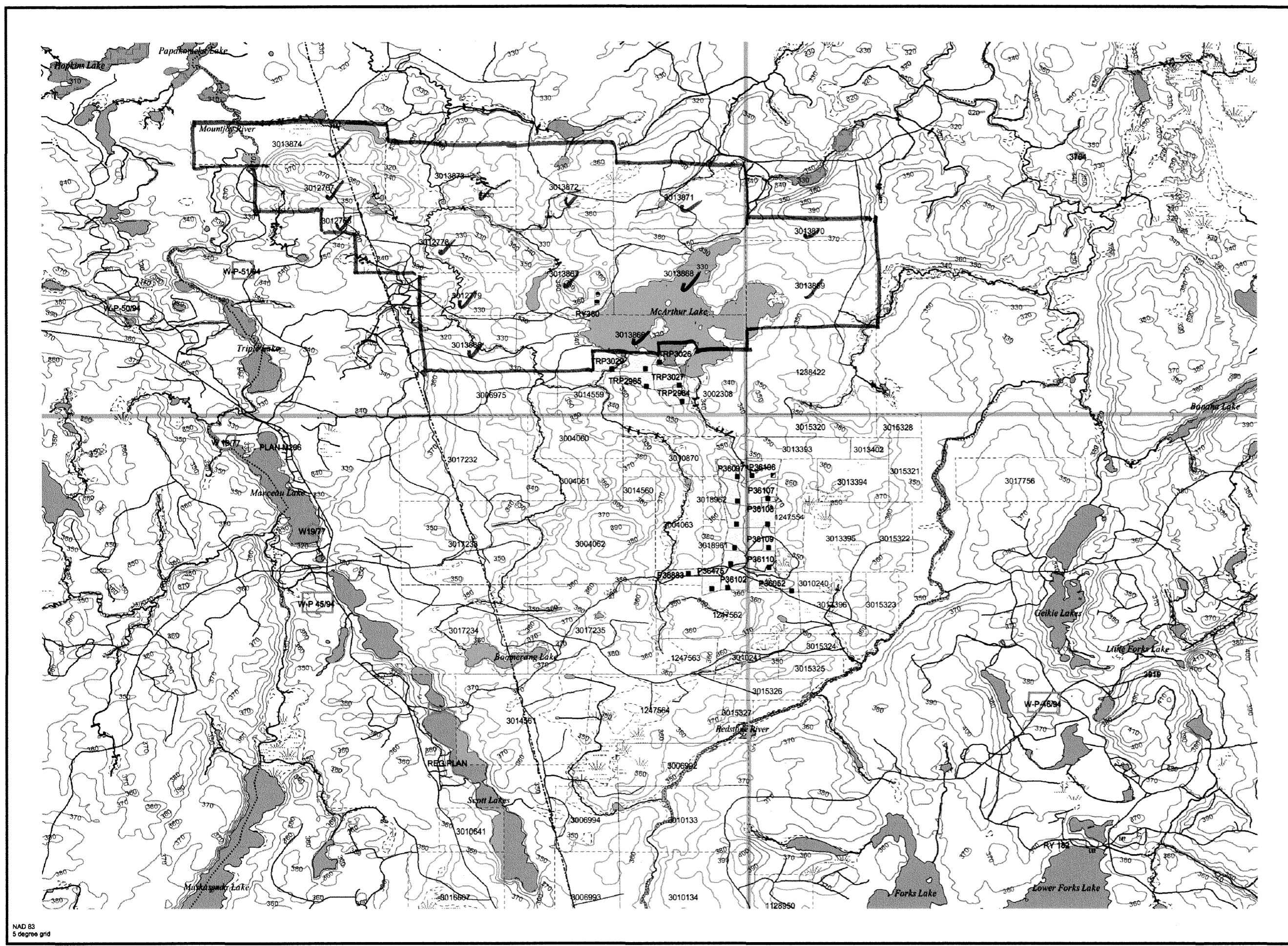
TOWNSHIP / AREA  
BARTLETT

PLAN  
M-0262

ADMINISTRATIVE DISTRICTS / DIVISIONS

Mining Division  
Land Titles/Registry Division  
Ministry of Natural Resources District

Porcupine  
TIMISKAMING  
TIMMINS



**TOPOGRAPHIC**

- Administrative Boundaries
- Township
- Concession, Lot
- Provincial Park
- Indian Reserve
- Cliff, Pit & Pile
- Contour
- Mine Shafts
- Mine Headframe
- Railway
- Road
- Trail
- Natural Gas Pipeline
- Utilities
- Tower

**Land Tenure**

**Freehold Patent**

- Surface And Mining Rights
- Surface Rights Only
- Mining Rights Only

**Leasehold Patent**

- Surface And Mining Rights
- Surface Rights Only
- Mining Rights Only

**Licence of Occupation**

- Uses Not Specified
- Surface And Mining Rights
- Surface Rights Only
- Mining Rights Only
- Land Use Permit
- Order In Council (Not open for staking)
- Water Power Lease Agreement

**Mining Claim**

- 1234567
- 1234567

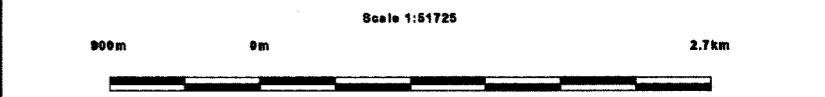
**FILED ONLY MINING CLAIMS**

**LAND TENURE WITHDRAWALS**

- 1234
- Areas Withdrawn from Disposition
- Mining Acts Withdrawal Types
  - Wsm Surface And Mining Rights Withdrawn
  - Ws Surface Rights Only Withdrawn
  - Wm Mining Rights Only Withdrawn
- Order In Council Withdrawal Types
  - W'sm Surface And Mining Rights Withdrawn
  - W's Surface Rights Only Withdrawn
  - W'm Mining Rights Only Withdrawn

**IMPORTANT NOTICES**

No



2.29089  
AMAG  
AEM

Those wishing to stake mining claims should consult with the Provincial Mining Recorders' Office of the Ministry of Northern Development and Mines for additional information on the status of the lands shown hereon. This map is not intended for cadastral survey or land title determination purposes as the information contained hereon is not intended for such purposes. Additional information may also be obtained through the

General Information and Limitations

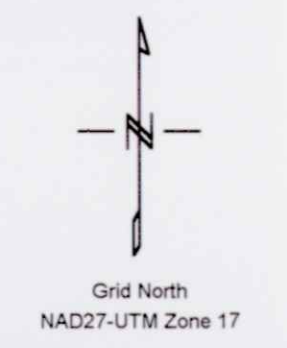
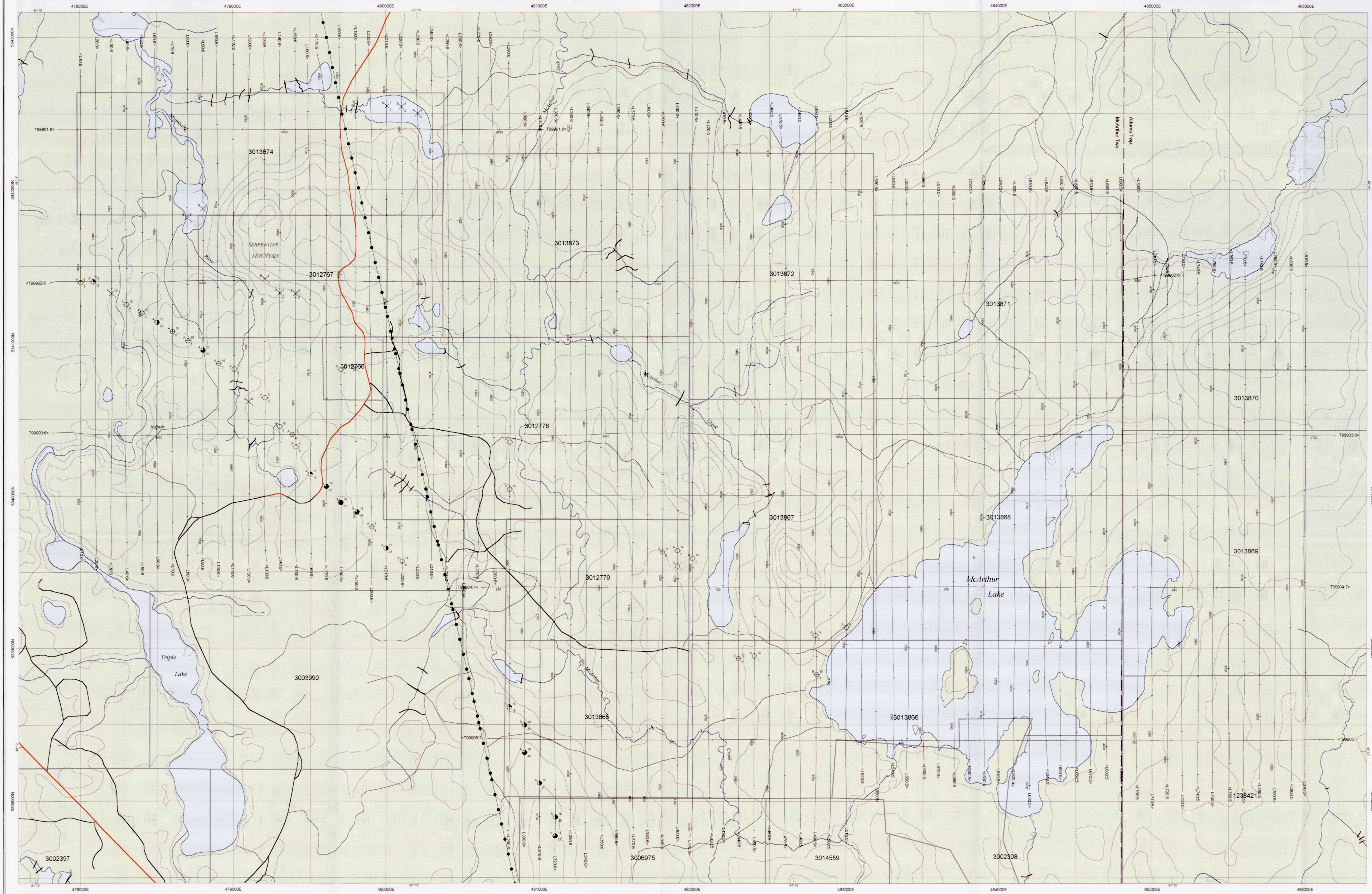
Contact Information:  
Provincial Mining Recorders' Office  
Willet Green Miller, Centre 933 Ramseye Lake Road  
Subsury ON P3E 6B5  
Home Page: www.mdm.gov.on.ca/MNDM/MINES/LANDS/mismppgpe.htm

Toll Free  
Tel: 1 (888) 415-9845 ext 5777  
Fax: 1 (877) 670-1444

Map Datum: NAD 83  
Projection: Geographic Coordinates  
Topographic Data Source: Land Information Ontario  
Mining Land Tenure Source: Provincial Mining Recorders' Office

This map may not show unregistered land tenure and interests in land including certain patents, leases, easements, right of ways, flooding rights, licences, or other forms of disposition of rights and interest from the Crown. Also certain land tenure and land uses that restrict or prohibit free entry to stake mining claims may not be illustrated.





The topographic base was derived from the 1:20,000 CBM Digital Topographic Data Base. The map accompanies the technical report entitled 'Report on a Helicopter-Borne Magnetic and Electromagnetic Survey, McArthur Property' by AeroQuest Limited, April 2004.

- AEROTEM Conductance Symbols:**
- >50 S ●
  - 35-50 S ●
  - 20-35 S ●
  - 10-20 S ●
  - 5-10 S ●
  - 1-5 S ●
  - <1 S ●
- Interpretation by S. Balch and J. Rudd
- Anomaly Letter A 12  
33  
Conductance (S)  
(0 indicates <1S)

**SURVEY SPECIFICATIONS:**  
 Survey from: April 14-15, 2004  
 Traverse line spacing: 100 metres  
 Traverse line direction: N-S  
 Nominal EM bird height: 30 metres  
 Aircraft: Aerospatiale AStar 350B2 (C-PAVI)

**INSTRUMENTATION:**  
 Data acquisition: MDAS2 & RMS DGR-33  
 Magnetometer: Geometrics G-823A cesium vapour  
 Installation: Towed bird 21 m above EM bird  
 Resolution: 501 nanoTesla  
 Electromagnetics: AEROTEM Mx-II System  
 Configuration: Towed bird

**NAVIGATION:**  
 Navigation: Global Positioning System (DGPS)  
 Navigation equipment: Trimble AGPS 32  
 Radar Altimeter: Terra TRA3000/TRI-30

**DATA PROCESSING:**  
 Magnetica: Base station levelling applied  
 EM smoothing: Non-linear-4pt, Low Pass-5pt boxcar

**POSITIONING:**  
 Ellipsoid: NAD27  
 Major Axis: 6378206.400  
 Eccentricity: 0.06271864  
 Projection: Universal Transverse Mercator  
 Central Meridian: 81°W (Zone 17)  
 Central Scale Factor: 0.9996  
 False Easting: 500,000m/0m

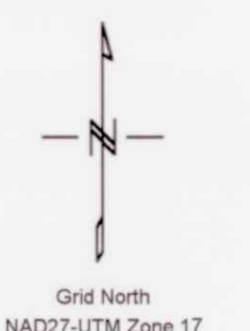
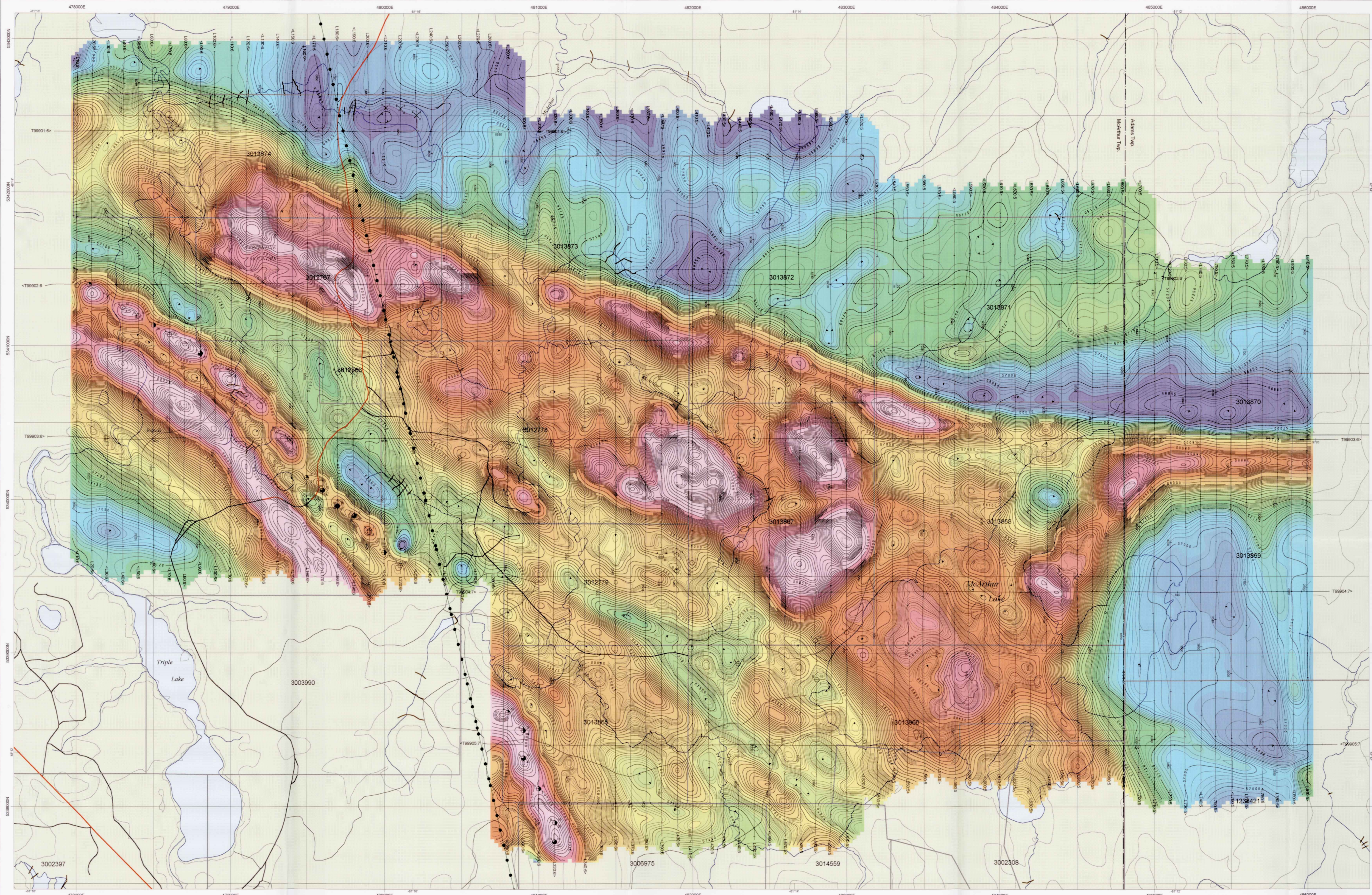


Mustang Minerals Corp.  
 McArthur Twp., Timmins Area, Ontario

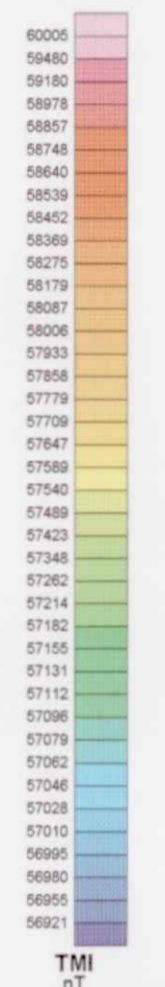
**FLIGHT PATH**  
**McArthur Block**  
 NTS 42A/3

Survey flown by:  
**AEROQUEST LIMITED**  
 4-845 Main St. East  
 Milton, Ont., CANADA L9T 3Z3  
 Tel: (905) 883-8123 Fax: (905) 883-9128  
 www.aeroquestsurvey.com

2.29089



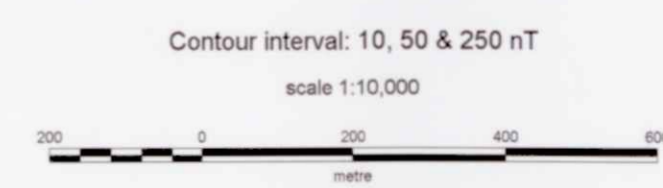
Grid North  
NAD27-UTM Zone 17  
The topographic base was derived from the 1:20,000 CBM Digital Topographic Data Base  
This map accompanies the technical report entitled Report on a Helicopter-Borne Magnetic and Electromagnetic Survey, McArthur Property  
by AeroQuest Limited, April 2004.



- AEROTEM Conductance Symbols:**
- >50 S
  - 35-50 S
  - 20-35 S
  - 10-20 S
  - 5-10 S
  - 1-5 S
  - <1 S

Interpretation by S. Balch and J. Rudd  
Anomaly Letter A  CR Time Channels of Response (1-16)  
Conductance (S)   
(0 indicates <math>-1 S</math>)

**SURVEY SPECIFICATIONS:**  
Survey from: April 14-15, 2004  
Traverse line spacing: 100 metres  
Traverse line direction: N-S  
Nominal EM bird height: 30 metres  
Aircraft: Aerospaciale Altair 350B2 (C-FAVI)  
**INSTRUMENTATION:**  
Data acquisition: MDAS2 & RMS DGR-33  
Magnetometer: Geometrics G-823A cesium vapour  
Installation: Towed bird 21 m above EM bird  
Resolution: 0.01 nanoTesla  
Electromagnetics: AEROTEM Mk-II System  
Configuration: Towed bird  
**NAVIGATION:**  
Navigation: Global Positioning System (DGPS)  
Navigation equipment: Trimble AgGPS132  
Radar Altimeter: Terra TRA3000/TRI-30  
**DATA PROCESSING:**  
Magnetic: Base station levelling applied  
EM smoothing: Non-linear-4pt, Low Pass-5pt boxcar  
**POSITIONING:**  
Ellipsoid: NAD27  
Major Axis: 6378206.400  
Eccentricity: 0.082271854  
Projection: Universal Transverse Mercator  
Central Meridian: 81°W (Zone 17)  
Central Scale Factor: 0.9996  
False Easting/Northing: 500,000m/0m



Mustang Minerals Corp.  
McArthur Twp., Timmins Area, Ontario

**TOTAL MAGNETIC INTENSITY**

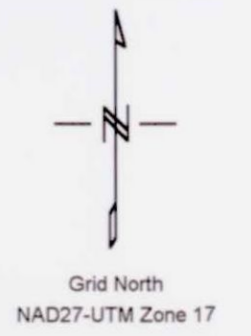
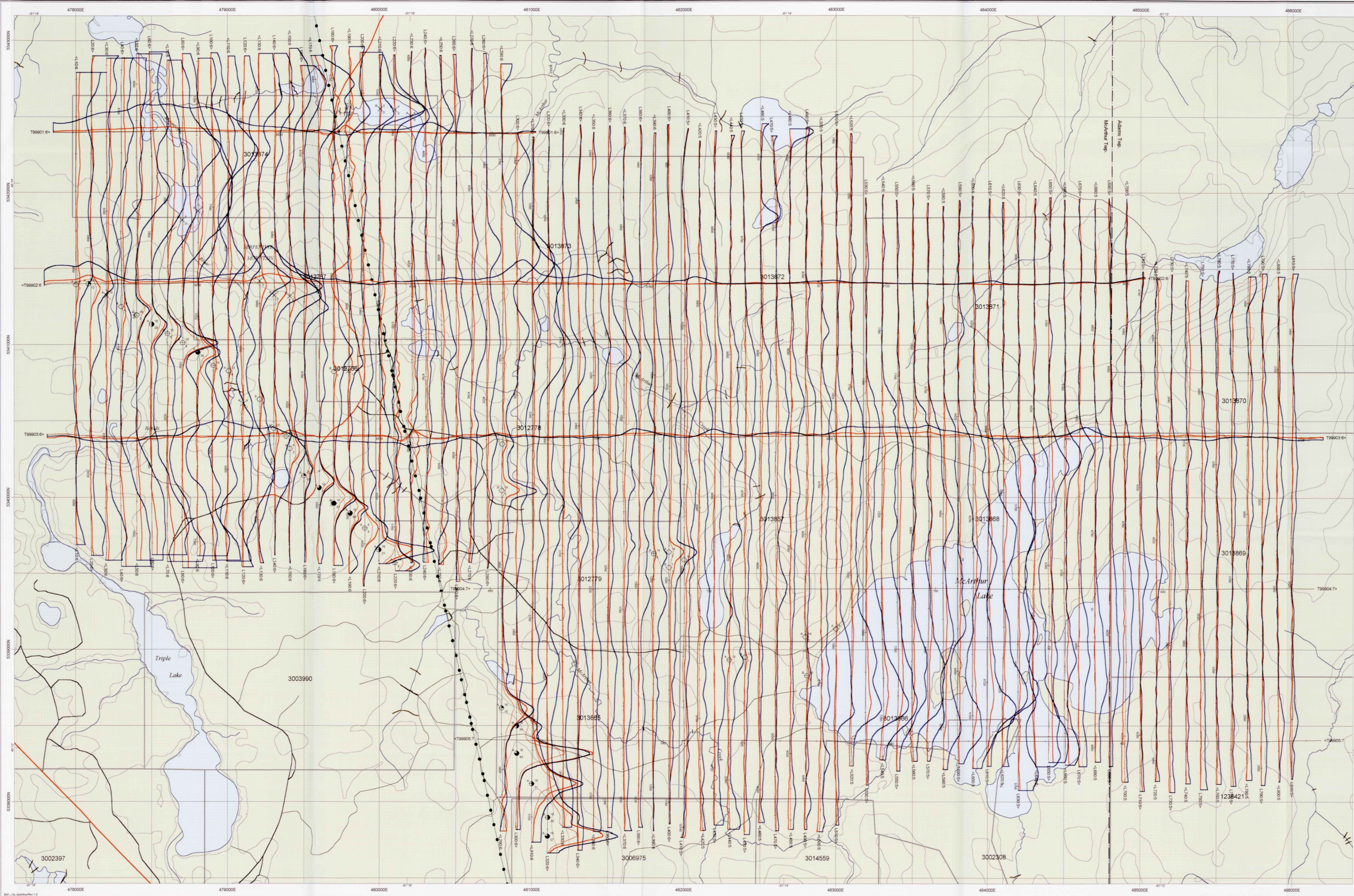
McArthur Block  
NTS 42A/3

2.29080

Survey from by:  
**AEROQUEST LIMITED**  
4-845 Main St. East  
Milton, Ont., CANADA L7T 3Z3  
Tel: (905) 884-3128 Fax: (905) 884-3128  
www.aeroquestminerals.com

April, 2004





The topographic base was derived from the 1:20,000 OBM Digital Topographic Data Base  
 This map accompanies the technical report entitled 'Report on a Helicopter-Borne Magnetic and Electromagnetic Survey, McArthur Property' by AeroQuest Limited, April 2004.

Positive EM Profile excursion to the right and top  
 On-Time Z1 channel, 1mm=40nT/sec  
 On-Time Z5 channel, 1mm=40nT/sec  
 Off-Time Z0 channel, 1mm=40nT/sec

**AEROTEM Conductance Symbols:**  
 >50 S ●  
 35-50 S ◐  
 20-35 S ◑  
 10-20 S ◒  
 5-10 S ◔  
 1-5 S ◕  
 <1 S ×  
 Interpretation by S. Balch and J. Rudd

**SURVEY SPECIFICATIONS:**  
 Survey from: April 14-15, 2004  
 Traverse line spacing: 100 metres  
 Traverse line direction: N-S  
 Nominal EM bird height: 30 metres  
 Aircraft: Aerospatec ASAR 300B2 (C-FAV)  
**INSTRUMENTATION:**  
 Data acquisition: MDAS2 & RMS DGR-33  
 Magnetometer: Geometrics G-823A cesium vapour  
 Installation: Towed bird 21 m above EM bird  
 Resolution: 201 nanoTesla  
 Electromagnetics: AEROTEM Mx-II System  
 Configuration: Towed bird  
**NAVIGATION:**  
 Navigation: Global Positioning System (DGPS)  
 Navigation equipment: Trimble AGPS132  
 Radar Altimeter: Terra TRA3000TRI-30  
**DATA PROCESSING:**  
 Magnetics: Base station leveling applied  
 EM smoothing: Non-linear-4pt, Low Pass-Spt boxcar  
**POSITIONING:**  
 Ellipsoid: NAD27  
 Major Axis: 6378206.400  
 Eccentricity: 0.082271854  
 Projection: Universal Transverse Mercator  
 Central Meridian: 81°W (Zone 17)  
 Central Scale Factor: 0.9996  
 False Easting/Northing: 500,000m/0m



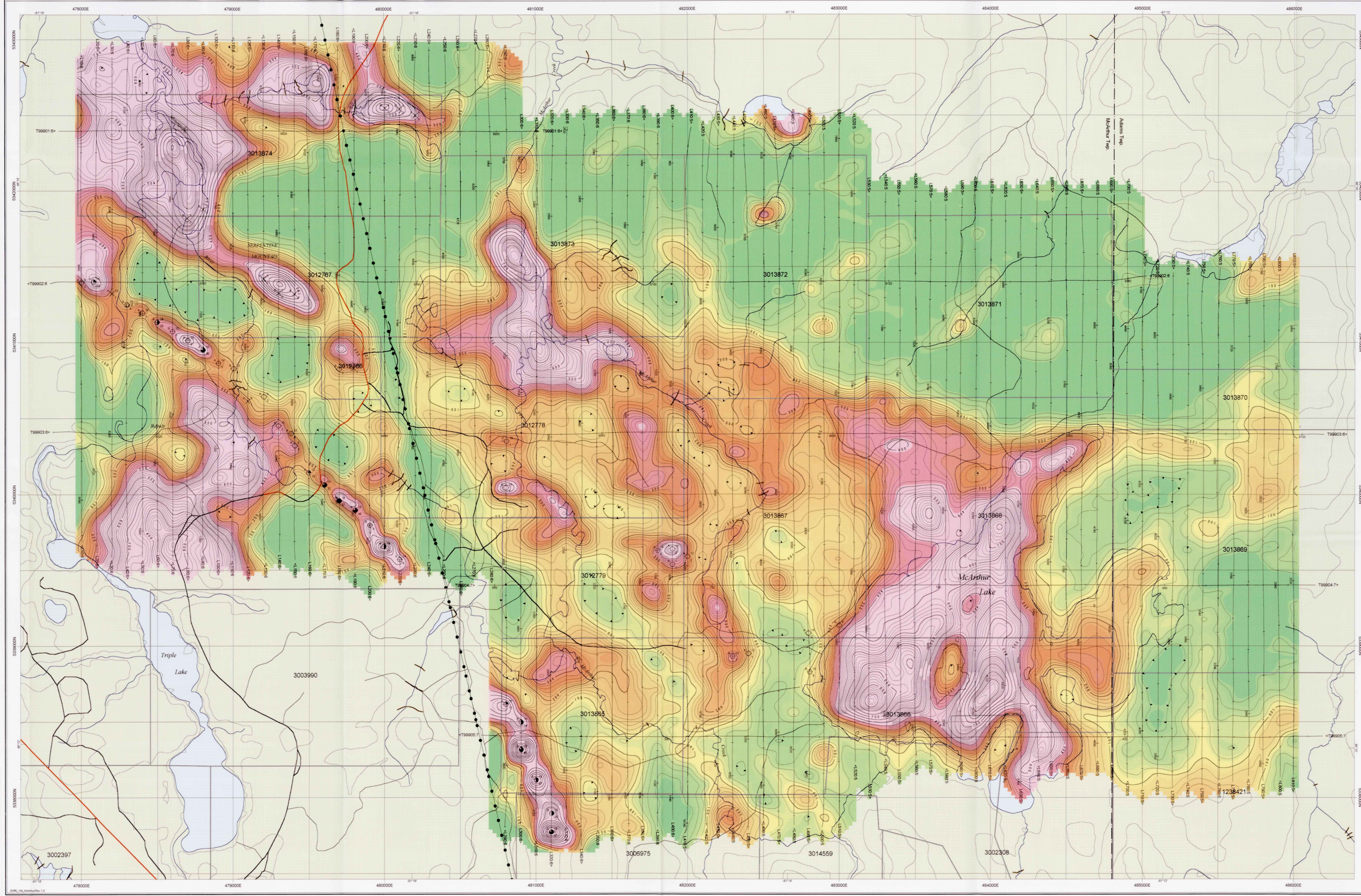
Mustang Minerals Corp.  
 McArthur Twp., Timmins Area, Ontario  
**AEROTEM PROFILES**  
**RMS Z3 & Z5 Channels**  
 McArthur Block  
 NTS 42A/3

Survey flown by  
**AEROQUEST LIMITED**  
 4-845 Main St. East  
 Milton, Ont., CANADA L9T 3Z3  
 Tel: (905) 880-0220 Fax: (905) 880-0228  
 www.aeroquest.com  
 April, 2004

2. 290 89

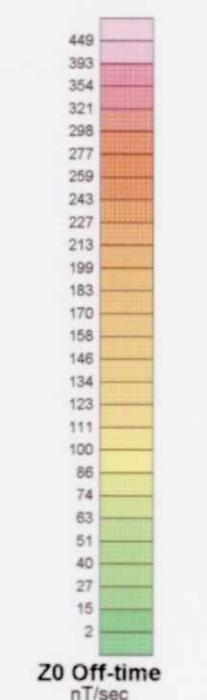






Grid North  
NAD27-UTM Zone 17

The topographic base was derived from the 1:20,000 CBM Digital Topographic Data Base  
This map accompanies the technical report entitled "Report on a Helicopter-Borne Magnetic and Electromagnetic Survey, McArthur Property," by AeroQuest Limited, April 2004.



- AEROTEM Conductance Symbols:**
- >50 S
  - 35-50 S
  - 20-35 S
  - 10-20 S
  - 5-10 S
  - 1-5 S
  - <1 S
- Interpretation by S. Balch and J. Rudd
- Anomaly Letter A
- Off-Time Channels of Response (1-16)
- Conductance (S)
- (S indicates <math>+10</math>)

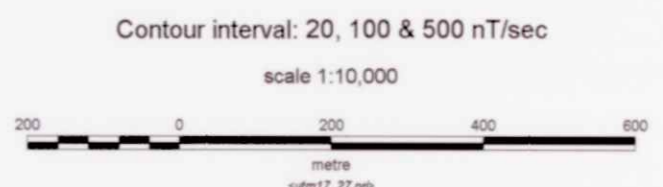
**SURVEY SPECIFICATIONS:**  
 Survey from: April 14-15, 2004  
 Traverse line spacing: 100 metres  
 Traverse line direction: N-S  
 Nominal EM bird height: 30 metres  
 Aircraft: Aerospaciale AStar 350B2 (C-FAVI)

**INSTRUMENTATION:**  
 Data acquisition: MDAS2 & RMS DGR-33  
 Magnetometer: Geometrics G-823A cesium vapour  
 Installation: Towed bird 21 m above EM bird  
 Resolution: .001 nanoTesla  
 Electromagnetics: AEROTEM Mk-II System  
 Configuration: Towed bird

**NAVIGATION:**  
 Navigation: Global Positioning System (DGPS)  
 Navigation equipment: Trimble AgGPS 132  
 Radar Altimeter: Terra TRA3000TRI-30

**DATA PROCESSING:**  
 Magnetics: Base station levelling applied  
 EM smoothing: Non-linear-4pt, Low Pass-5pt boxcar

**POSITIONING:**  
 Ellipsoid: NAD27  
 Major Axis: 6378206.400  
 Eccentricity: 0.082271854  
 Projection: Universal Transverse Mercator  
 Central Meridian: 81°W (Zone 17)  
 Central Scale Factor: 0.9996  
 False Easting/Northing: 500,000m/0m



Mustang Minerals Corp.  
 McArthur Twp., Timmins Area, Ontario

**AEROTEM Z0 Off-Time**  
 McArthur Block  
 NTS 42A/3

Survey flown by:  
**AEROQUEST LIMITED**  
 4-845 Main St. East  
 Milton, Ont., CANADA L9T 3Z3  
 Tel: (905) 881-3128 Fax: (905) 881-3128  
 www.aeroquest.com

April, 2004

Plate 4

2.29089

